

Monoidal Streams for Dataflow Programming

Extended abstract

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Abstract

We introduce monoidal streams: a generalization of causal stream functions to monoidal categories. In the same way that streams provide semantics to dataflow programming with pure functions, monoidal streams provide semantics to dataflow programming with theories of processes represented by a symmetric monoidal category. At the same time, monoidal streams form a feedback monoidal category, which can be used to interpret signal flow graphs. As an example, we study a stochastic dataflow language.

This is an extended abstract of “[Monoidal Streams for Dataflow Programming](#)”, to appear in LiCS ’22.

Keywords: Monoidal stream, Stream, Monoidal category, Dataflow programming, Feedback, Signal flow graph, Coalgebra, Stochastic process.

1 Introduction

Dataflow languages. Dataflow (or *stream-based*) programming languages, such as LUCID [11, 22], follow a paradigm in which every declaration represents an infinite list of values: a *stream* [2, 20]. The following program in a LUCID-like language (Figure 1) computes the Fibonacci sequence, thanks to a FBY (“followed by”) operator.

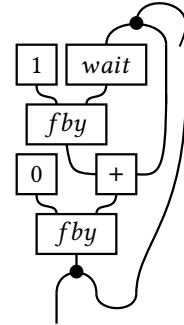
$$fib = 0 \text{ FBY } (fib + (1 \text{ FBY } \text{WAIT}(fib)))$$

Figure 1. The Fibonacci sequence is 0 followed by the Fibonacci sequence plus the Fibonacci sequence preceded by a 1.

The control structure of dataflow programs is inspired by *signal flow graphs* [2, 15, 18]. Signal flow graphs are diagrammatic specifications of processes with feedback loops, widely used in control system engineering. In a dataflow program, feedback loops represent how the current value of a stream may depend on its previous values. For instance, the previous program (Figure 1) corresponds to the signal flow graph in Figure 2.

Feedback monoidal categories. Signal flow graphs are the graphical syntax for *feedback monoidal categories* [5, 6, 9, 10, 14]: they are the *string diagrams* for any monoidal theory, extended with *feedback*.

Yet, semantics of dataflow languages have been mostly restricted to theories of pure functions [2, 7, 8, 16, 19, 21]: what are called *cartesian* monoidal categories. We claim that this restriction is actually inessential; dataflow programs



$$\begin{aligned} fib = & \text{fbk}(\text{copy}; \\ & \partial(1 \times \text{wait}) \times \text{id}; \\ & \partial(\text{fby}) \times \text{id}; \\ & \partial(+); \\ & 0 \times \text{id}; \\ & \text{fby}; \\ & \text{copy}) \end{aligned}$$

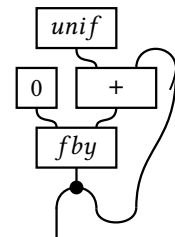
Figure 2. Fibonacci: signal flow graph and morphism.

may take semantics in non-cartesian monoidal categories, exactly as their signal flow graphs do.

Contributions. The present work provides this missing semantics: we construct *monoidal streams* (Theorem 2.3) over a symmetric monoidal category, which form a *feedback monoidal category* (Theorem 3.3). Monoidal streams model the values of a *monoidal dataflow language*, in the same way that streams model the values of a classical dataflow language. This opens the door to stochastic, effectful, or quantum dataflow languages. In particular, we give semantics and string diagrams for a *stochastic dataflow programming language*, where the following code can be run.

$$walk = 0 \text{ FBY } (\text{UNIFORM}(-1, 1) + walk)$$

Figure 3. A stochastic dataflow program. A random walk is 0 followed by the random walk plus a stochastic stream of steps to the left (-1) or to the right (1), sampled uniformly.



$$\begin{aligned} walk = & \text{fbk} (\\ & \partial(\text{unif}) \otimes \text{id}; \\ & 0 \otimes \partial(+); \\ & \text{fby}; \\ & \text{copy}) \end{aligned}$$

Figure 4. Random walk: signal flow graph and morphism.

2 Monoidal Streams

The manuscript contains three main definitions in terms of universal properties: *intensional* [19], *extensional* and *observational monoidal streams* (Figure 5). The latter are our

definitive notion of streams and we refer to them as simply *monoidal streams*. The present extended abstract directly introduces the coinductive definition of monoidal streams (Definition 2.4) and their explicit construction: *observational sequences* (Definition 2.2).

Monoidal streams. Classically, type-variant streams have a neat coinductive definition [12, 17] that says:

“A stream of type $\mathbb{A} = (A_0, A_1, \dots)$ is an element of A_0 together with a stream of type $\mathbb{A}^+ = (A_1, A_2, \dots)$ ”.

Formally, streams are the final fixpoint of the equation

$$S(A_0, A_1, \dots) \cong A_0 \times S(A_1, A_2, \dots);$$

and this fixpoint is computed to be $S(\mathbb{A}) = \prod_{n \in \mathbb{N}}^\infty A_n$.

In the same vein, we want to introduce not only streams but *stream processes* over a fixed theory of processes.

“A stream process from $\mathbb{X} = (X_0, X_1, \dots)$ to $\mathbb{Y} = (Y_0, Y_1, \dots)$ is a process from X_0 to Y_0 communicating along a channel M with a stream process from $\mathbb{X}^+ = (X_1, X_2, \dots)$ to $\mathbb{Y}^+ = (Y_1, Y_2, \dots)$.”

Streams are recovered as stream processes on an empty input, so we take this more general slogan as our definition of *monoidal stream* (in Theorem 2.3). Formally, they are the final fixpoint of the equation in Figure 5.

$$Q(\mathbb{X}, \mathbb{Y}) \cong \int^{M \in C} \text{hom}(X_0, M \otimes Y_0) \times Q(M \cdot \mathbb{X}^+, \mathbb{Y}^+).$$

Figure 5. Fixpoint equation for monoidal streams.

Remark 2.1 (Notation). Let $\mathbb{X} \in [\mathbb{N}, C]$ be a sequence of objects (X_0, X_1, \dots) . We write \mathbb{X}^+ for its *tail* (X_1, X_2, \dots) . Given $M \in C$, we write $M \cdot \mathbb{X}$ for the sequence $(M \otimes X_0, X_1, X_2, \dots)$; As a consequence, we write $M \cdot \mathbb{X}^+$ for $(M \otimes X_1, X_2, X_3, \dots)$.

Definition 2.2 (Observational sequence). The set of observational sequences is

$$\text{Obs}(\mathbb{X}, \mathbb{Y}) \cong \left(\int^{M \in [\mathbb{N}, C]} \prod_{i=0}^\infty \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i) \right) / \approx$$

where (\approx) is observational equivalence.

Theorem 2.3. *In a productive category, the final fixpoint of the equation in Figure 5, which is the set of monoidal streams, coincides with the set of observational sequences.*

The final fixpoint of a functor does not need to exist in general. However, when C satisfies some extra conditions, which we call *productivity*, the final fixpoint does exist and can be computed by Adámek’s theorem [1]. This allows us to recast the definition of monoidal streams in coinductive terms.

Definition 2.4 (Monoidal stream). A *monoidal stream* $f \in \text{Stream}(\mathbb{X}, \mathbb{Y})$ is a triple consisting of

- $M(f) \in \text{Obj}(C)$, the *memory*,
- $\text{now}(f) \in \text{hom}(X_0, M(f) \otimes Y_0)$, the *first action*,
- $\text{later}(f) \in \text{Stream}(M(f) \cdot \mathbb{X}^+, \mathbb{Y}^+)$, the *rest of the action*,

quotiented by dinaturality in M .

Explicitly, monoidal streams are quotiented by the equivalence relation $f \sim g$ generated by

- the existence of $r: M(g) \rightarrow M(f)$,
- such that $\text{now}(f) = \text{now}(g); r$,
- and such that $r \cdot \text{later}(f) \sim \text{later}(g)$.

Here, $r \cdot \text{later}(f) \in \text{Stream}(M(g) \cdot \mathbb{X}^+, \mathbb{Y}^+)$ is obtained by precomposition of the first action of $\text{later}(f)$ with r .

3 Delayed feedback for streams

Monoidal streams form a *feedback monoidal category* with respect to the “delay functor” $\partial: [\mathbb{N}, C] \rightarrow [\mathbb{N}, C]$.

Definition 3.1 (Delay functor). Let $\partial: [\mathbb{N}, C] \rightarrow [\mathbb{N}, C]$ be the endofunctor defined on objects $\mathbb{X} = (X_0, X_1, \dots)$, as $\partial(\mathbb{X}) = (I, X_0, X_1, \dots)$; and on morphisms $\mathbb{f} = (f_0, f_1, \dots)$ as $\partial(\mathbb{f}) = (\text{id}_I, f_0, f_1, \dots)$.

Given some stream in $\text{Stream}(\partial S \otimes \mathbb{X}, S \otimes \mathbb{Y})$, we can create a new stream in $\text{Stream}(\mathbb{X}, \mathbb{Y})$ that passes the output in S as a memory channel that gets used as the input in ∂S . As a consequence, the category of monoidal streams has a graphical calculus given by that of feedback monoidal categories [3, 4, 9, 13, 14]. This graphical calculus is complete for extensional equivalence.

Definition 3.2. A *feedback monoidal category* is a symmetric monoidal category (C, \otimes, I) endowed with a monoidal endofunctor $F: C \rightarrow C$ and an operation

$$\text{fbk}_S: \text{hom}(F(S) \otimes X, S \otimes Y) \rightarrow \text{hom}(X, Y)$$

for all S, X and Y objects of C ; this operation needs to satisfy the following axioms.

- (A1). Tightening: $u; \text{fbk}_S(f); v = \text{fbk}_S((\text{id}_{FS} \otimes u); f; (\text{id}_S \otimes v))$.
- (A2). Vanishing: $\text{fbk}_I(f) = f$.
- (A3). Joining: $\text{fbk}_T(\text{fbk}_S(f)) = \text{fbk}_{S \otimes T}(f)$.
- (A4). Strength: $\text{fbk}_S(f) \otimes g = \text{fbk}_S(f \otimes g)$.
- (A5). Sliding: $\text{fbk}_S((Fh \otimes \text{id}_X); f) = \text{fbk}_T(f; (h \otimes \text{id}_Y))$.

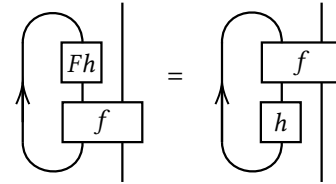


Figure 6. The sliding axiom (A5).

Theorem 3.3. *Monoidal streams over a symmetric monoidal category form a ∂ -feedback monoidal category.*

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