

Strategic games as cybernetic systems

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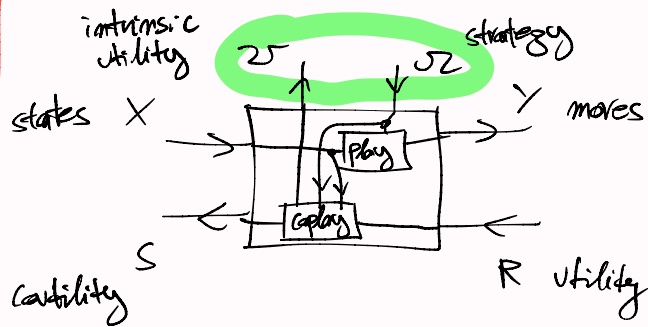
MSP101

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Outline

1. The issue with open games
2. Learning from learners
3. Feedback structures
4. A behavioural approach to Nash equilibria

ARENA



$$\text{play} : J2 \times X \longrightarrow Y$$

$$\text{coplay} : J2 \times X \times R \longrightarrow S \times 25$$

Selection
function

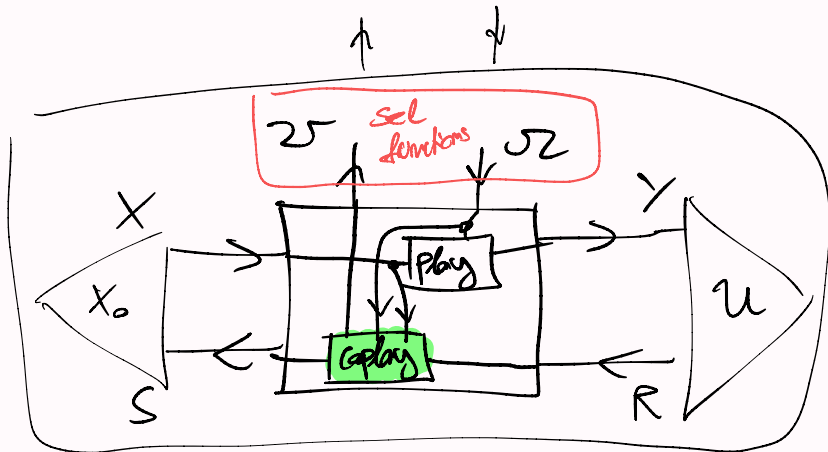
(eq predicate)

$$\varepsilon : (J2 \rightarrow 25) \rightarrow P J2$$

$$\parallel$$

$$\text{argmax}$$

$$25 = IR$$

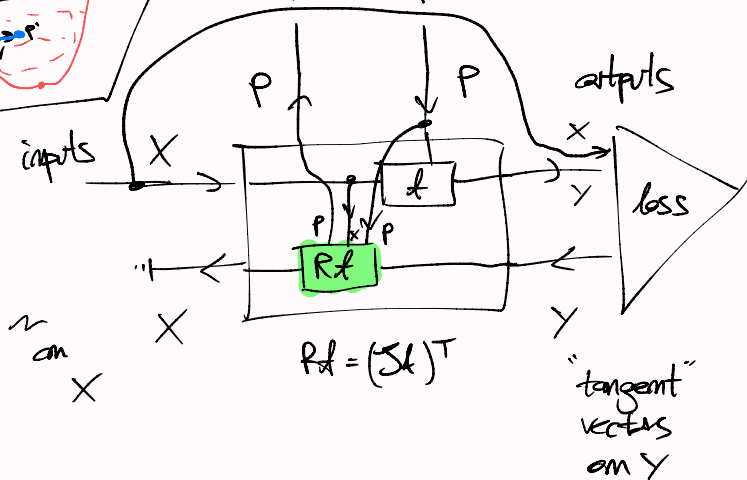
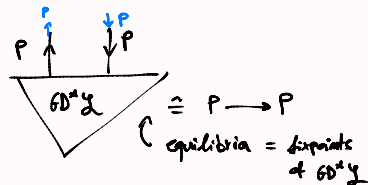
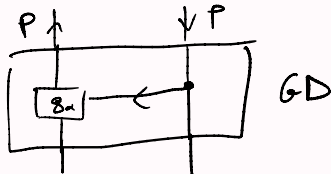
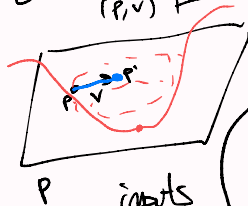


$$w \in \Sigma \quad \forall \text{ player} \quad u(\underline{w}') \leq u(w)$$

w with a unilateral deviation

$$g: (p:P) \times (v:P) \rightarrow P$$

$$(p,v) \mapsto p - 2v$$



$$l: Y \longrightarrow \mathbb{R} \in \mathcal{C}^\infty(Y) \quad \text{scalar field/function}$$

$$dl: TY \xrightarrow{\text{lin}} \mathbb{R} \times \mathbb{R}$$

$$TY \xrightarrow{\pi_Y} Y$$

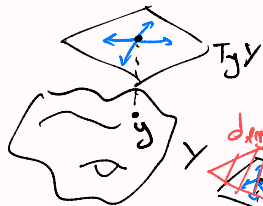
tangent space bundle

$$l: Y \longrightarrow \mathbb{R} \quad g: Y \times T_y Y \text{ type + vector space}$$

(0, +, \cdot)

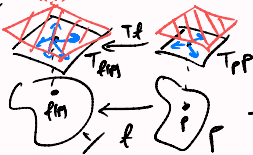
$$dl: (g: Y) \times T_y Y \longrightarrow \mathbb{R}$$

linear
" functional
over $T_y Y$

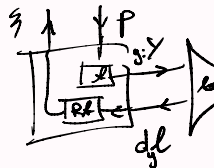


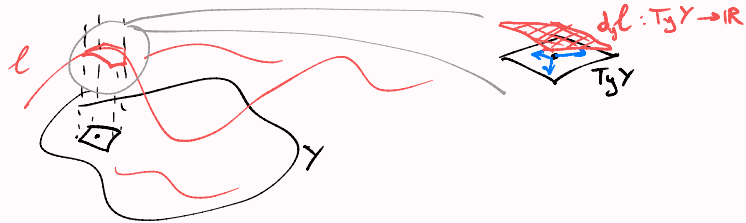
$$T_y P \xrightarrow{\pi^*} T_y Y \xrightarrow{d_{\text{lin}} l} \mathbb{R}$$

$f^*(d_{\text{lin}} l)$



evaluation of the comm. mbl of y





$T^*: \text{Smooth} \longrightarrow \text{Dens}(\text{Smooth}) \approx \text{reverse derivative}$

$$\begin{array}{ccc}
 X & & T^*X \xleftarrow{T^*f} T^*Y \\
 \downarrow f & \mapsto & \downarrow \quad \downarrow \quad \downarrow \\
 Y & & X = X \xrightarrow{f} Y
 \end{array}$$

$$T^*f: (x: X) \times (y: T_{f(x)} Y) \longrightarrow T_x X$$

(1) What is our feedback like?

$$R = \mathbb{R}^N \text{ payoff vector}$$

$$R^{\Omega} = \Omega \rightarrow \mathbb{R}$$

(2) What are our changes?

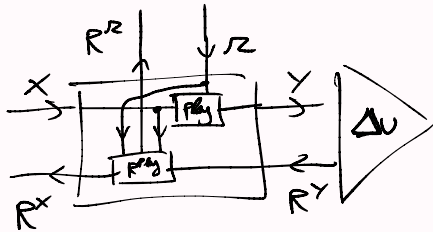
$$P\Omega$$

$$w \in \Omega$$



$$R^*: \text{Set} \rightarrow \text{DLens}(\text{Set})$$

$$\begin{array}{ccc}
 X & & X \quad Y \\
 \downarrow f & \mapsto & \downarrow f \quad \uparrow R^f: X \times R^Y \rightarrow R^X \\
 Y & & Y \quad R^Y
 \end{array}
 \quad
 \begin{array}{l}
 (x, v) \mapsto f; v \\
 X \rightarrow Y \rightarrow v
 \end{array}$$



Para (R^*)

Para(Set) ($\mathcal{R}, *$): $X \rightarrow Y$

↓

↓

Para(Dens(Set)) $\text{Para}(R^*)(\mathcal{R}, *)$

$$\Delta u: Y \rightarrow R^Y$$

$$y \mapsto u$$

$$y \mapsto \lambda y'. u(y') - u(y)$$

lax functor!

$$R^{\mathcal{R} \times \mathcal{R}} \neq R^{\mathcal{R}} \times R^{\mathcal{R}}$$

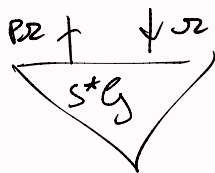
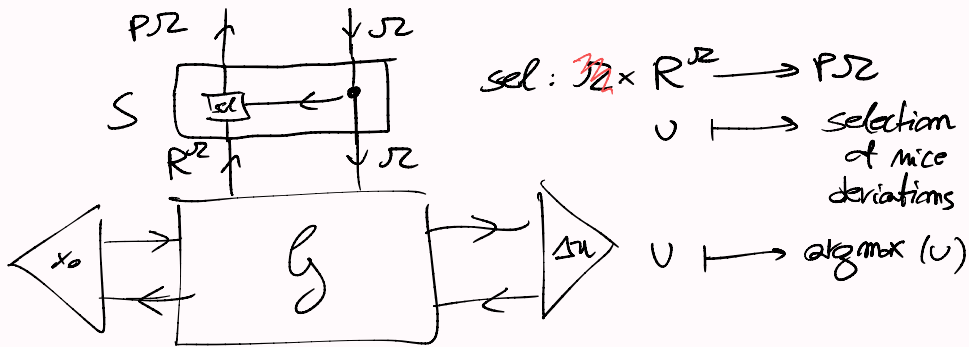
$R^*: \text{Set} \longrightarrow \text{Dens}(\text{Set})$ lax monoidal

$$X, Y \longmapsto (X, R^X) \otimes (Y, R^Y) = (X \times Y, R^X \times R^Y)$$

$$\begin{array}{c} \swarrow \quad \xrightarrow{1} \quad \searrow \\ (X \times Y, R^{X \times Y}) \end{array} \quad \begin{array}{l} P_{X,Y}: X \times Y \times R^{X \times Y} \longrightarrow R^X \times R^Y \\ (x, y, u) \longmapsto \langle u(x, -), u(-, y) \rangle \end{array}$$

$$(\mathcal{R}, f): X \longrightarrow Y = \mathcal{R} \times X \longrightarrow Y$$

$$\begin{array}{ccc} & \downarrow & \\ R^t: R^Y & \longrightarrow & R^{\mathcal{R} \times X} \\ & \downarrow & \\ R^Y & \longrightarrow & R^{\mathcal{R}} \times R^X \end{array} \quad \begin{array}{c} R^{\mathcal{R}} \uparrow \\ \text{---} \boxed{\text{copy}} \text{---} \\ R^X \end{array} \quad R^Y$$








equilibria are
 fixpoints
 $\cong \Omega \xrightarrow{s^*g} P\Omega$

$$w \in s^*g(w)$$

Thanks for your attention!

Questions?

References |

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