

Dependent Optics

Pietro Vertechi - Applied Category Theory 2022

Structure

- Brief introduction to lenses.

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- Definition and basic properties of (dependent) optics.
- Dependent optics and functor lenses comparison.
- Representations of dependent optics.

Lenses

Lenses are a useful abstraction to access and update data structures.

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jane = (name="Jane", age=32)

# get value for a given field
get_age(person) = person.age

# build new structure from old structure and new field value
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Composability. Lenses can be composed to handle nested data:

$$\begin{array}{ll} X \rightarrow Z & X \times Z' \rightarrow X' \\ x \mapsto \text{get}_2(\text{get}_1(x)) & (x, z') \mapsto \text{put}_1(x, \text{put}_2(\text{get}_1(x), z')) \end{array}$$

Functor lenses

Richer framework for lenses recently put forward (Spivak, 2019).

Setting. Let \mathcal{C} be a category and $\mathcal{F}: \mathcal{C}^{\text{op}} \rightarrow \mathbf{Cat}$ a pseudofunctor.

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Definition. The category $\mathbf{Lens}_{\mathcal{F}}$ has

- objects of the form $\begin{pmatrix} P \\ X \end{pmatrix}$, where $X \in \text{Ob}(\mathcal{C})$ and $P \in \text{Ob}(\mathcal{F}^X)$,
- morphisms given by

$$\mathbf{Lens}_{\mathcal{F}} \left(\begin{pmatrix} P \\ X \end{pmatrix}, \begin{pmatrix} Q \\ Y \end{pmatrix} \right) = \coprod_{f: X \rightarrow Y} \mathcal{F}^X(f^*(Q), P).$$

Here, the notation f^* is a shorthand for $\mathcal{F}(f)$.

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Here, the notation f^* is a shorthand for $\mathcal{F}(f)$.

Bidirectionality. $f: X \rightarrow Y$ is *forward* and $f^{\#}: f^*(Q) \rightarrow P$ is *backward*.

Composability. By functoriality of f^* (and \mathcal{F}), functor lenses compose.

Examples of functor lenses

Plain lenses. Functor lenses for $X \mapsto \text{coKleisli}(X \times -)$.

$$\begin{aligned} \mathbf{Lens}((X, X'), (Y, Y')) &= \coprod_{X \rightarrow Y} \mathcal{C}(X \times Y', X') \\ &\simeq \mathcal{C}(X, Y) \times \mathcal{C}(X \times Y', X'). \end{aligned}$$

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Dependent lenses. Functor lenses for $\mathcal{C}/-$ (contravariant slice functor).

$$\mathbf{DLens}(U \rightarrow X, V \rightarrow Y) = \coprod_{X \rightarrow Y} \mathcal{C}/X(X \times_Y V, U).$$

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The functor $(X, X') \mapsto (X \times X' \rightarrow X)$ embeds lenses inside dependent lenses.

We are replacing trivial bundles $X \times X' \rightarrow X$ with general bundles (aka dependent types) $U \rightarrow X$.

Reverse-mode automatic differentiation

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Applications. Compute gradients in deep learning (backpropagation).

Bidirectionality and composability suggest that lenses might be a good fit.

Reverse-mode automatic differentiation

Let $f: X \rightarrow Y$ be a smooth function between Euclidean spaces.

Then, we can define a lens as follows ($v \in Y^*$ is a dual vector):

$$\text{forward}(x) = f(x) \quad \text{and} \quad \text{backward}(x, v) = (Df(x)^*)v.$$

In other words,

- the **forward** method is given by the function,
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Inefficiency. The forward and backward passes often share computation.

Shared computation between forward and reverse passes

Closure encoding. Combine the forward and backward methods as

$$\begin{aligned} X &\rightarrow Y \times [Y', X'] \\ x &\mapsto (f(x), v \mapsto (Df(x)^*)v) . \end{aligned}$$

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- Default implementation of most automatic differentiation libraries.

Issues.

- No clear representation of shared computation (hidden in a closure).
- We actually need dependent lenses in general, but the equivalent of $X \rightarrow Y \times [Y', X']$ for dependent lenses is complicated.

Optics

Let M be a space of *shared* data (between forward and backward passes).

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Key intuition. If \mathcal{C} is a category with finite products,

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Efficiency. The morphism r can read data from M instead of recomputing it (Diffraction.jl).

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The Cartesian product can be replaced with a general symmetric monoidal structure

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where \cdot_L, \cdot_R are *actegories*: actions of a monoidal category \mathcal{M} on $\mathcal{C}_L, \mathcal{C}_R$ respectively.

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Issue. Unfortunately, this is not sufficient to generalize functor lenses, where one has a pseudofunctor to **Cat** rather than an actegory.

Key intuition. An actegory is a pseudofunctor from a bicategory with one object to **Cat**. Milewski (2022), Vertechhi (2022), and Capucci (2022) allow an arbitrary source bicategory.

The category of dependent optics

Setting. Let \mathcal{B} be a bicategory. Let $\mathcal{L}, \mathcal{R}: \mathcal{B}^{\text{op}} \rightrightarrows \mathbf{Cat}$ be pseudofunctors.

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- objects of the form $(X, X')^A$, where $A \in \text{Ob}(\mathcal{B})$, $X \in \text{Ob}(\mathcal{L}^A)$, and $X' \in \text{Ob}(\mathcal{R}^A)$,
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Theorem. $\mathbf{Optic}_{\mathcal{L}, \mathcal{R}}$ is a category.

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- \mathcal{B} is a 1-category and \mathcal{L} is trivial \Rightarrow functor lenses.

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Properties.

☑ **Coproducts.** If \mathcal{B} has finite coproducts which are turned into products by \mathcal{L}, \mathcal{R} , then the category $\mathbf{Optic}_{\mathcal{L},\mathcal{R}}$ has finite coproducts.

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☒ **Fibration.** There is in general no fibration $\mathbf{Optic}_{\mathcal{L},\mathcal{R}} \rightarrow \mathcal{B}$, due to the equivalence relation induced by coend. We need the bicategory of optics, as in Braithwaite et. al (2021).

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☐ **Monoidal structure.** Monoidality result for functor lenses may be valid here too.

Functor lenses as dependent optics, take 2

- With trivial \mathcal{L} and only trivial 2-morphisms in \mathcal{B} , we can't use f to share computation.
- f becomes, in a sense, the forward part of the optic.
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Lenses as optics.

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Dependent lenses as optics. Replace product with fibered product:

$$\int^{M \in \mathcal{C}/(A \times B)} \mathcal{C}/A(X, M \times_B Y) \times \mathcal{C}/A(M \times_B Y', X') \simeq \coprod_{X \rightarrow Y} \mathcal{C}/A(X \times_B Y', X').$$

The RHS is the set of dependent lenses from $(X \times_A X') \rightarrow X$ to $(Y \times_B Y') \rightarrow Y$.

Philosophical FAQs on functor lenses as dependent optics

Is it problematic that different, natural choices of pseudofunctors give rise to the same category of dependent lenses? Which is the most natural?

There is a unique *1-category* of dependent lenses, but at least two reasonable *bicategories* of dependent lenses.

The two choices of pseudofunctors reflect this.

As another example, $\mathbf{Optic}_{(\mathcal{C}, \times)}$ and $\mathbf{Lens}_{(\mathcal{C}, \times)}$ are not really the same: they are different as bicategories. Here, we recover them *separately*.

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What is the forward part of the optic if \mathcal{L} is trivial?

In the *bicategory* of optics, 1-morphisms are given by a coproduct rather than a coend.

$$\coprod_{f \in \mathcal{B}(A, B)} \mathcal{L}^A(X, f^*Y) \times \mathcal{R}^A(f^*Y', X')$$

↓

$$\coprod_{f \in \mathcal{B}(A, B)} \mathcal{L}^A(X, f^*Y).$$

Intuitively, the image of a 1-morphism is its forward part, whereas its value within a fiber is the backward part.

User-facing APIs

How should libraries based on dependent optics (e.g., Diffractor.jl) interface with users?

Dependent optics are encoded as equivalence classes of pairs of maps

$$l: X \rightarrow f^*Y \quad \text{and} \quad r: f'^*Y' \rightarrow X'.$$

The morphism f is somewhat ill-defined (due to the equivalence class).

How can it be hidden from the user?

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How can it be hidden from the user?

1. **Direct computation.** Compute coend explicitly (if possible) and use that as interface.
2. **Optics representation.** Define a functor from the category of optics to a *friendlier* category.

Tambara representations

Let \mathcal{D} be an arbitrary category.

Tambara representation. A \mathcal{D} -valued Tambara representation consists of

- a functor $P^A: (\mathcal{L}^A)^{\text{op}} \times \mathcal{R}^A \rightarrow \mathcal{D}$, for all object A in \mathcal{B} ,
- a natural transformation $\zeta_f: P^B(-, =) \Rightarrow P^A(f^* -, f^{*'} =)$ for all $f: A \rightarrow B$,

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Example. In the case of dependent lenses, we have a **Set**-valued Tambara representation

$$(X, X')^A \mapsto \mathcal{C}/A(X, X').$$

Geometric intuition. In the reverse-mode automatic differentiation case, it corresponds to the pullback of differential 1-forms along smooth maps.

Conclusions

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- ☐ What can one say about Tambara representations for special cases of dependent optics?

Thank you!

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