

# *Universality of asymmetric lens proxy pullbacks*



THE UNIVERSITY  
*of* EDINBURGH

*Applied Category Theory 2022*

Matthew Di Meglio





With	Index	Kind	Message
Ava	0	sent	Hi
	1	received	Hey
	2	sent	What's new?
	3	draft	I'm g
Cam	0	received	Hey



Current Time | 12:49

Time	From	To	Message
09:00	Matt	Ava	Hi
11:11	Bob	Ava	Gday
11:15	Ava	Matt	Hey
12:23	Matt	Ava	What's new?
12:31	Cam	Matt	Hello



With	Index	Kind	Message
Ava	0	sent	Hi
	1	received	Hey
	2	sent	What's new?
	3	draft	I'm g
Cam	0	received	Hey



Current Time | 12:49



Time	From	To	Message
09:00	Matt	Ava	Hi
11:11	Bob	Ava	Gday
11:15	Ava	Matt	Hey
12:23	Matt	Ava	What's new?
12:31	Cam	Matt	Hello

With	Index	Kind	Message
Ava	0	sent	Hi
	1	received	Hey
	2	sent	What's new?
	3	draft	I'm g
Cam	0	received	Hey



Current Time | 12:49



Time	From	To	Message
09:00	Matt	Ava	Hi
11:11	Bob	Ava	Gday
11:15	Ava	Matt	Hey
12:23	Matt	Ava	What's new?
12:31	Cam	Matt	Hello

With	Index	Kind	Message
Ava	0	sent	Hi
	1	received	Hey
	2	sent	What's new?
	3	draft	I'm g
Cam	0	received	Hey



Current Time | 12:49



Time	From	To	Message
09:00	Matt	Ava	Hi
11:11	Bob	Ava	Gday
11:15	Ava	Matt	Hey
12:23	Matt	Ava	What's new?
12:31	Cam	Matt	Hello

With	Index	Kind	Message
Ava	0	sent	Hi
	1	received	Hey
	2	sent	What's new?
	3	draft	I'm g
Cam	0	received	Hey

# *Asymmetric delta lens*

# Asymmetric delta lens

Source



View

# Asymmetric delta lens

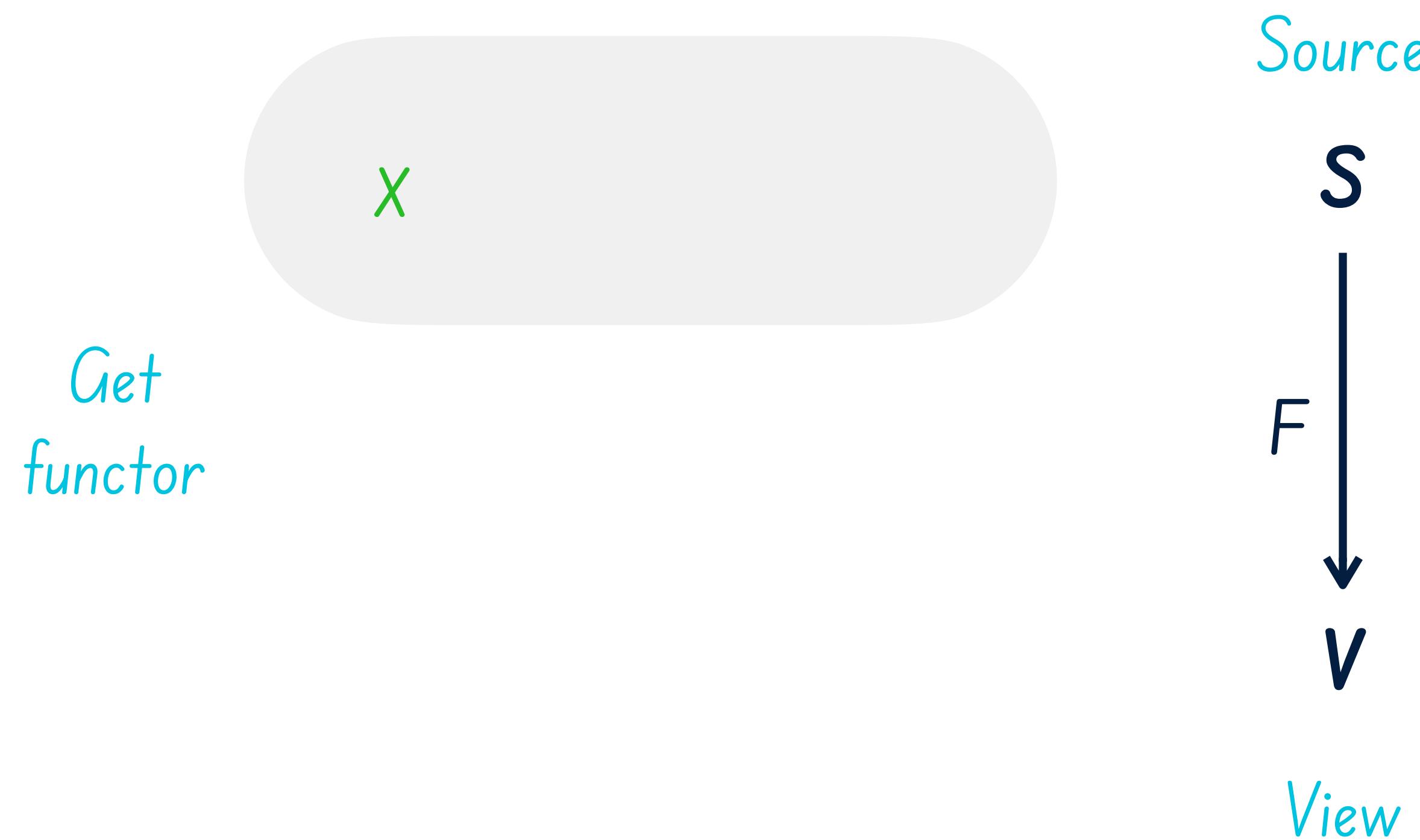
Get  
functor

Source

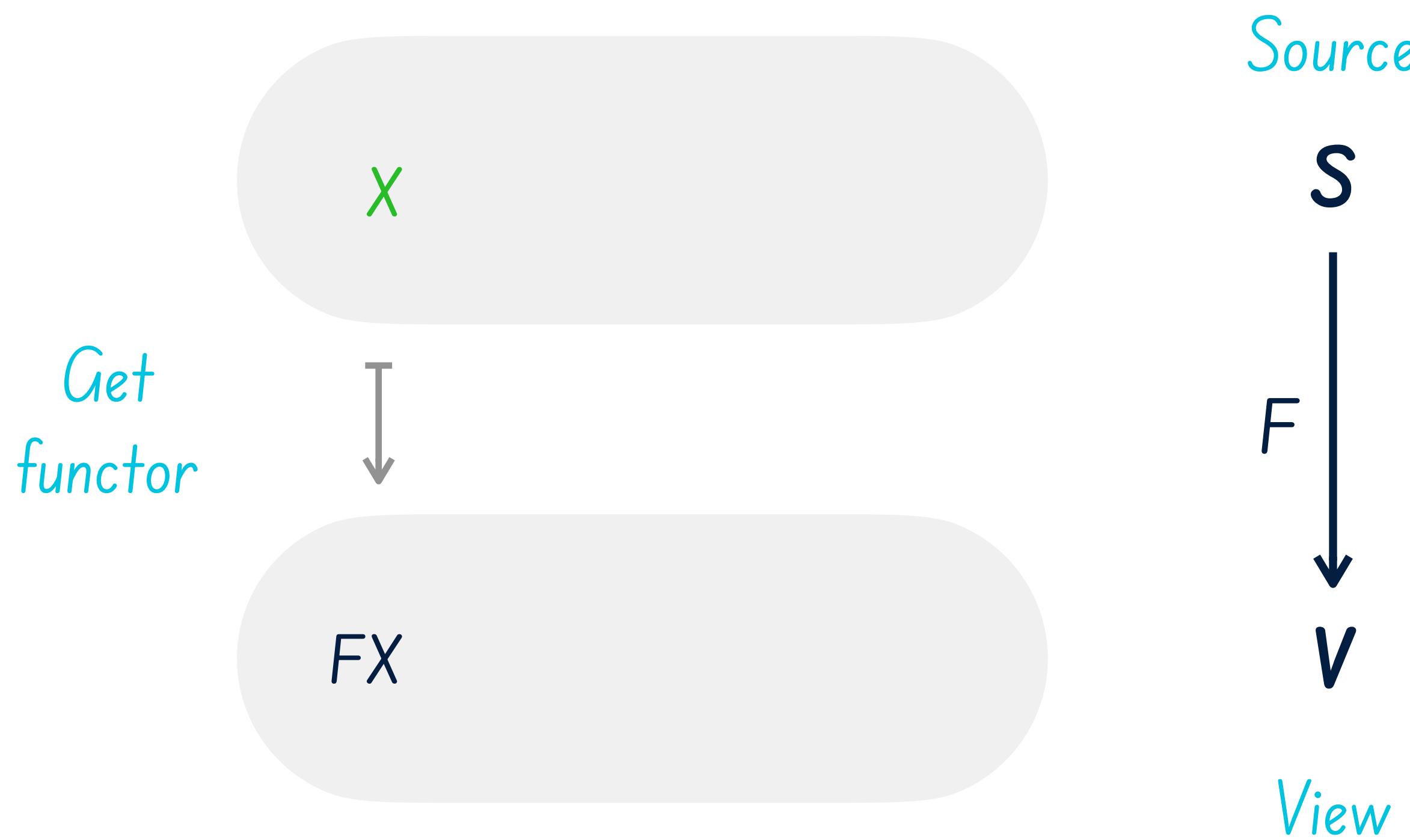


View

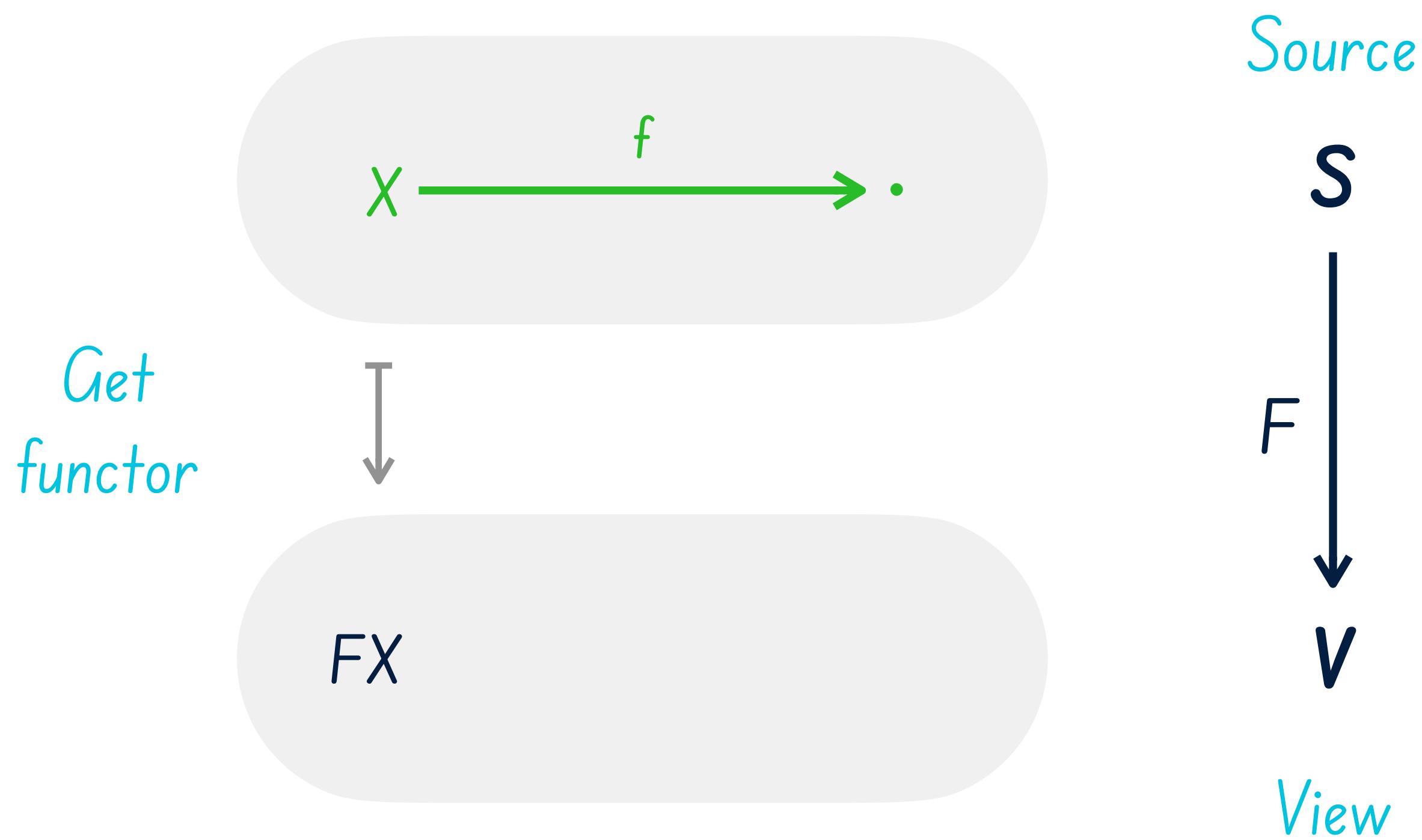
# Asymmetric delta lens



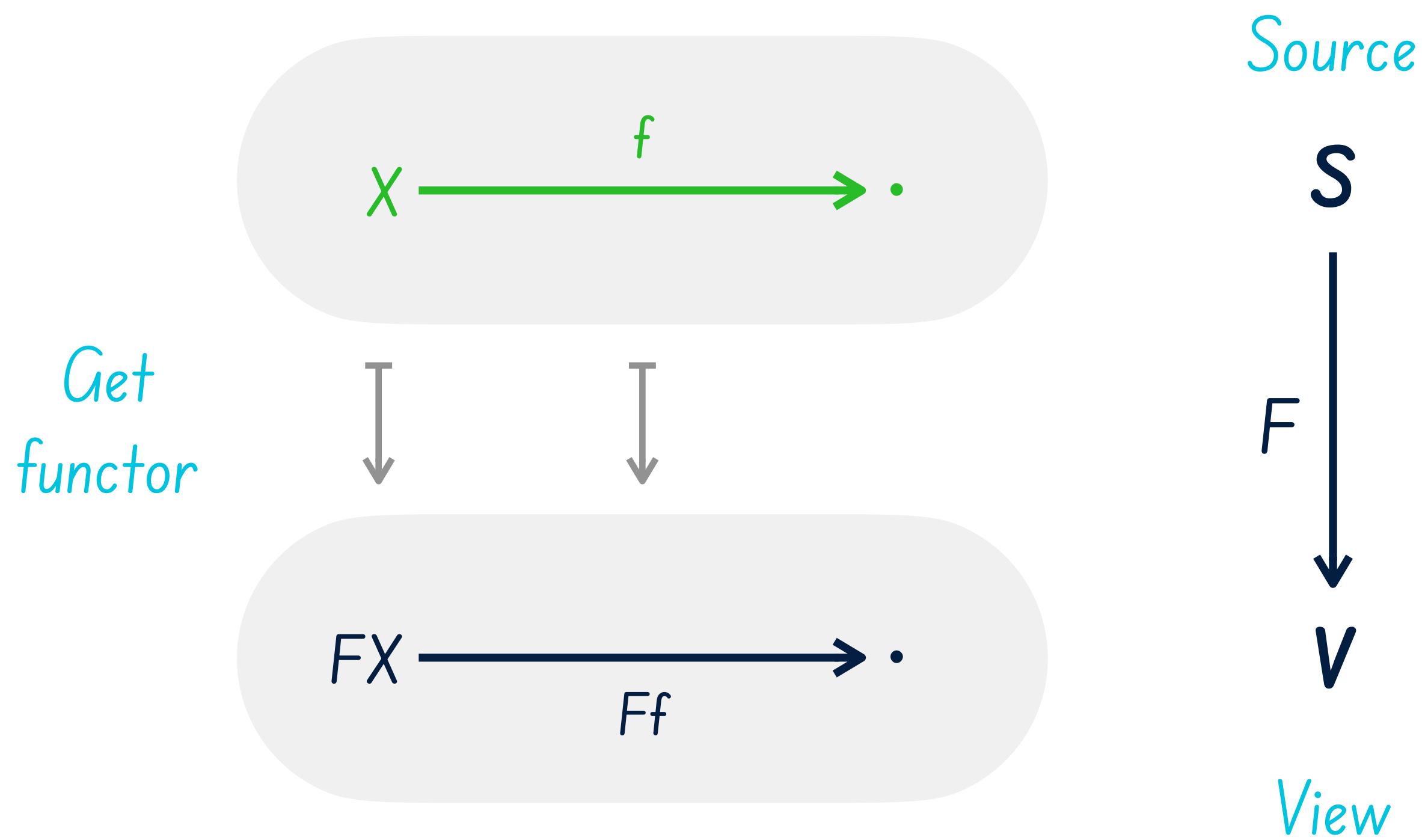
# Asymmetric delta lens



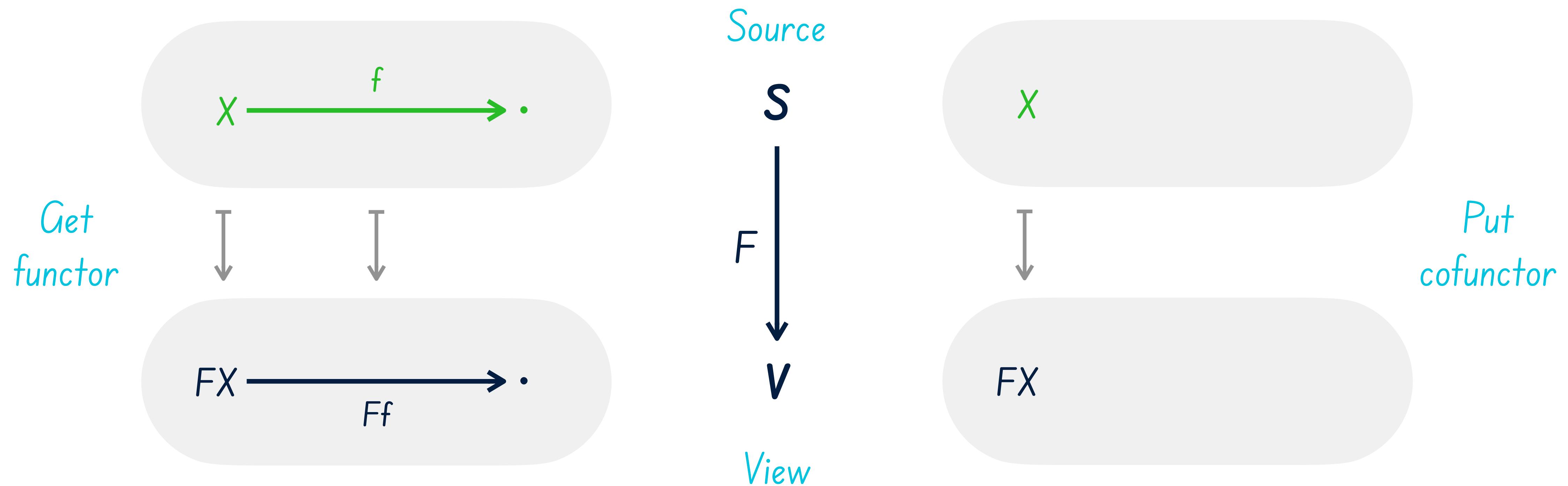
# Asymmetric delta lens



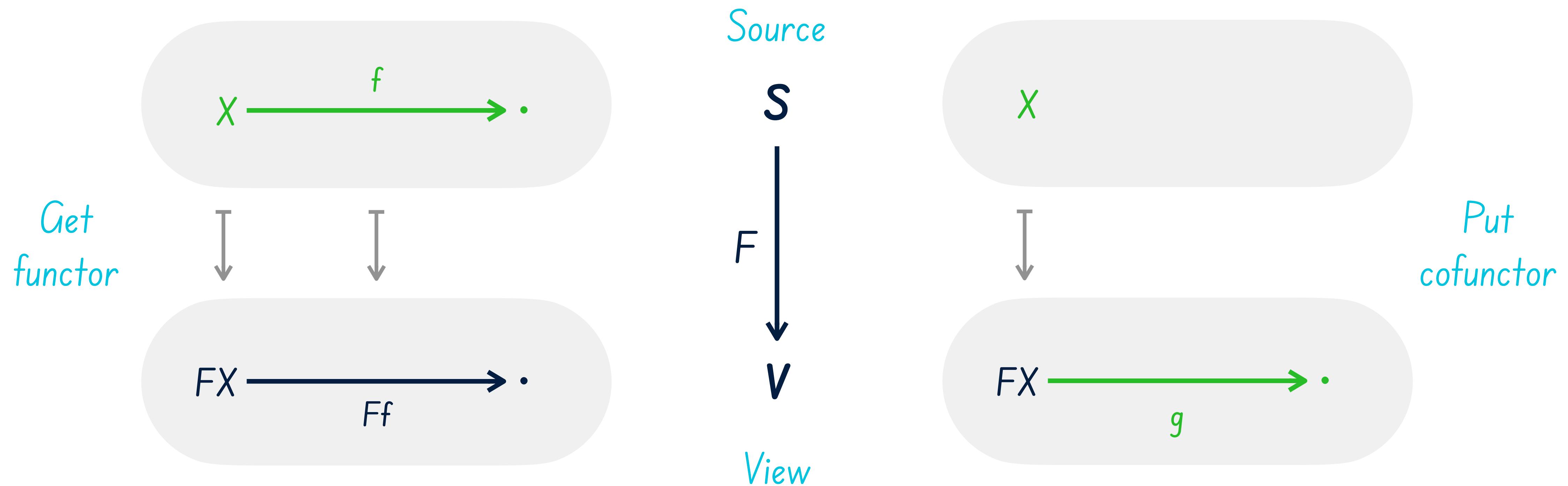
# Asymmetric delta lens



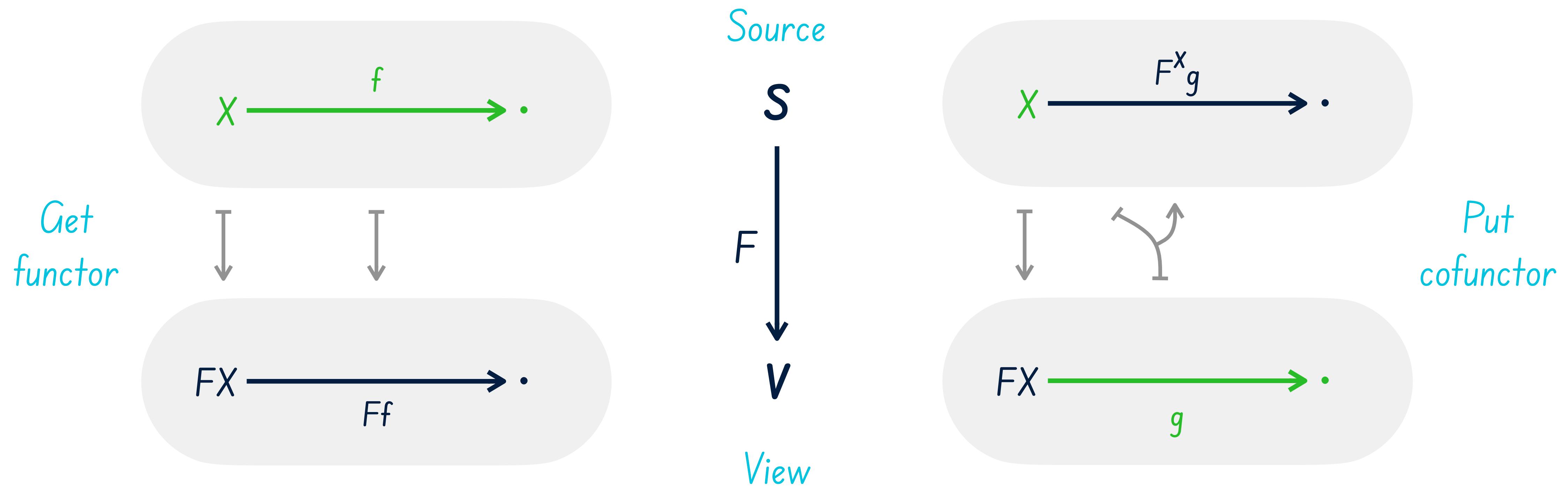
# Asymmetric delta lens



# Asymmetric delta lens

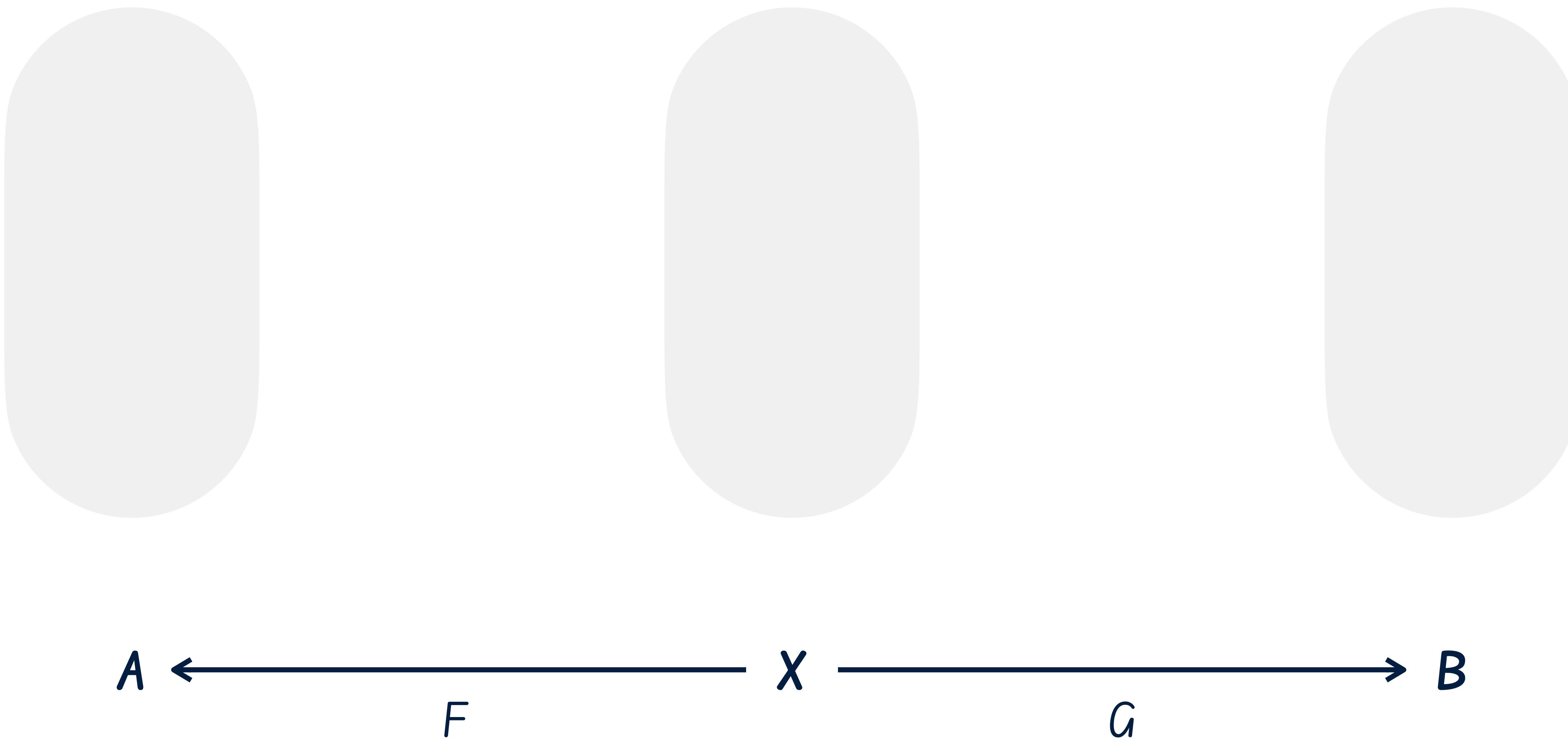


# Asymmetric delta lens

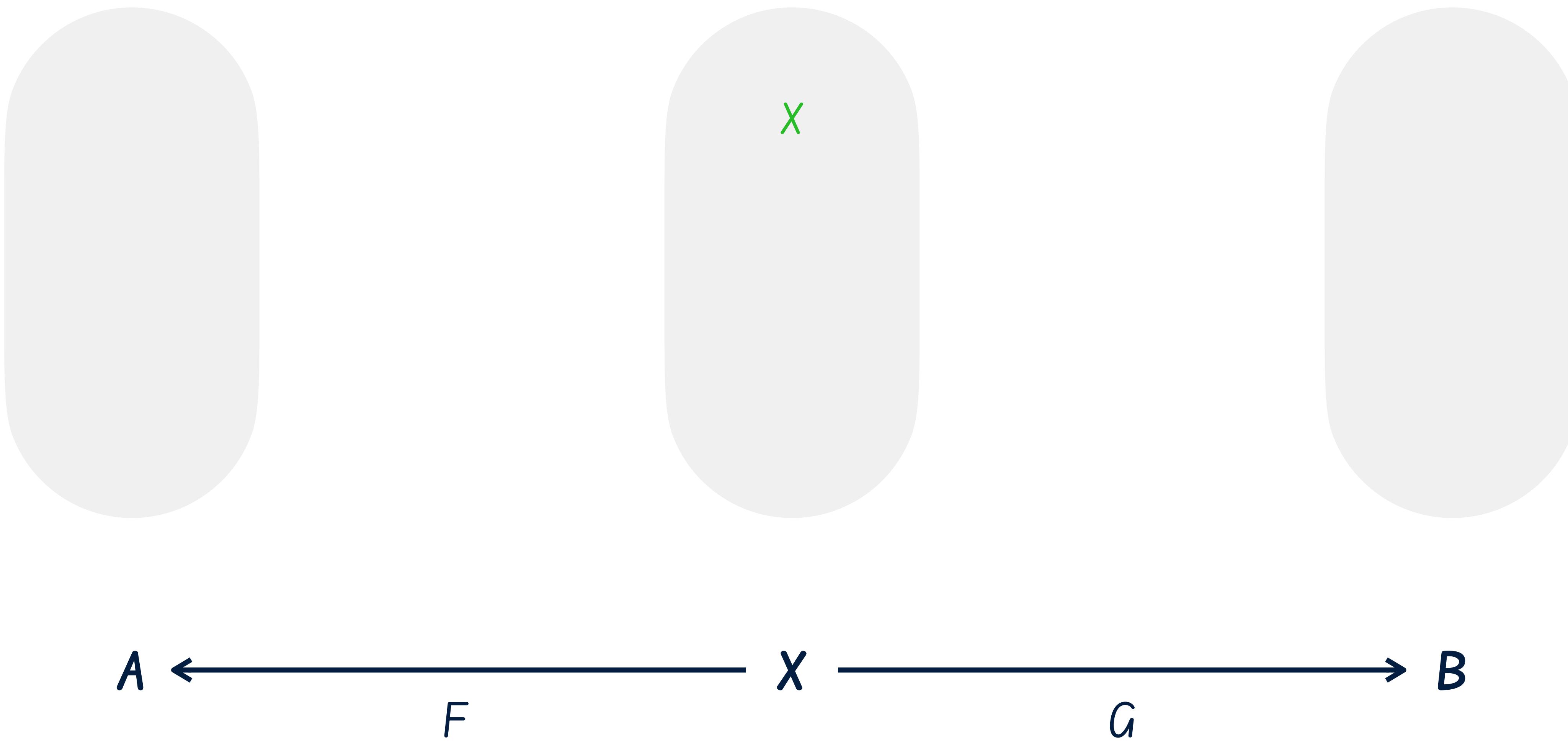


*Lens spans model bidirectional transformations*

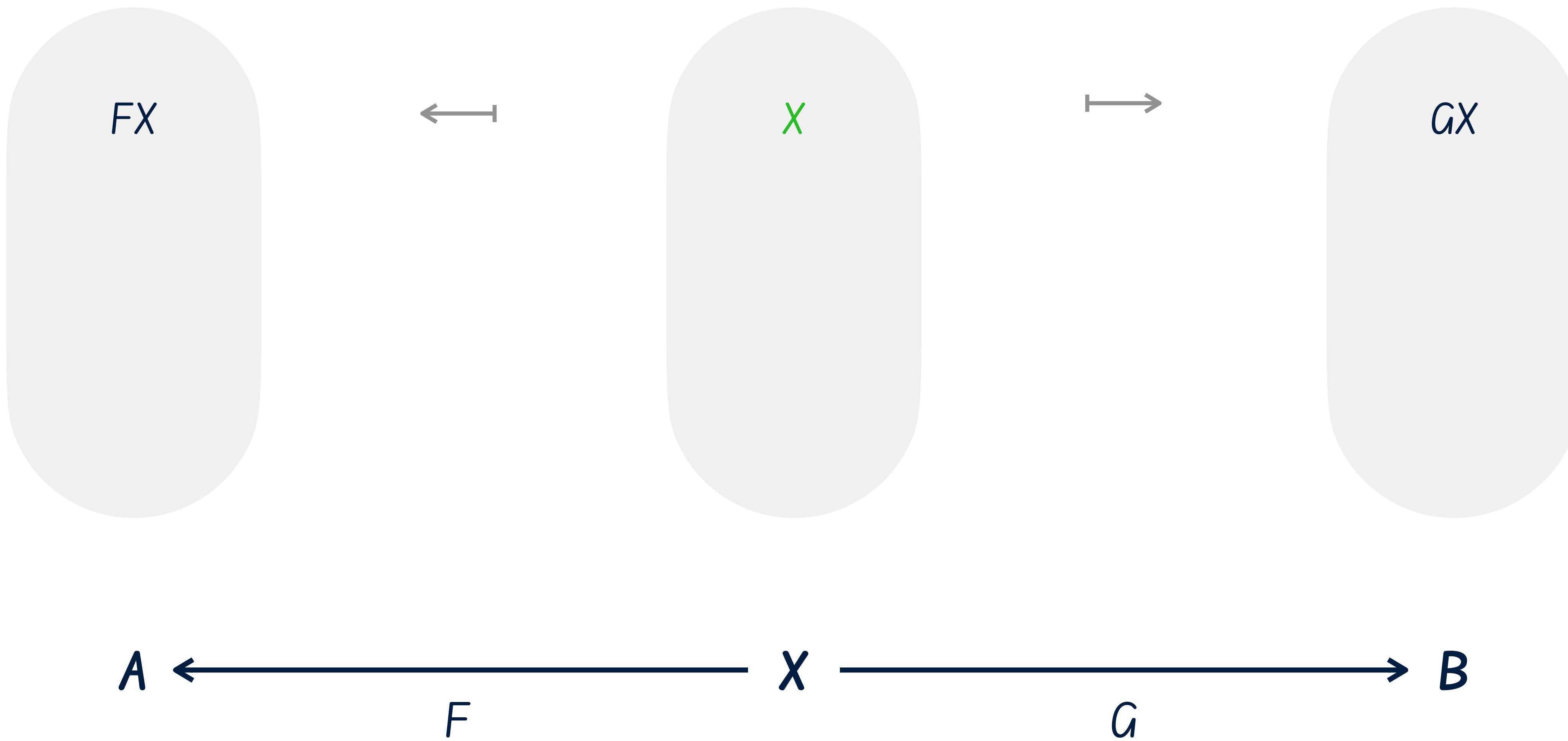
# *Lens spans model bidirectional transformations*



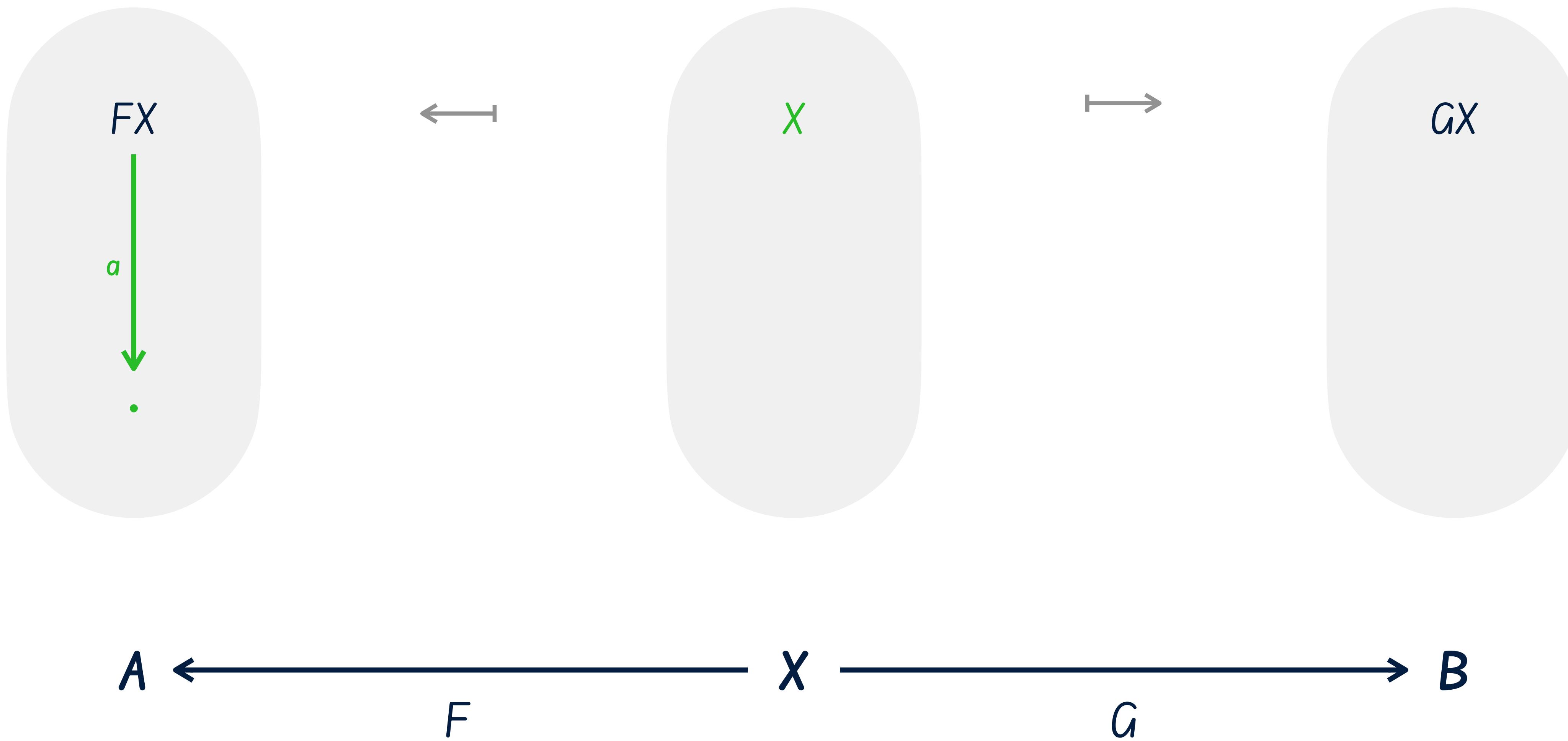
# *Lens spans model bidirectional transformations*



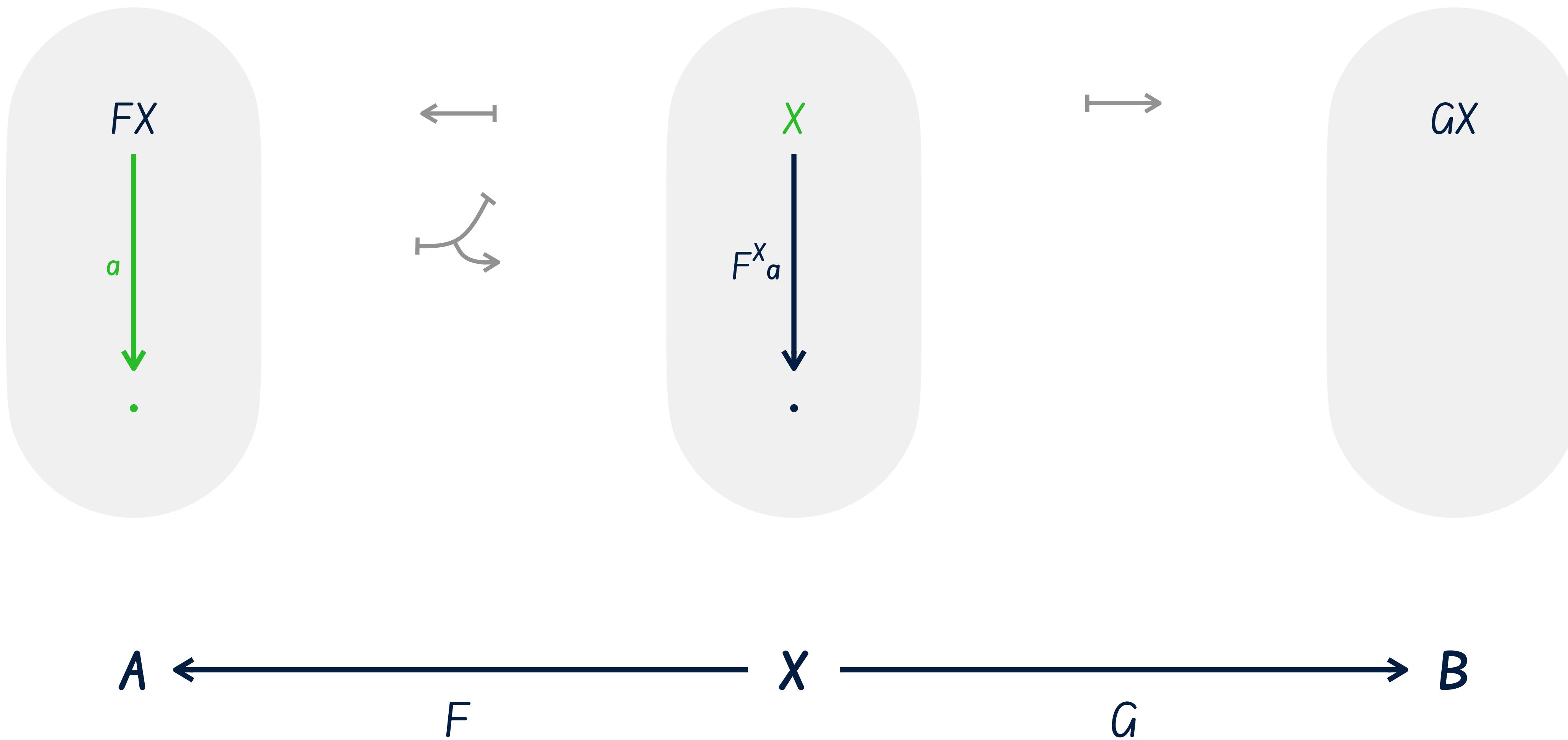
# *Lens spans model bidirectional transformations*



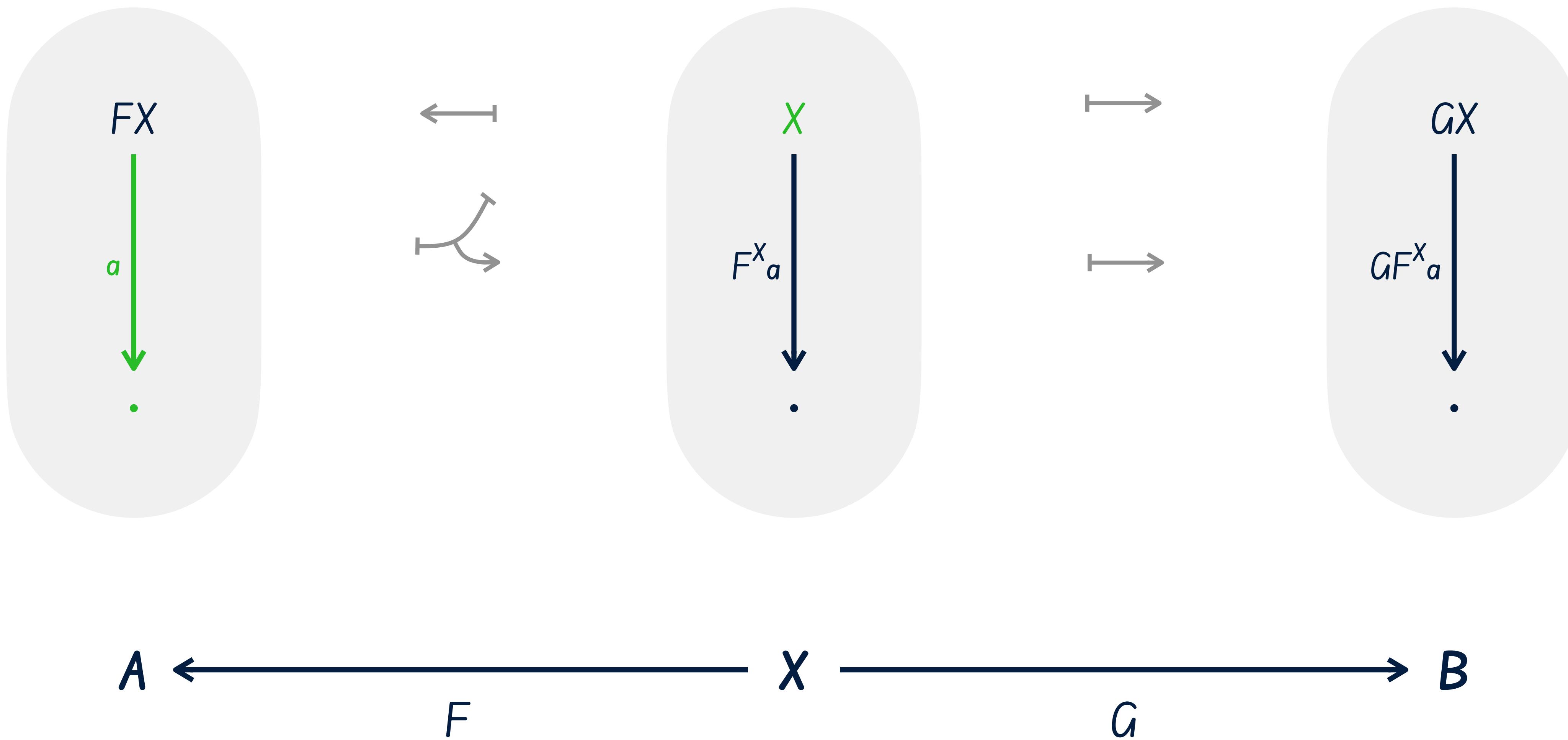
# *Lens spans model bidirectional transformations*



# *Lens spans model bidirectional transformations*

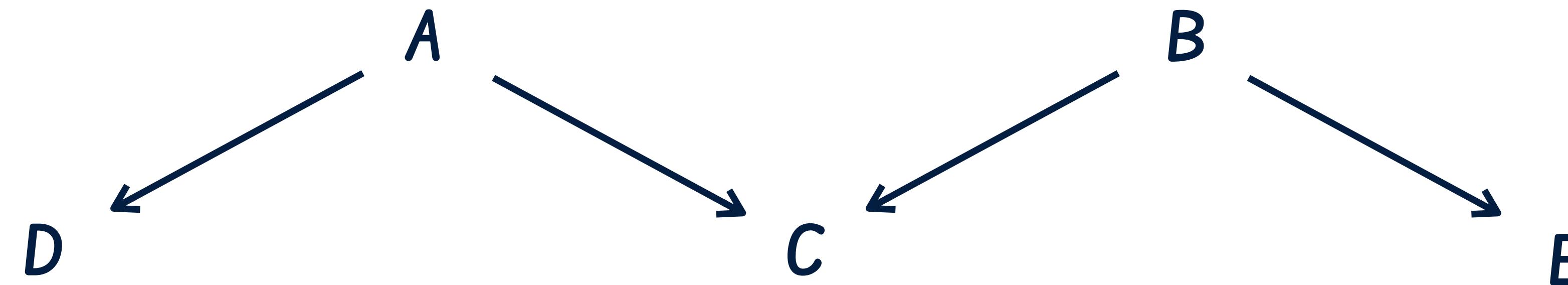


# *Lens spans model bidirectional transformations*

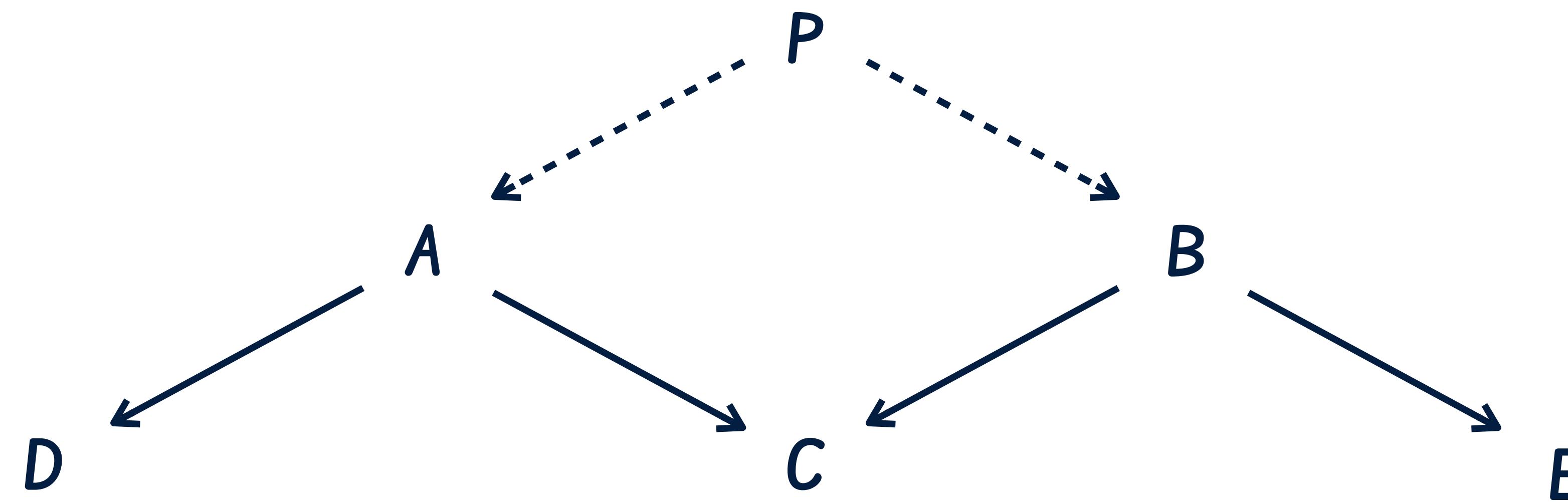


*Span composition by pullback?*

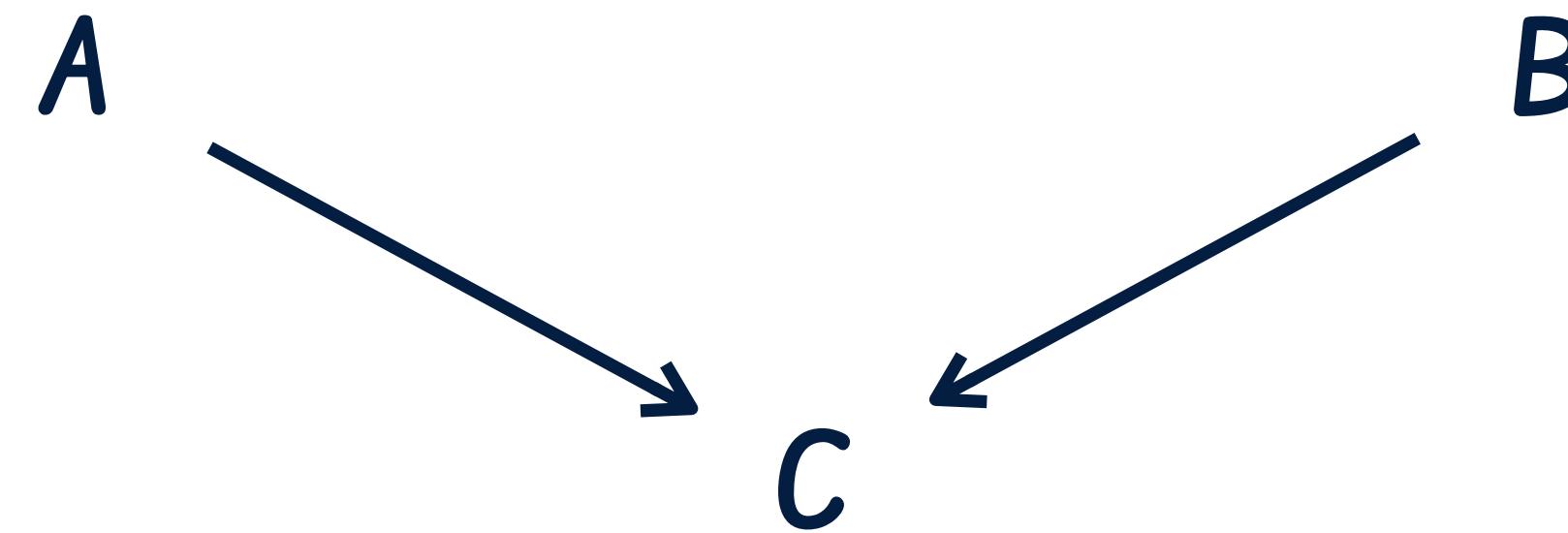
# *Span composition by pullback?*



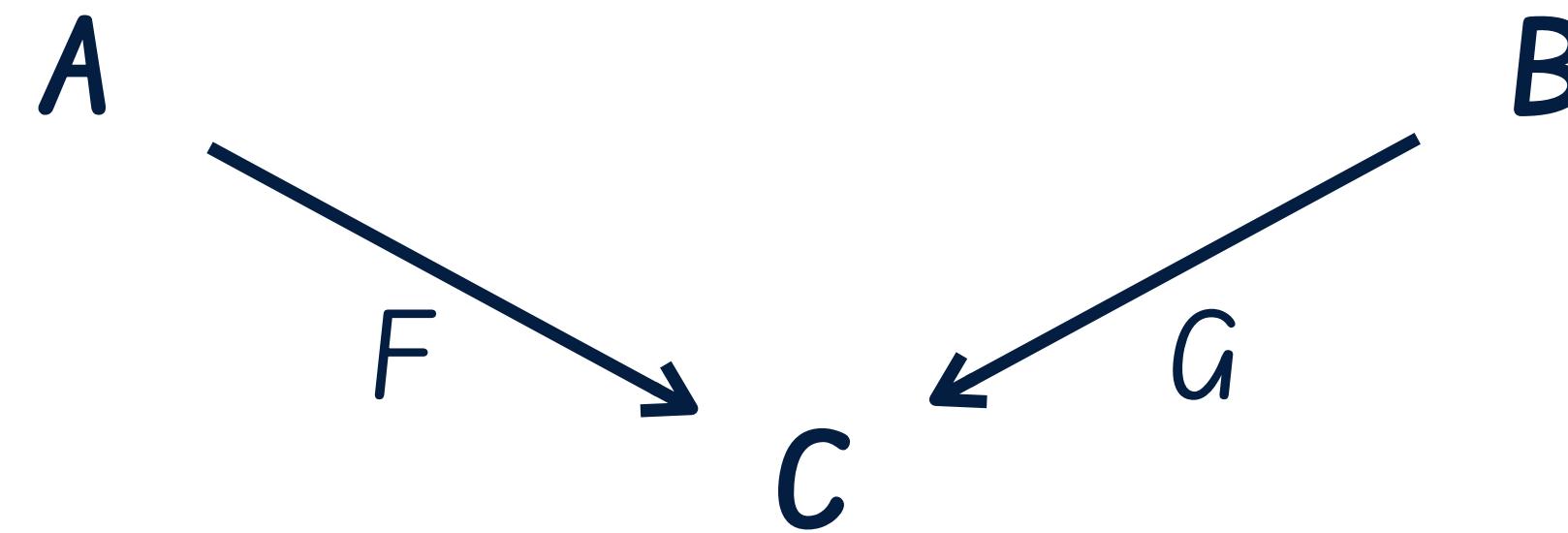
# Span composition by pullback?



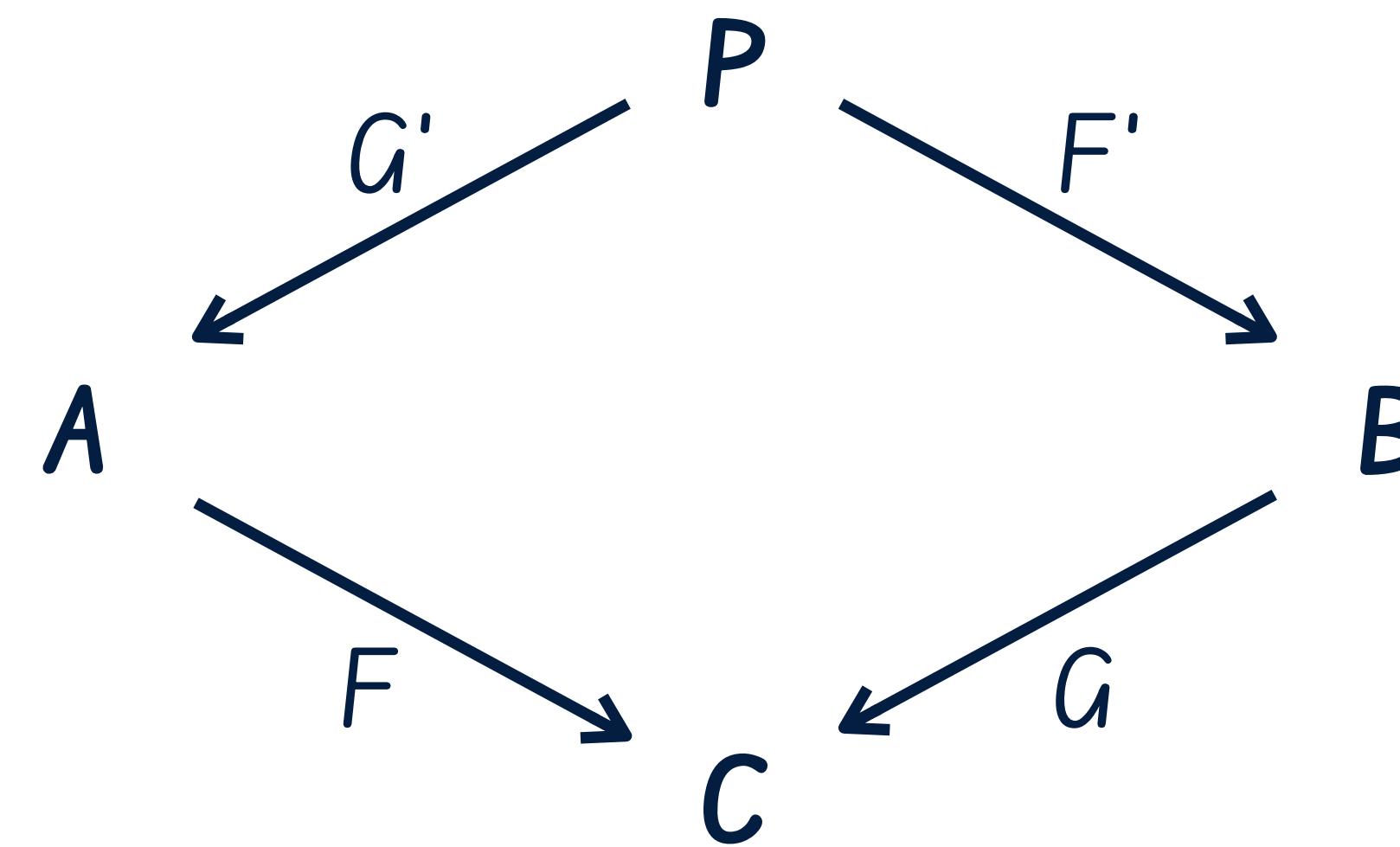
# *Span composition by pullback?*



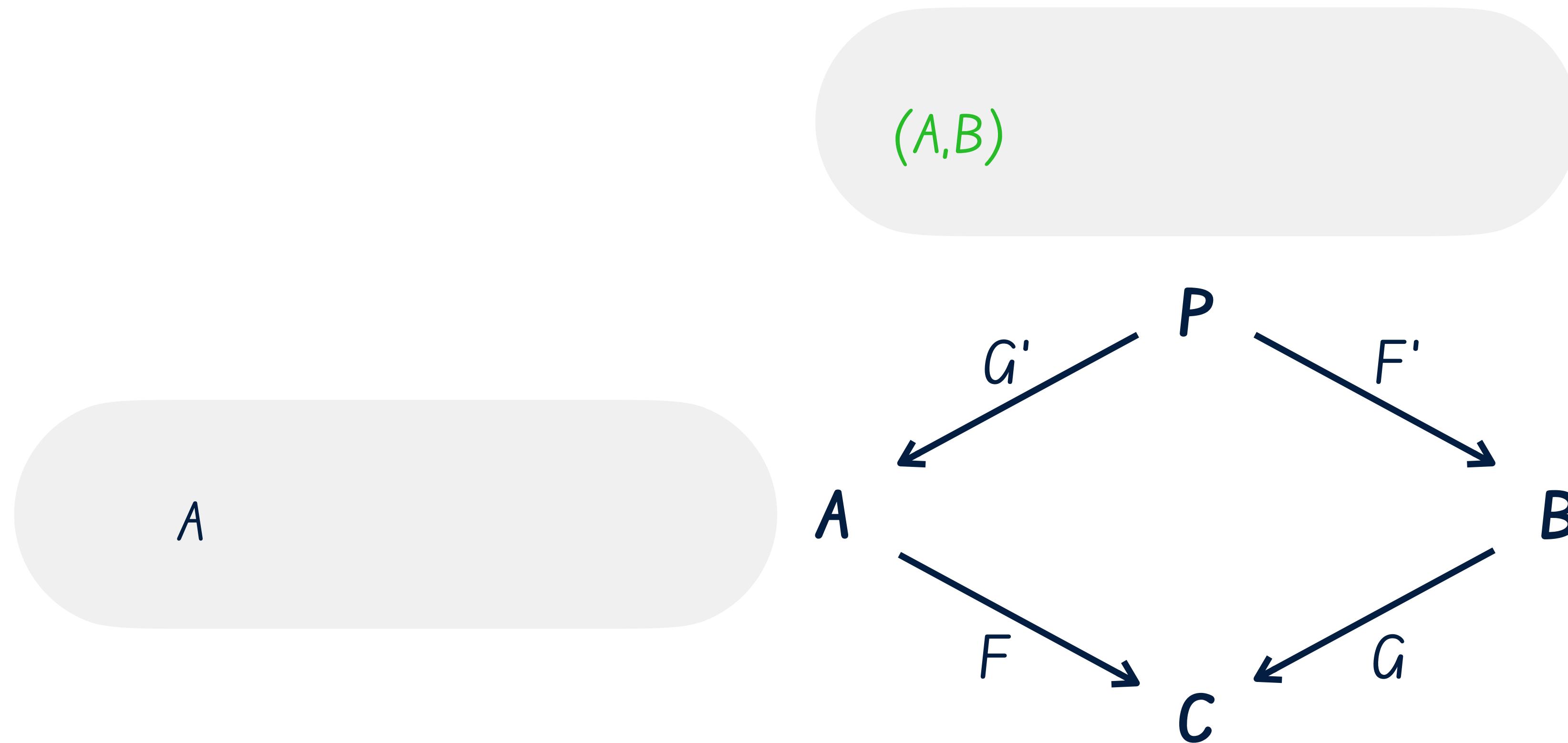
# *Span composition by pullback?*



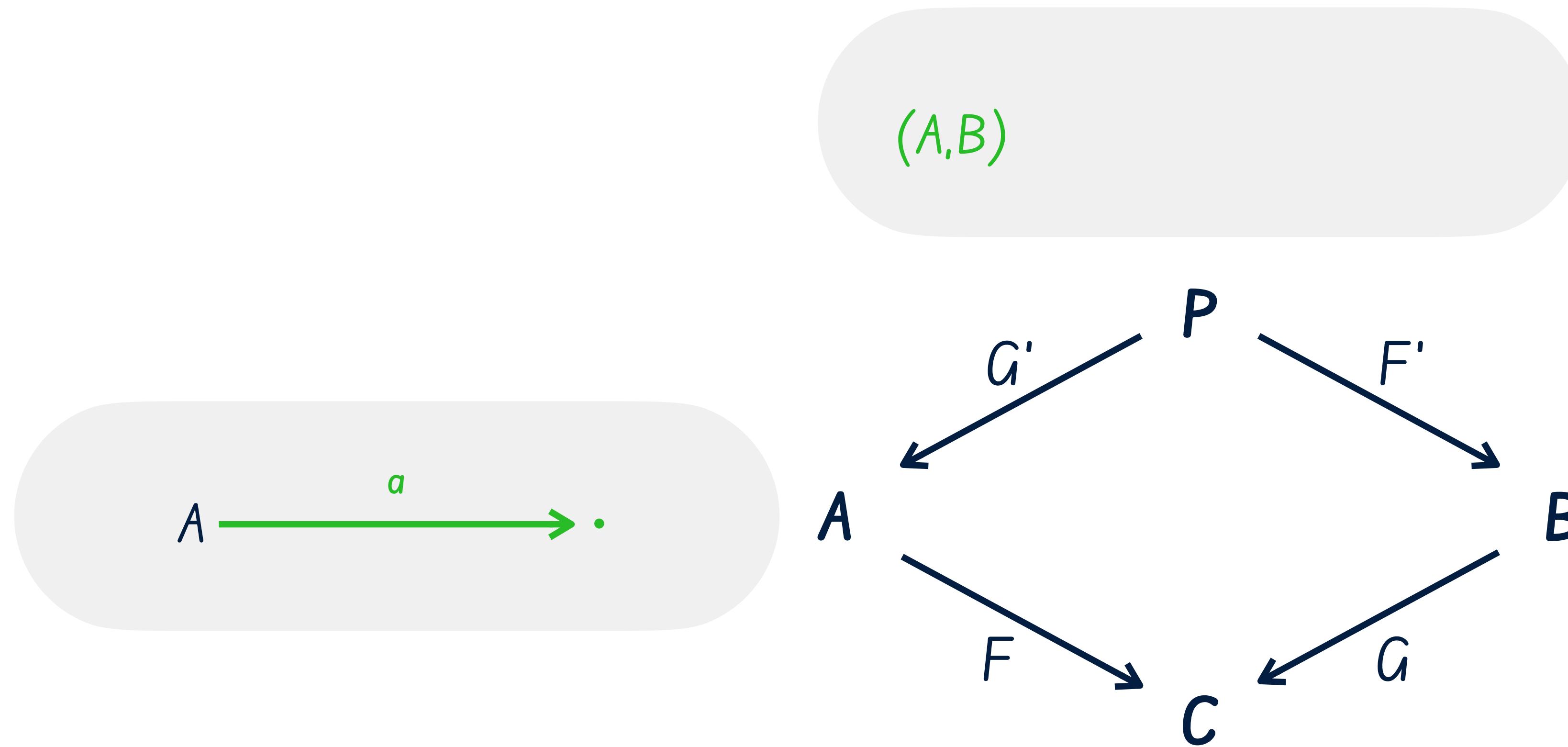
# Span composition by pullback?



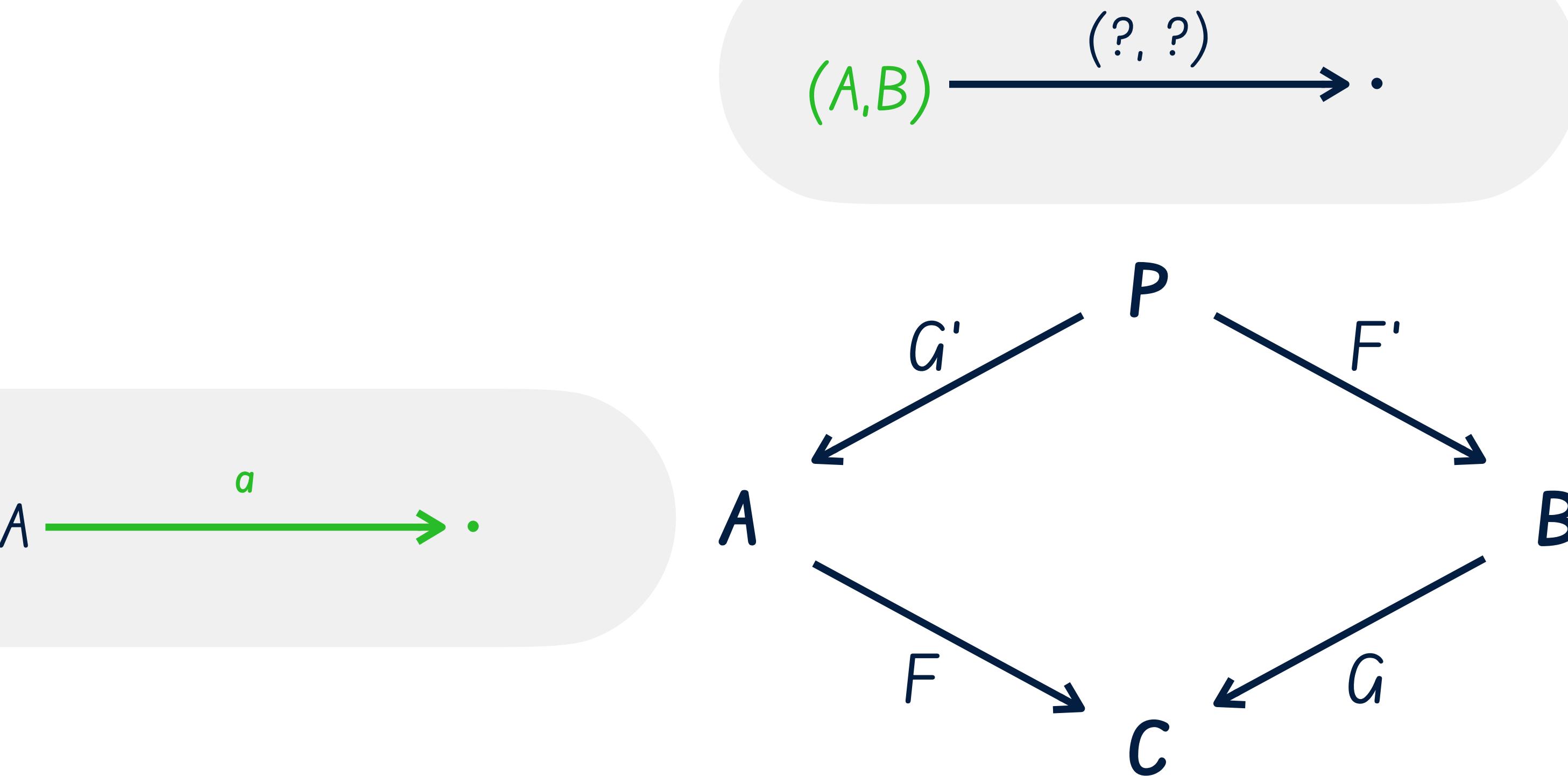
# Span composition by pullback?



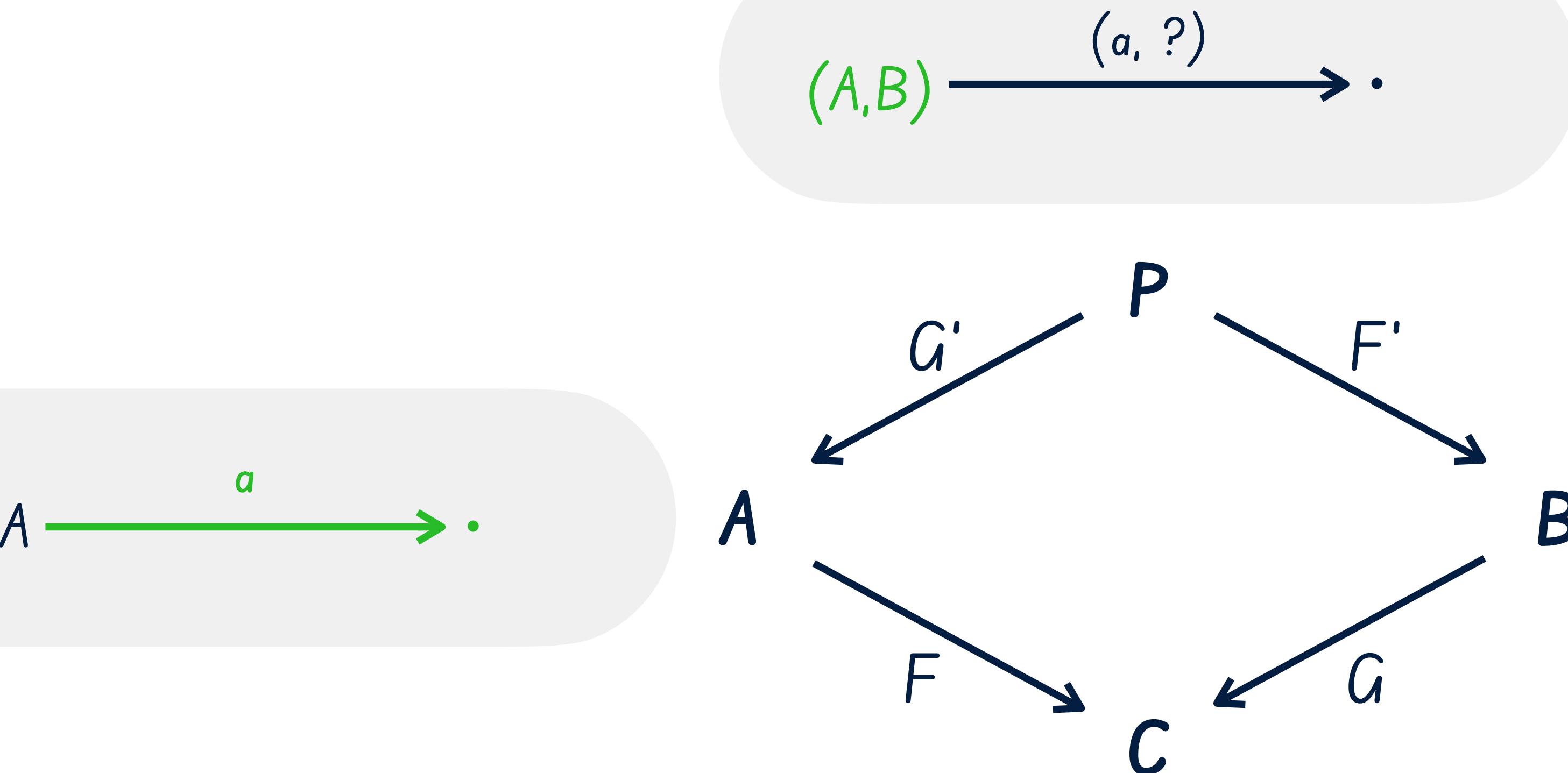
# Span composition by pullback?



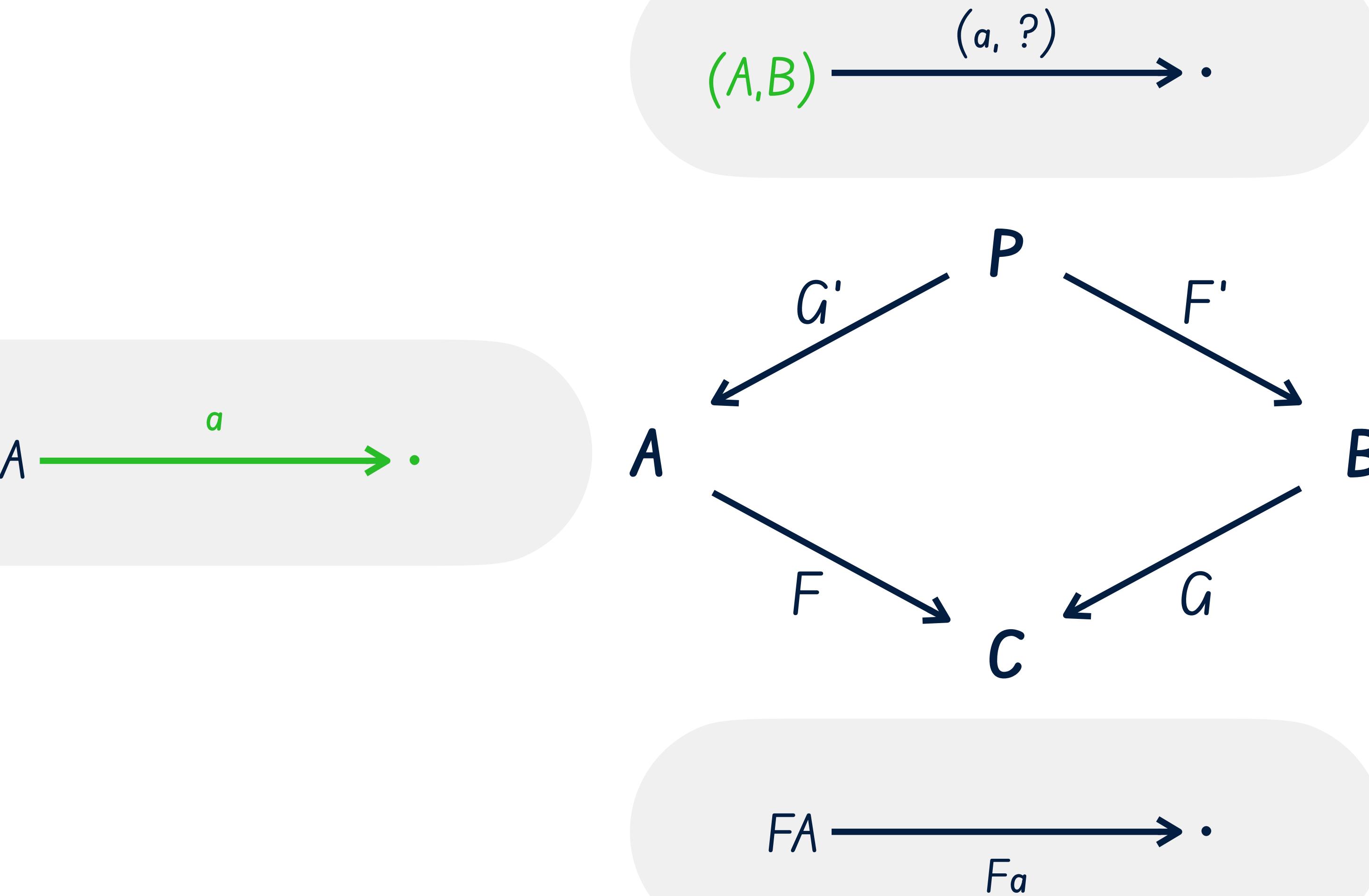
# Span composition by pullback?



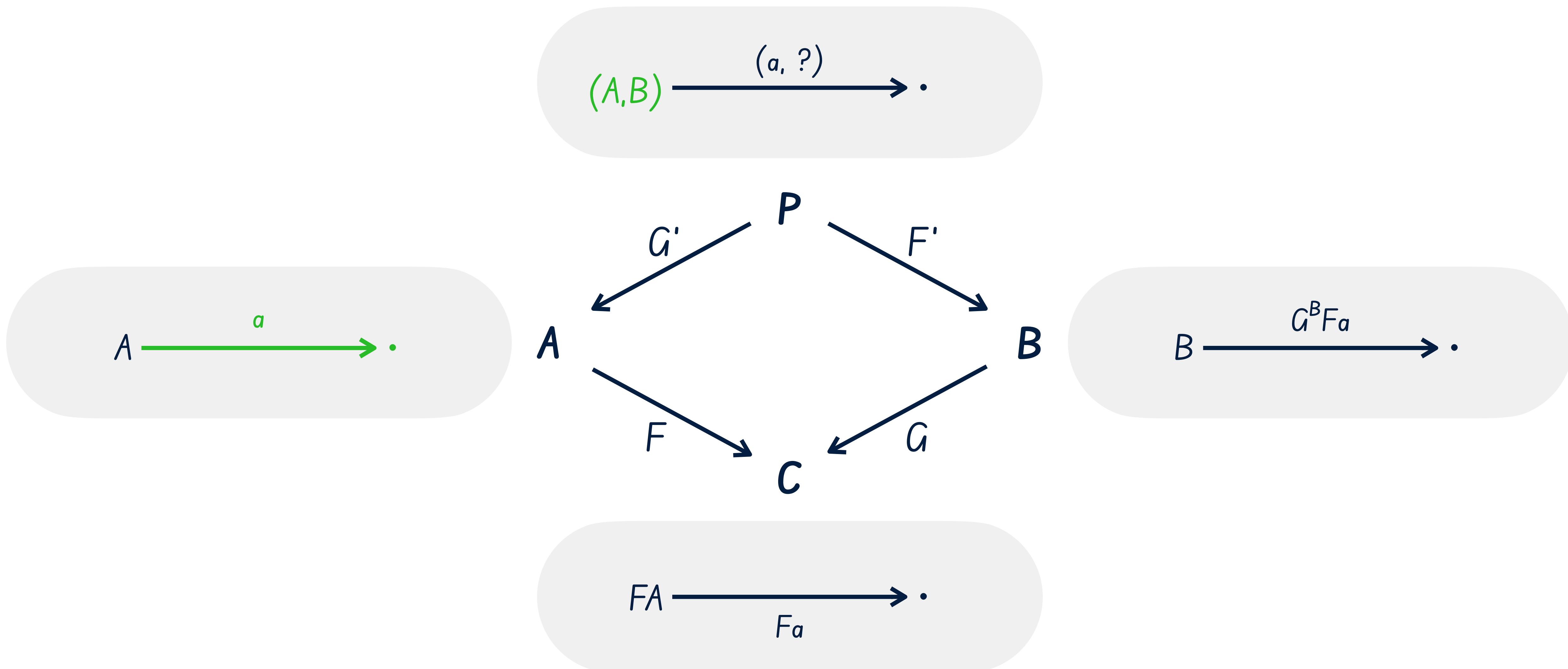
# Span composition by pullback?



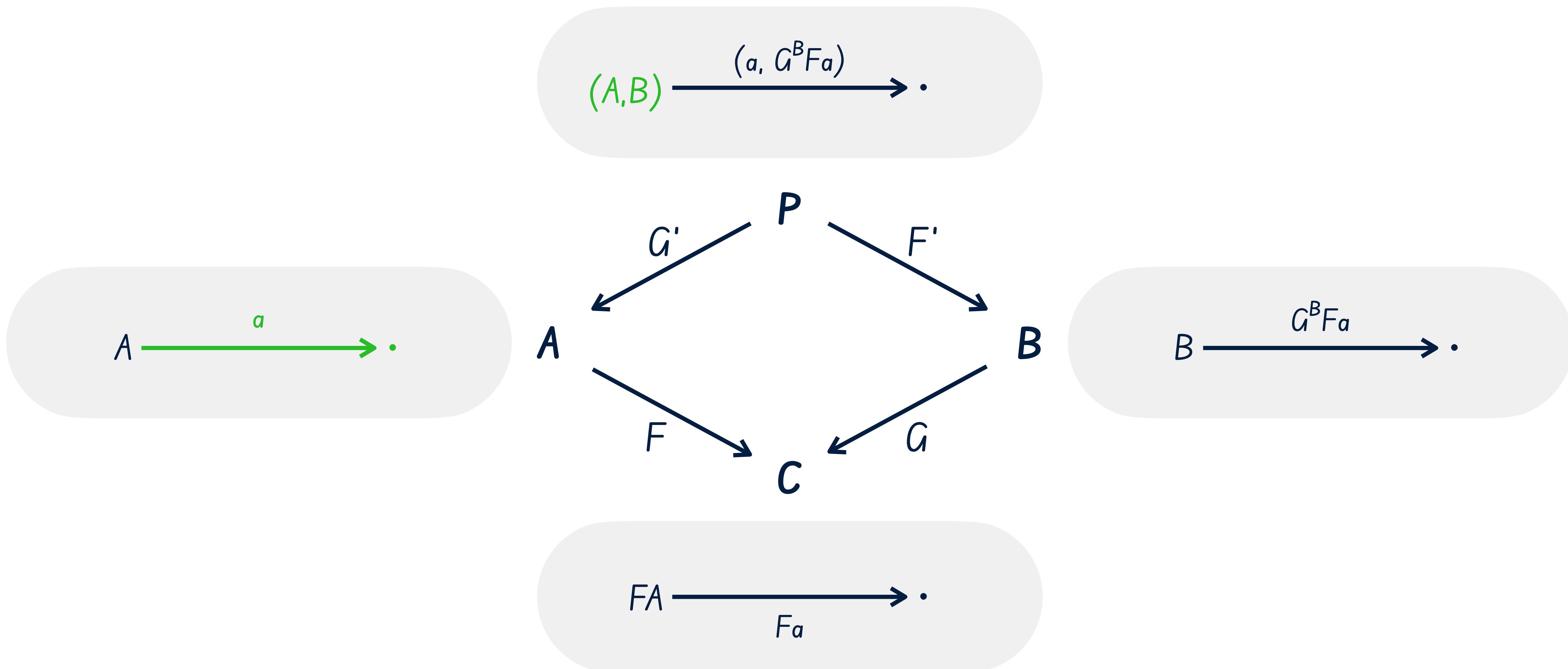
# Span composition by pullback?



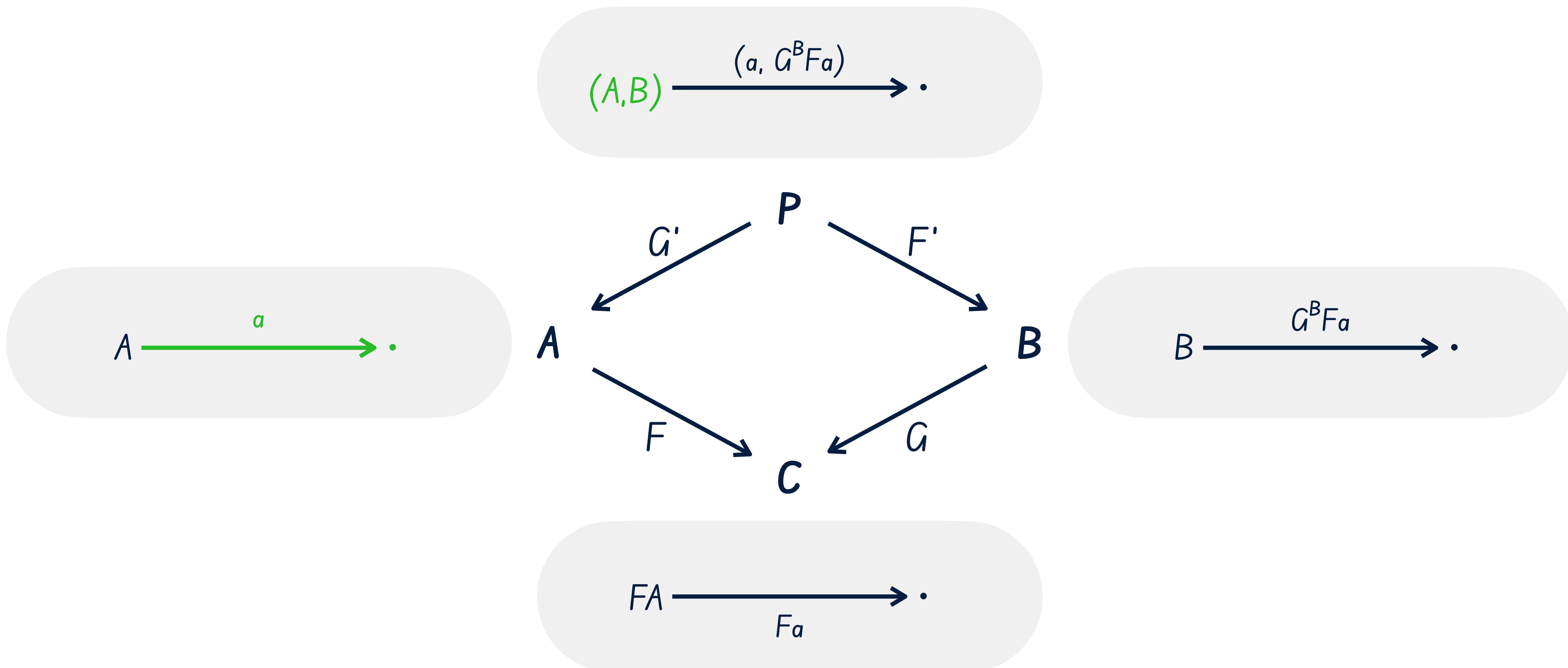
# Span composition by pullback?



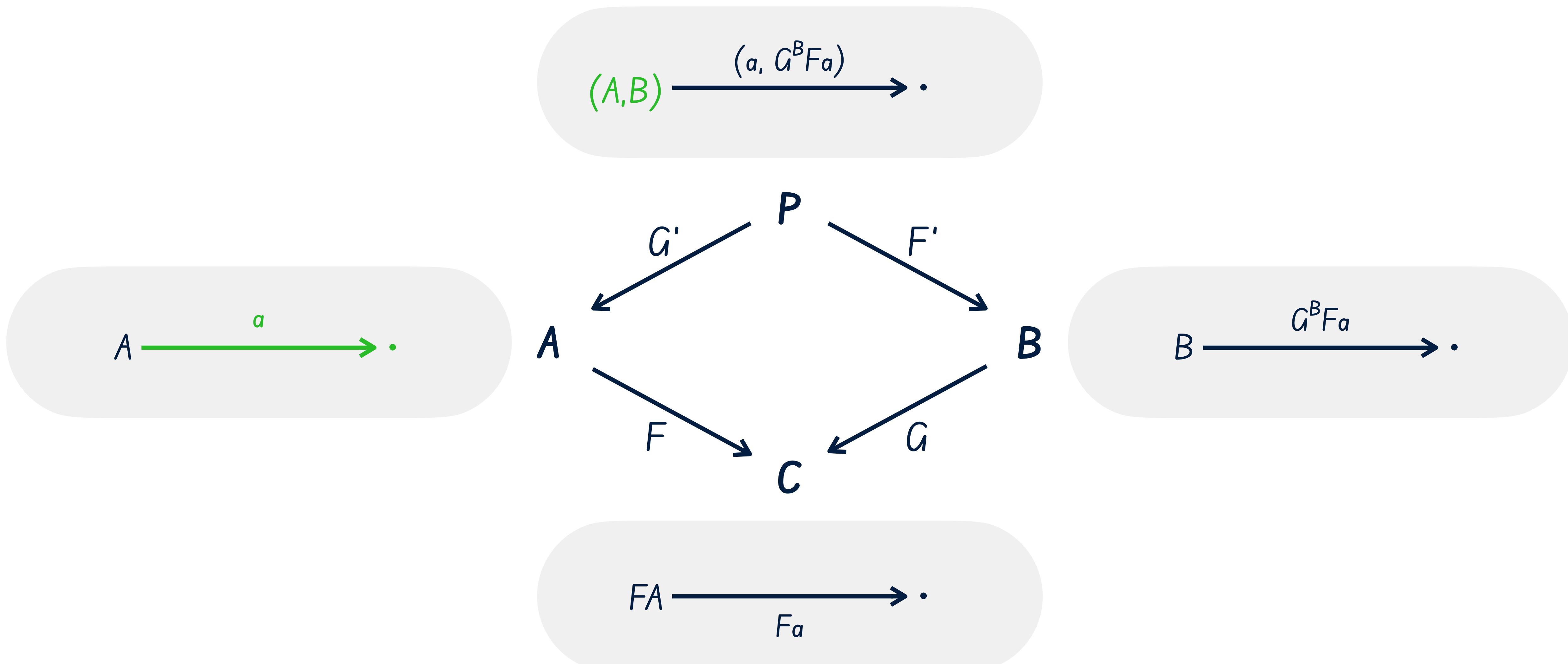
# Span composition by pullback?

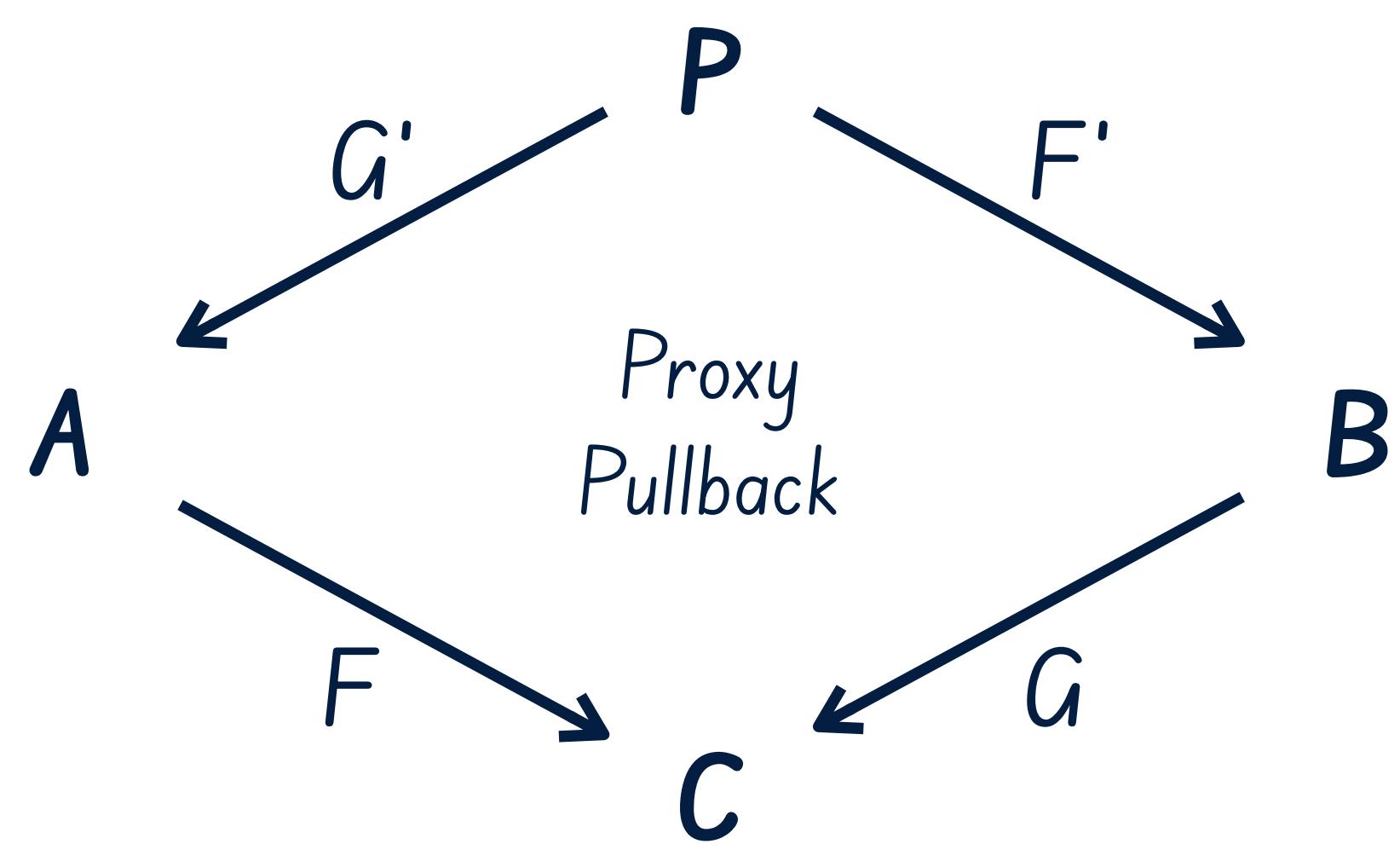


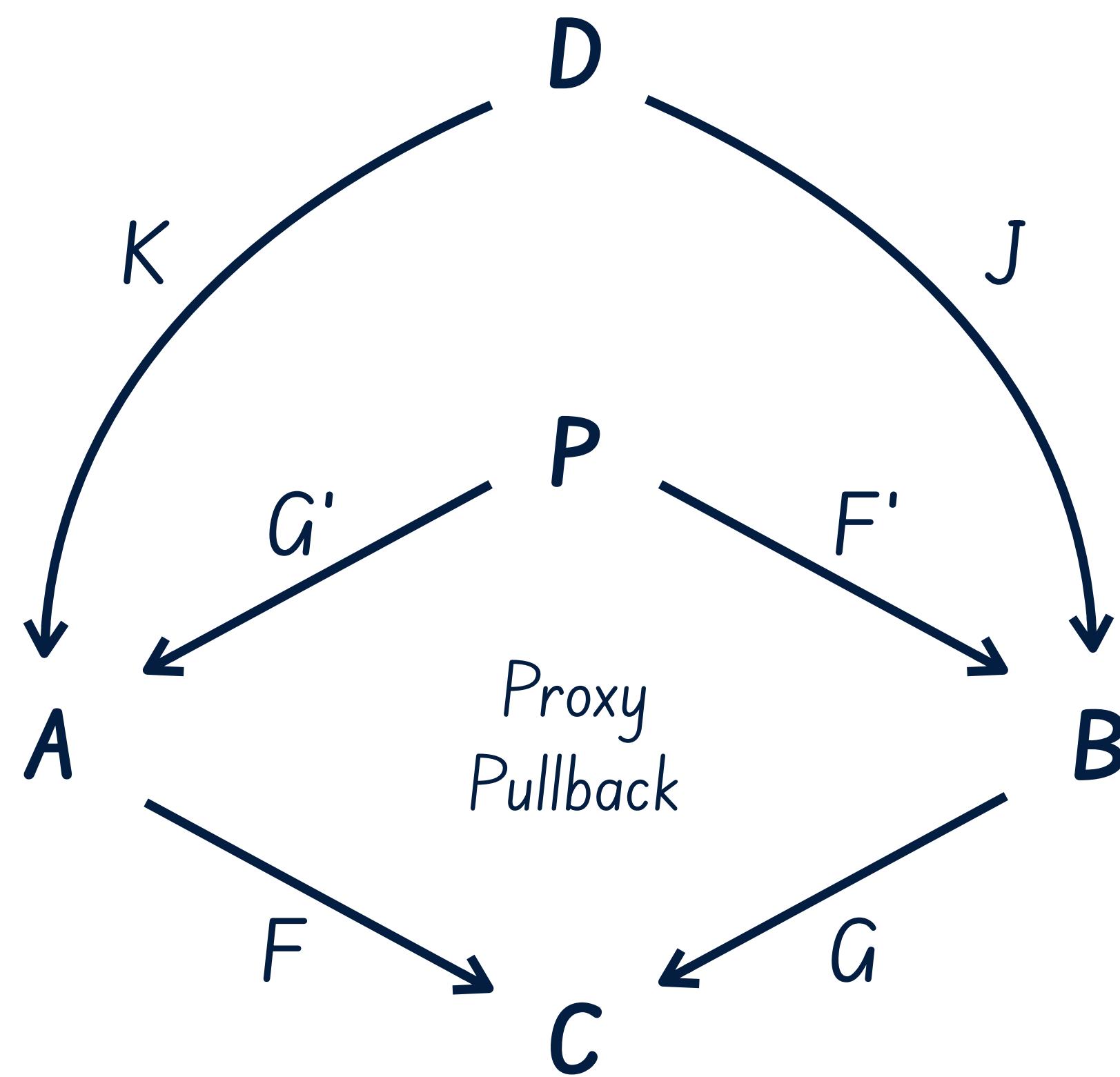
# Span composition by ~~pullback~~?

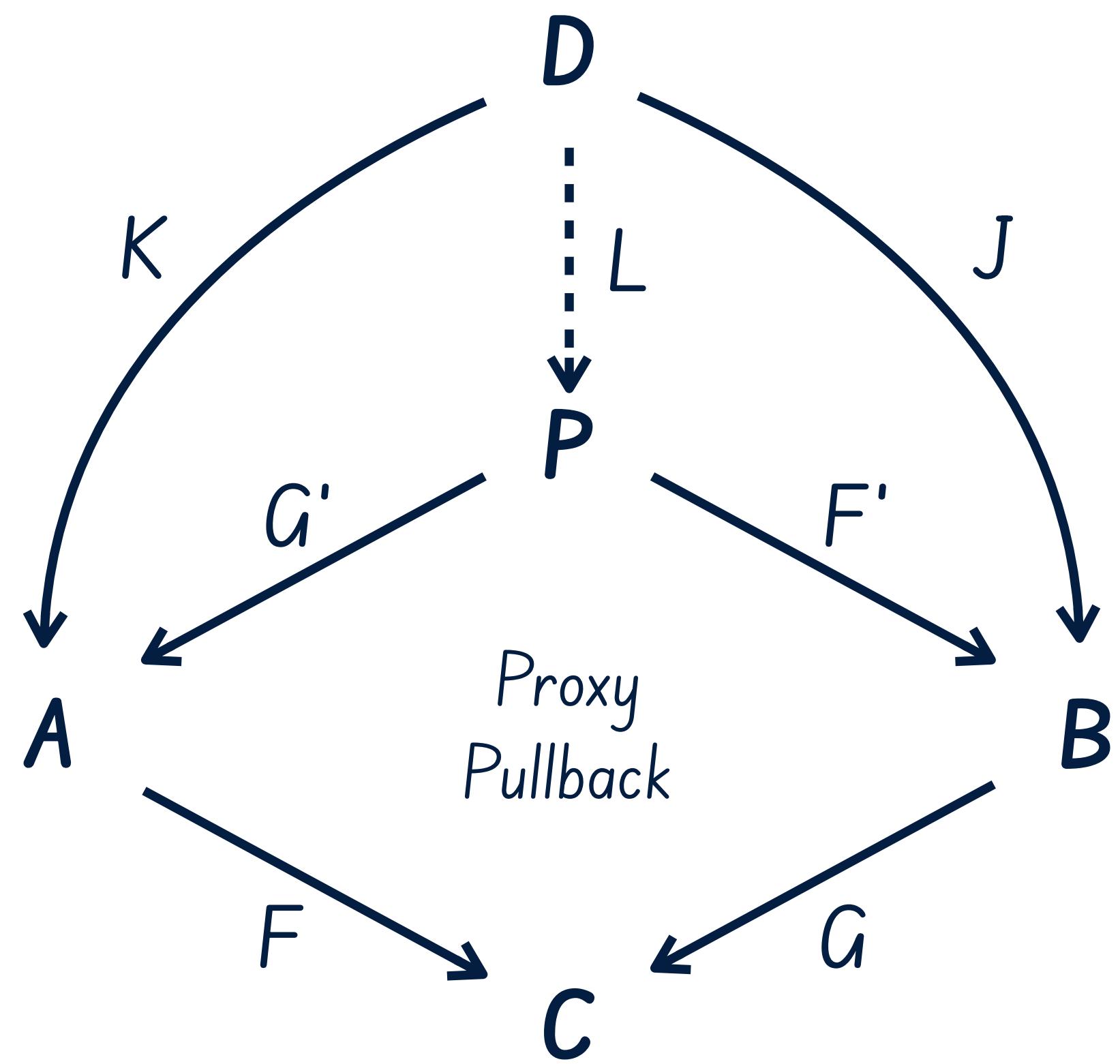


# *proxy pullback* Span composition by ~~pullback~~?



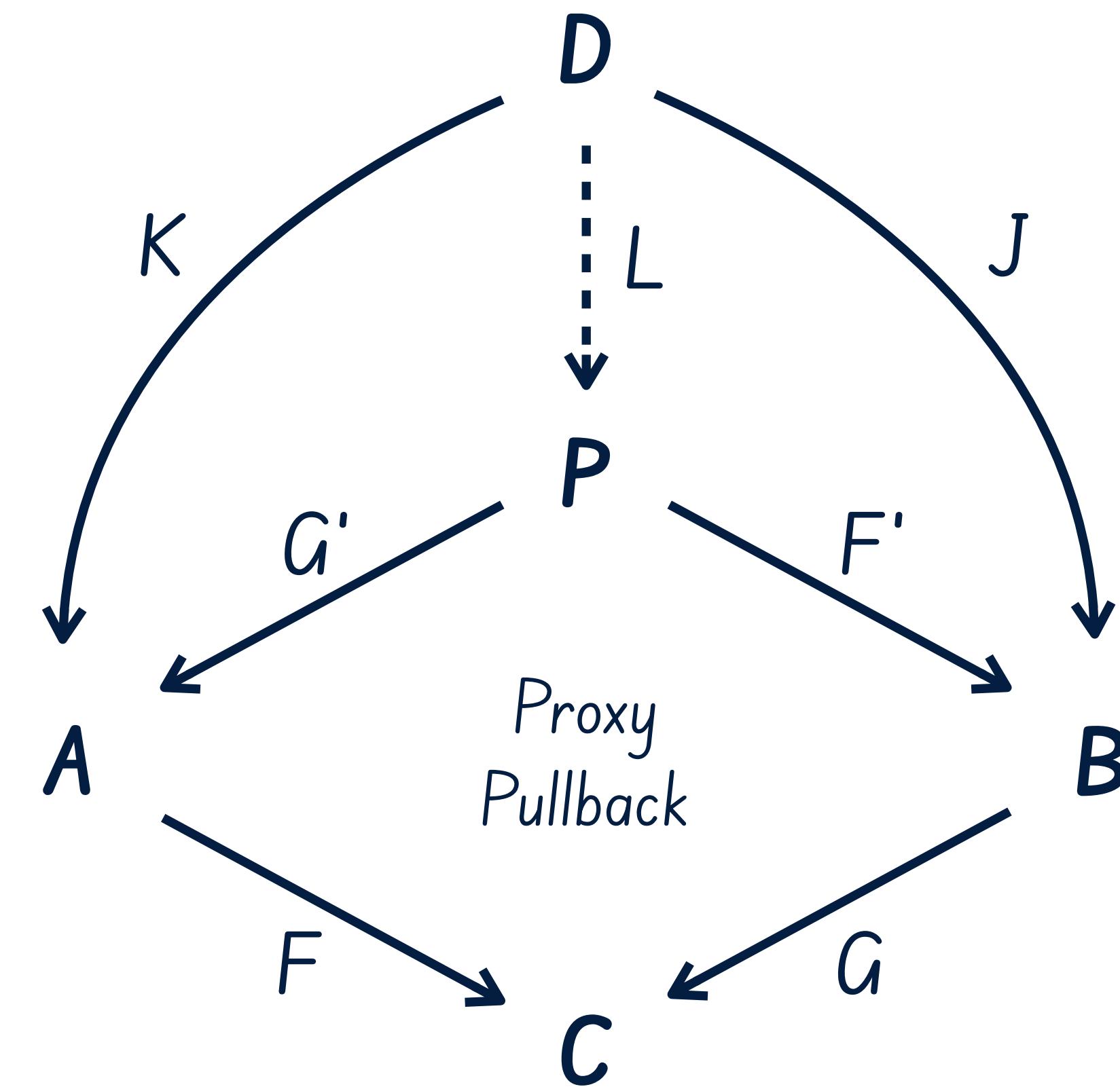






# Necessary conditions

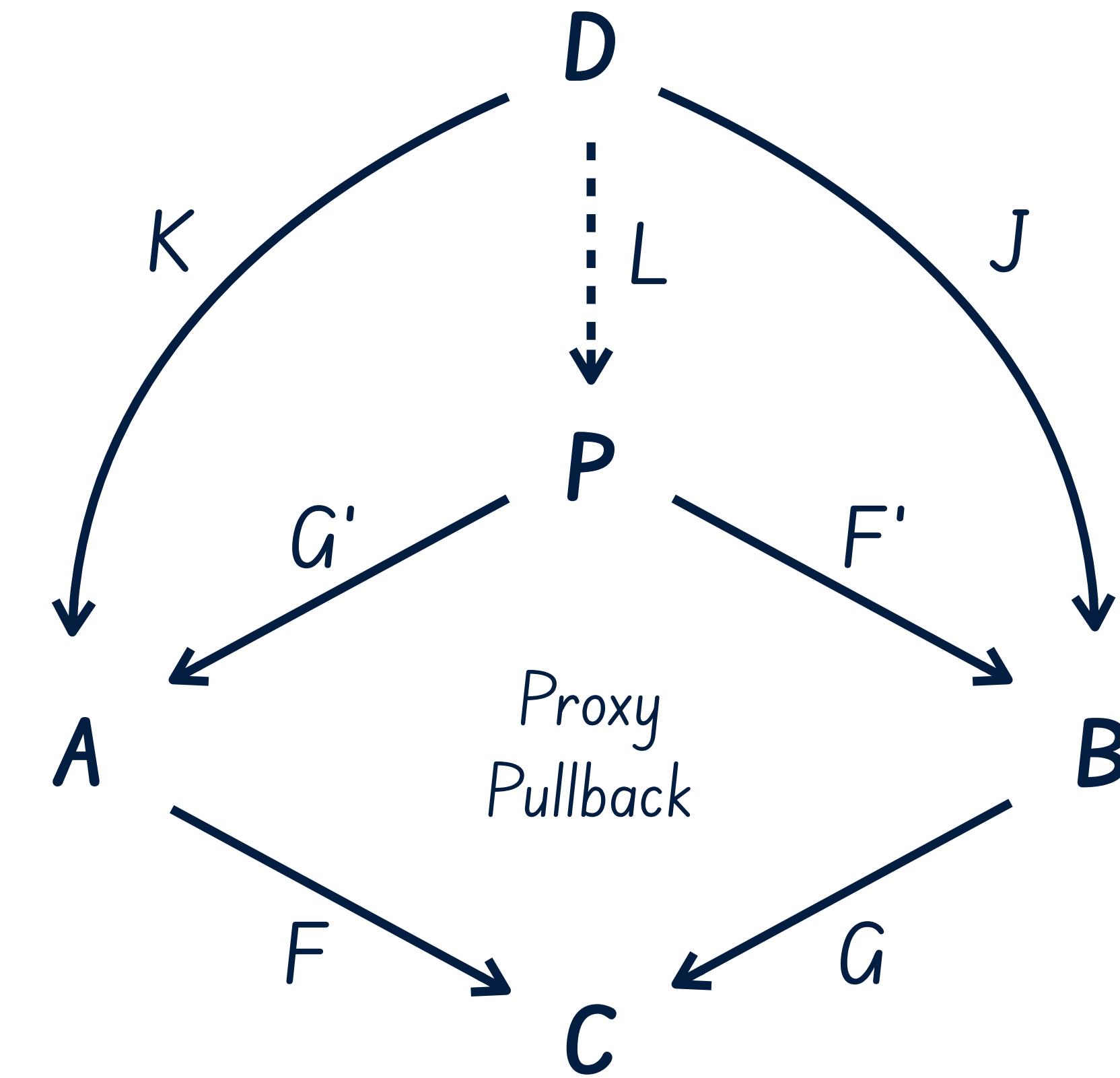
If  $L$  exists then



# Necessary conditions

If  $L$  exists then

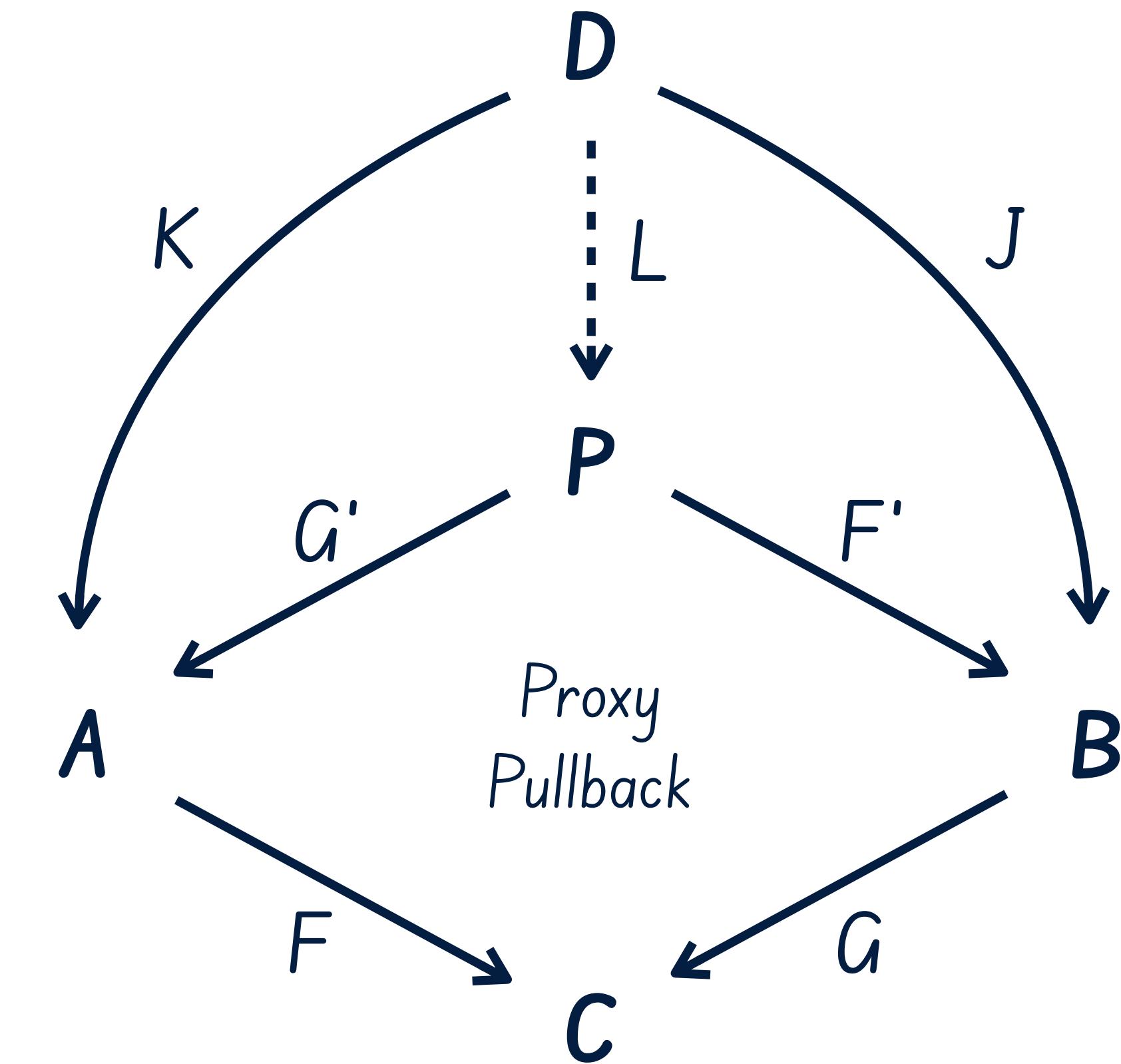
- I.  $(K, J)$  is *compatible* with  $(F, G)$



# Necessary conditions

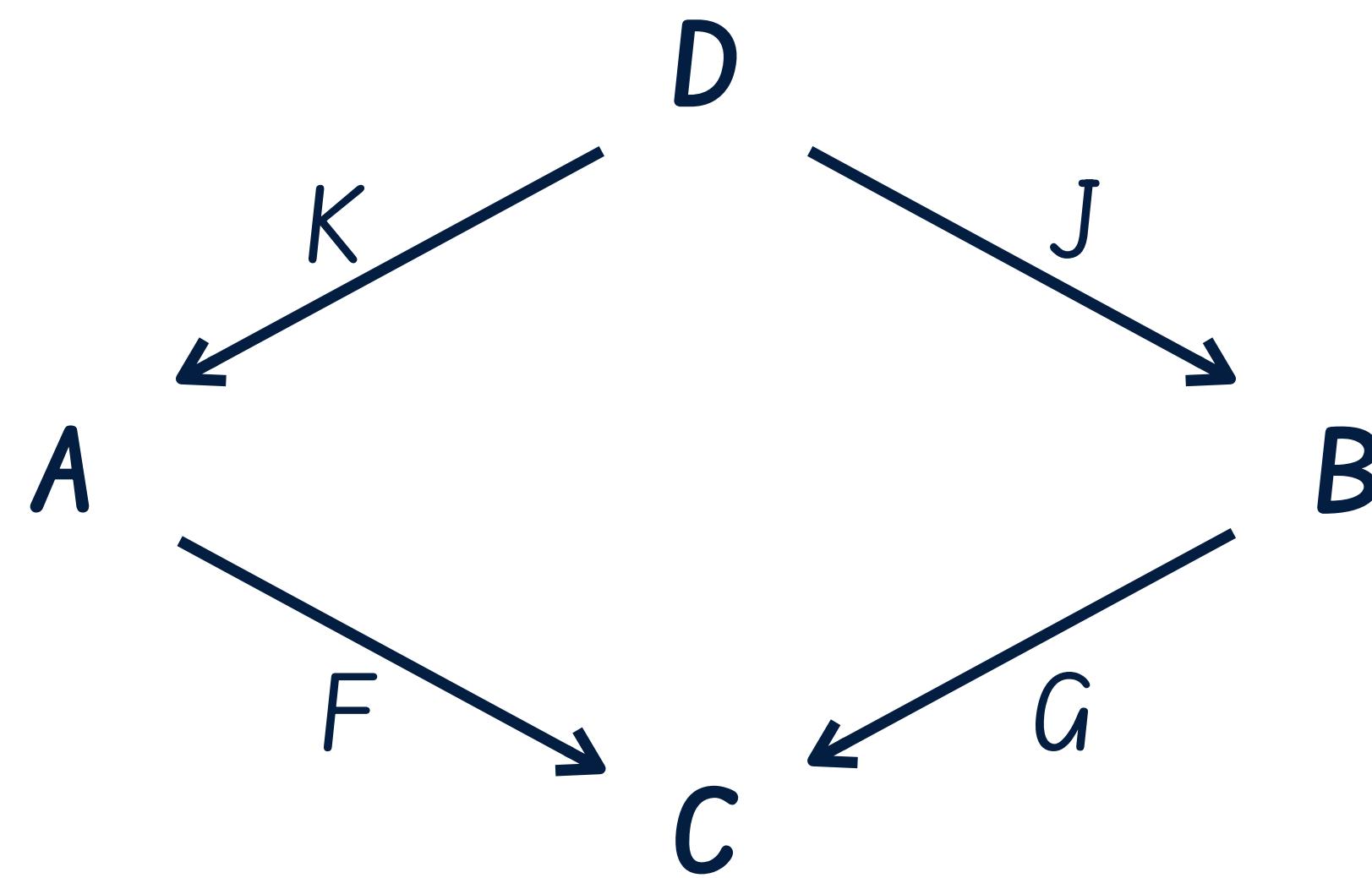
If  $L$  exists then

1.  $(K, J)$  is *compatible* with  $(F, G)$
2.  $(K, J)$  is *independent*

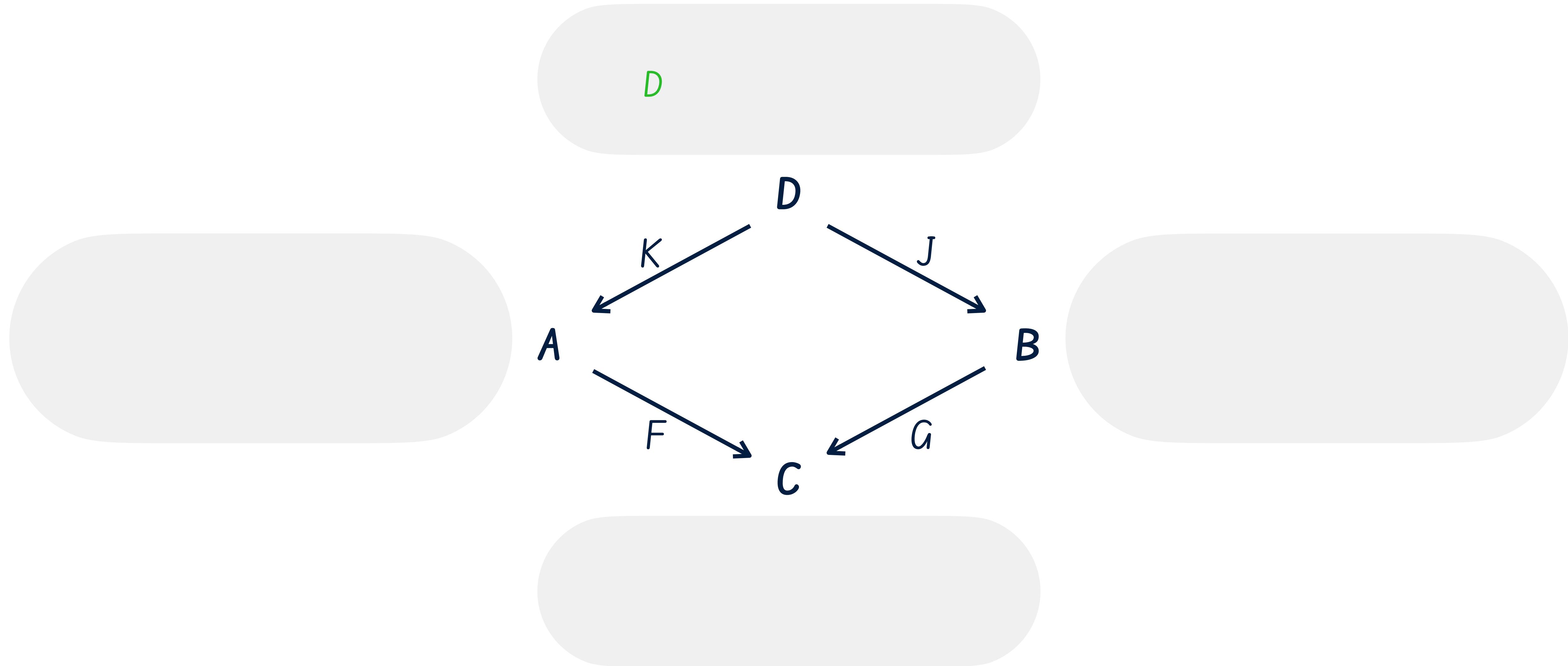


# *Compatibility*

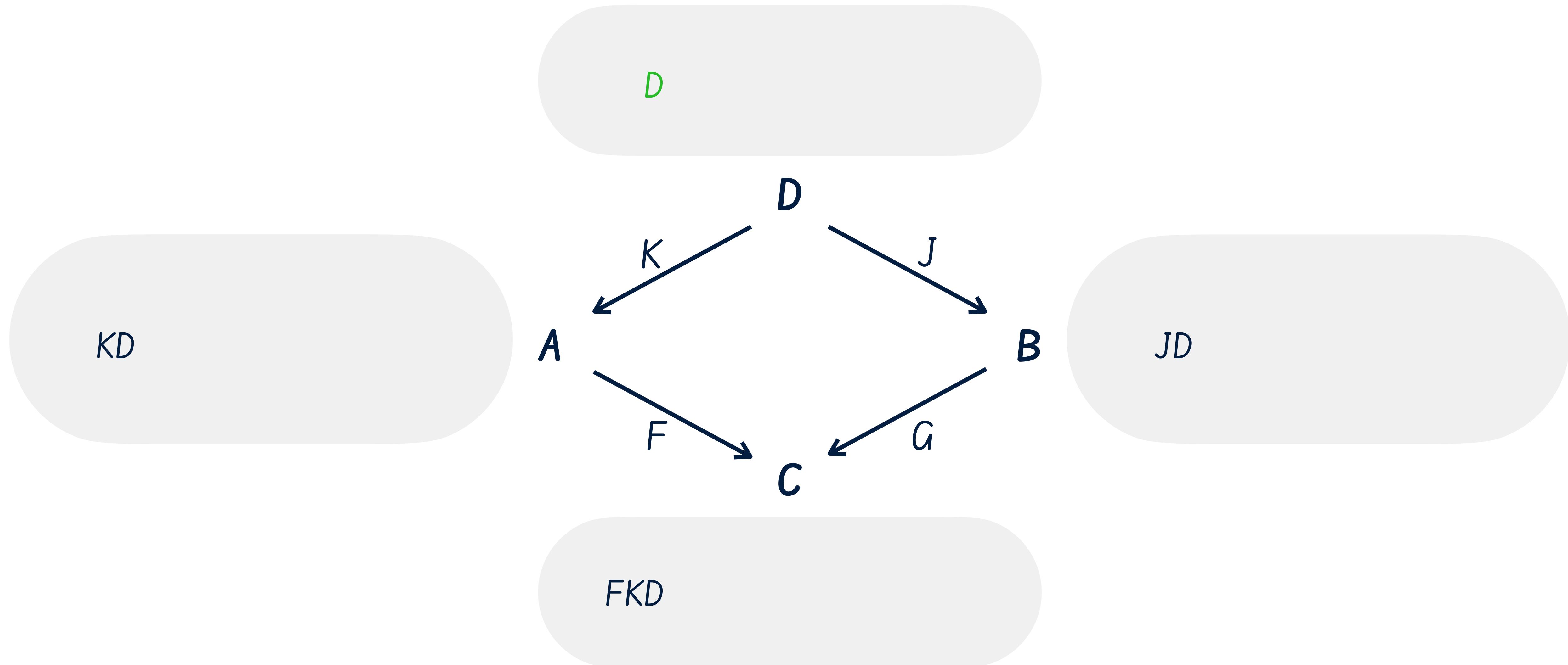
# Compatibility



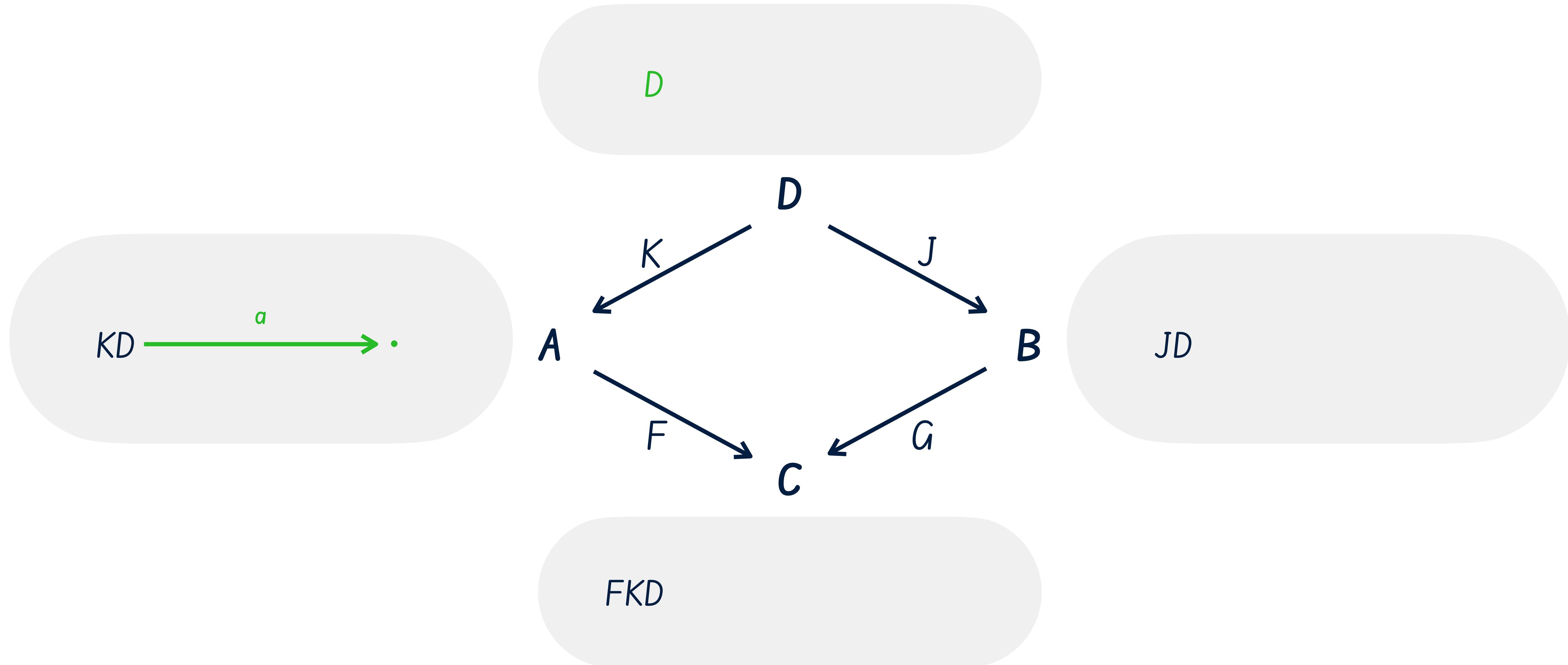
# Compatibility



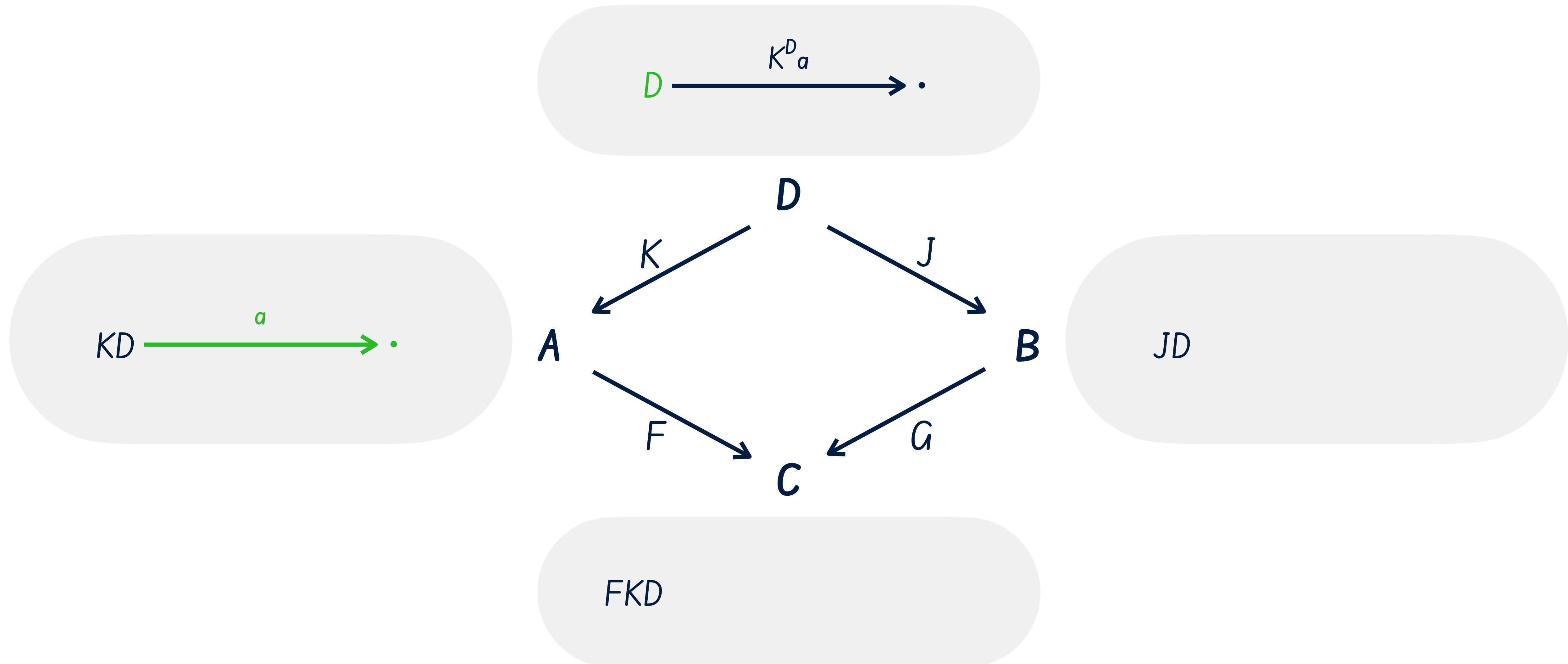
# Compatibility



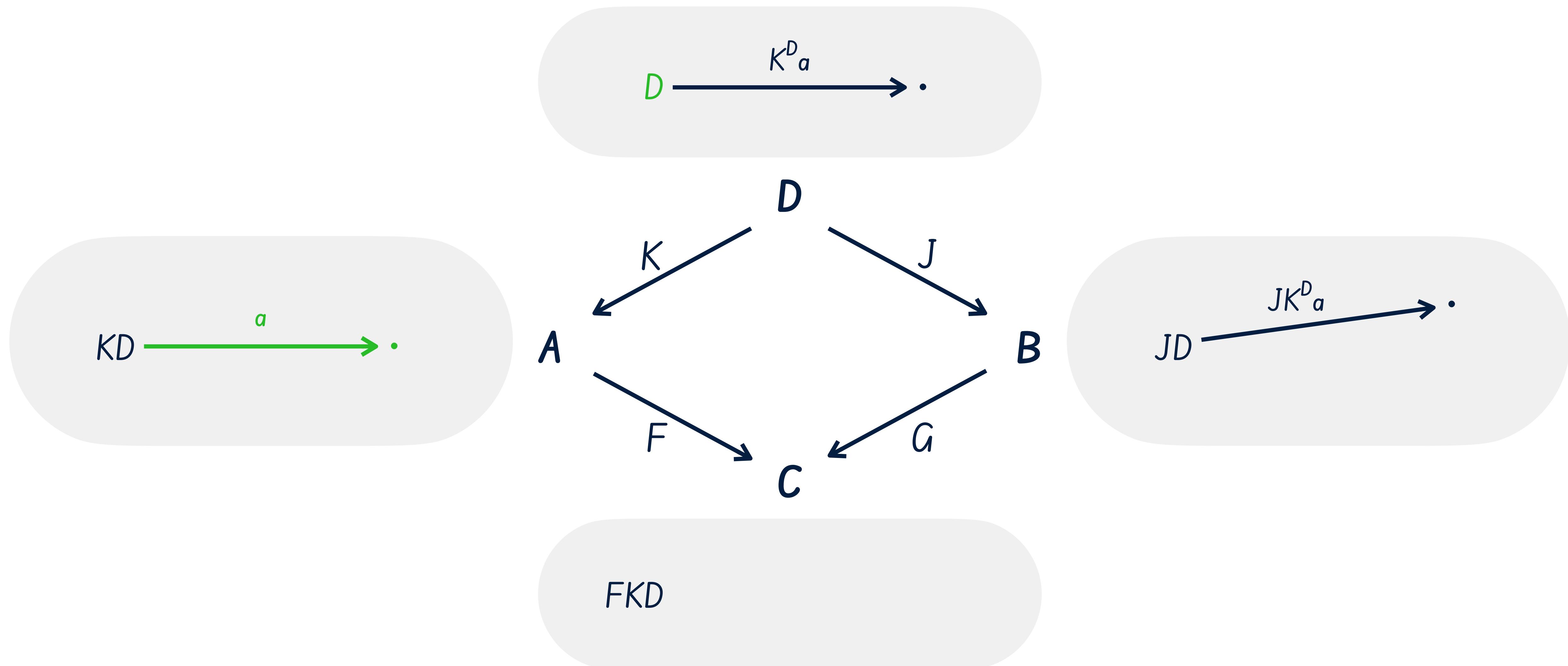
# Compatibility



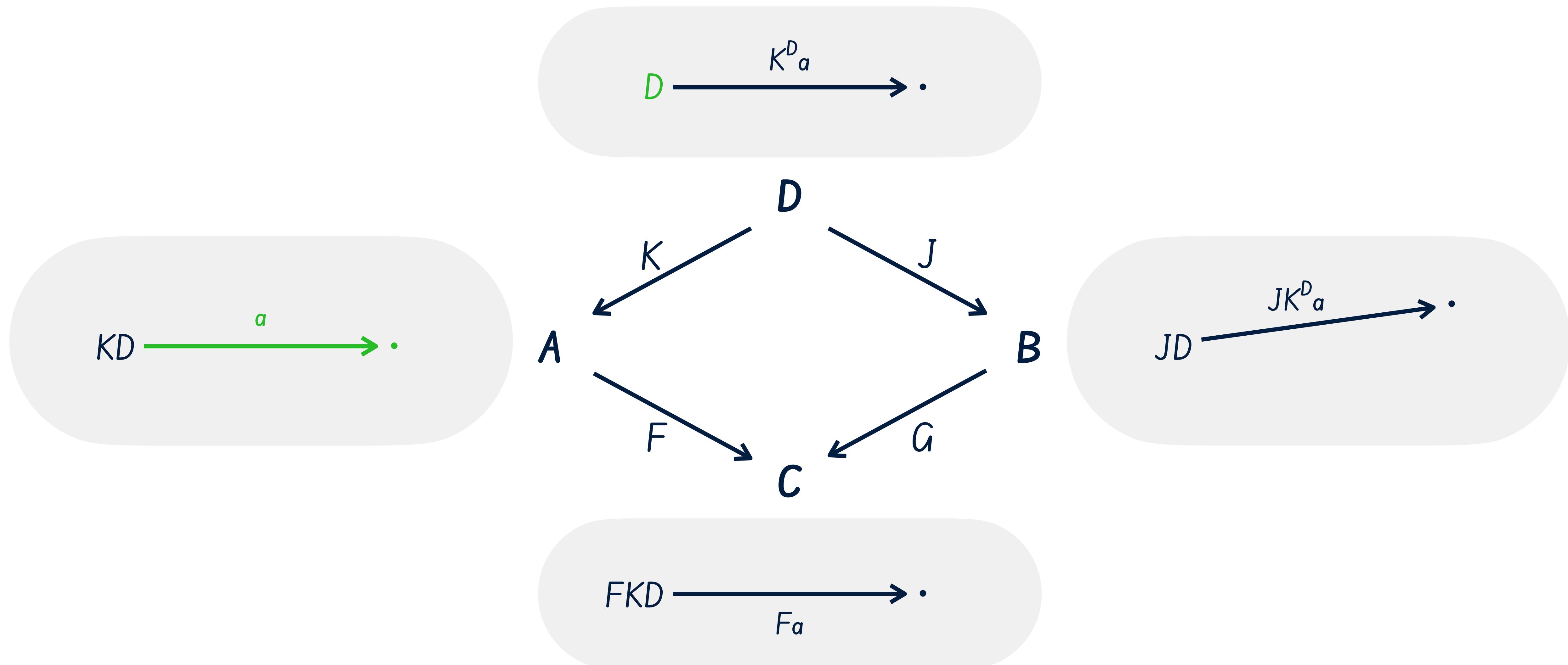
# Compatibility



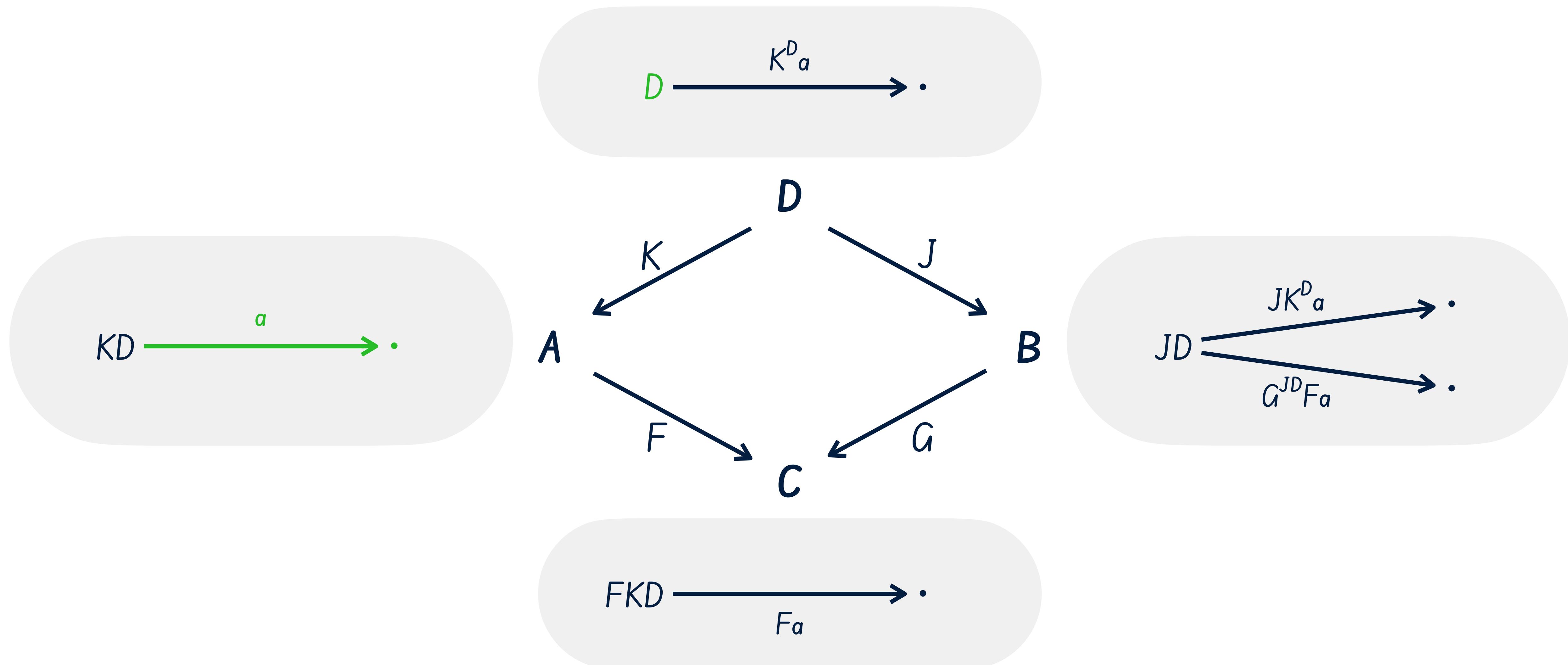
# Compatibility



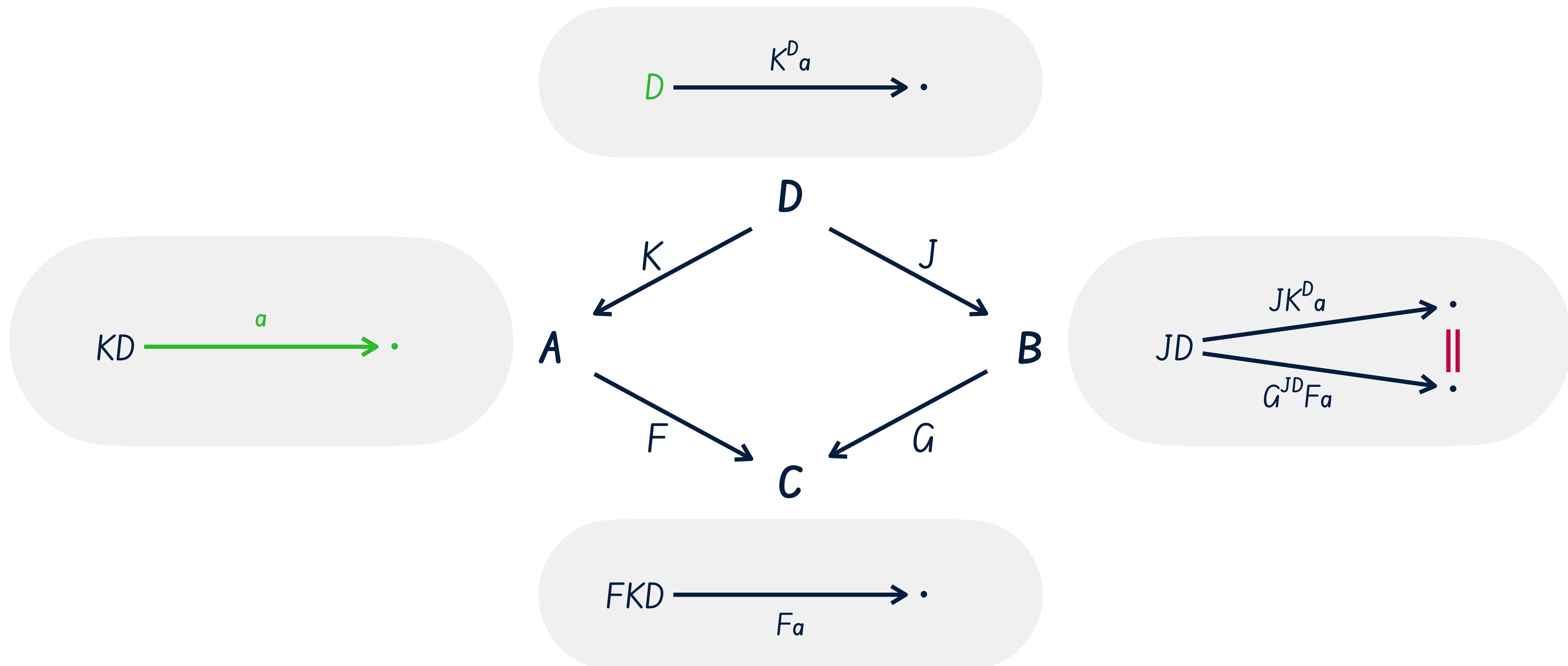
# Compatibility



# Compatibility

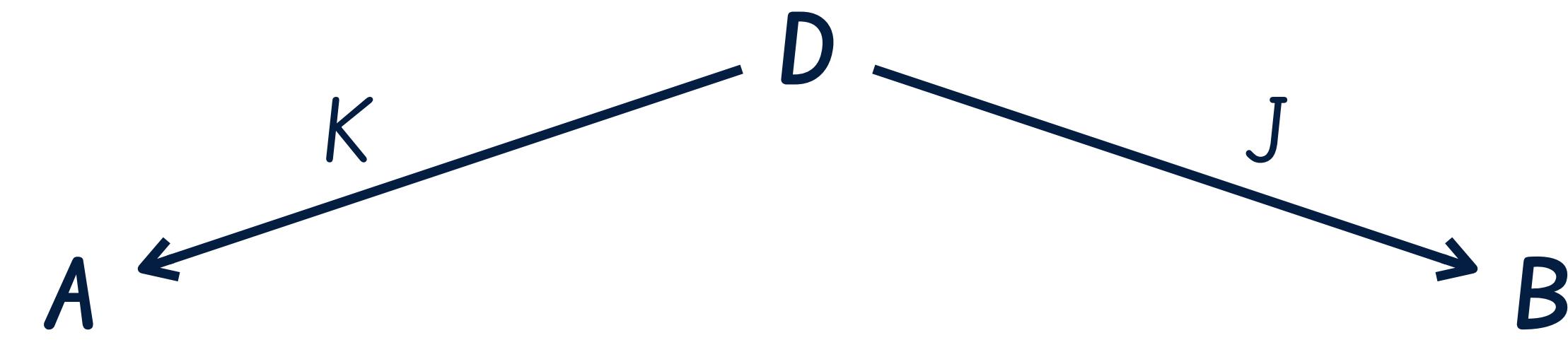


# Compatibility

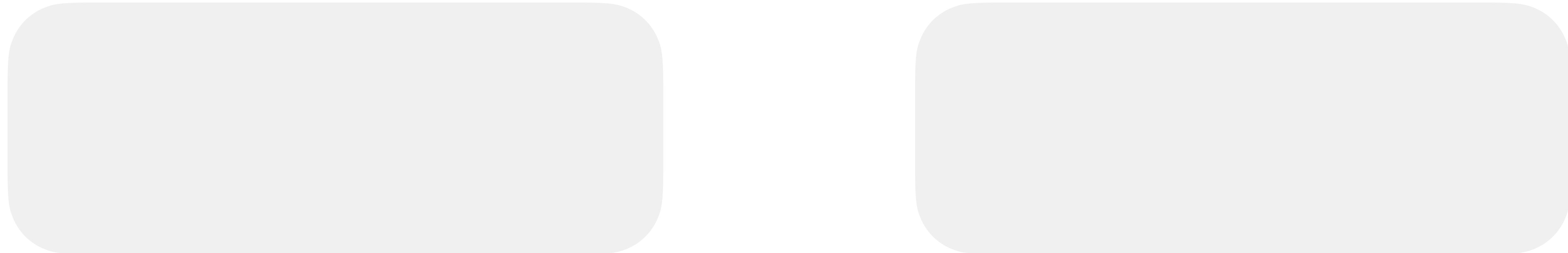
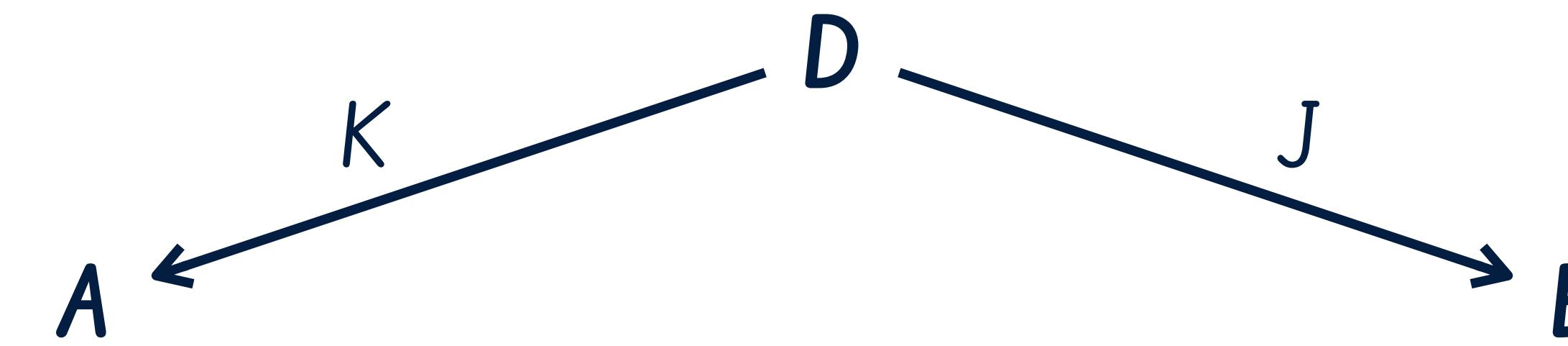
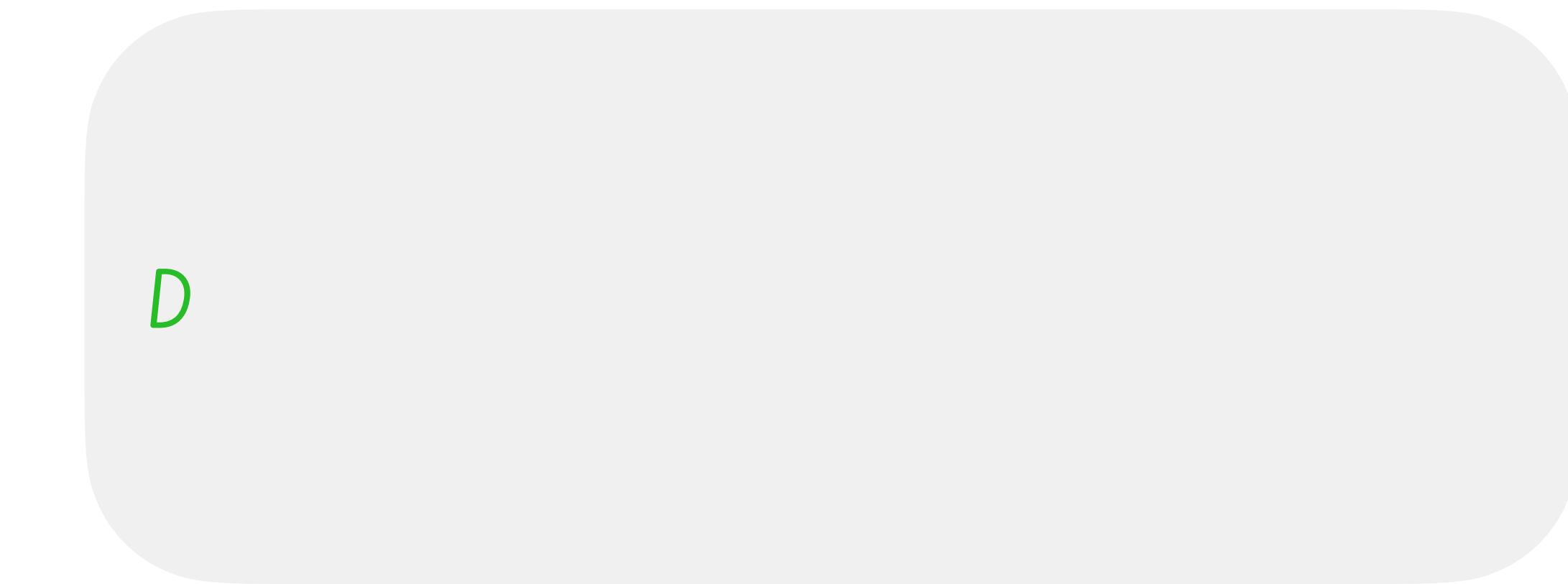


*Independence*

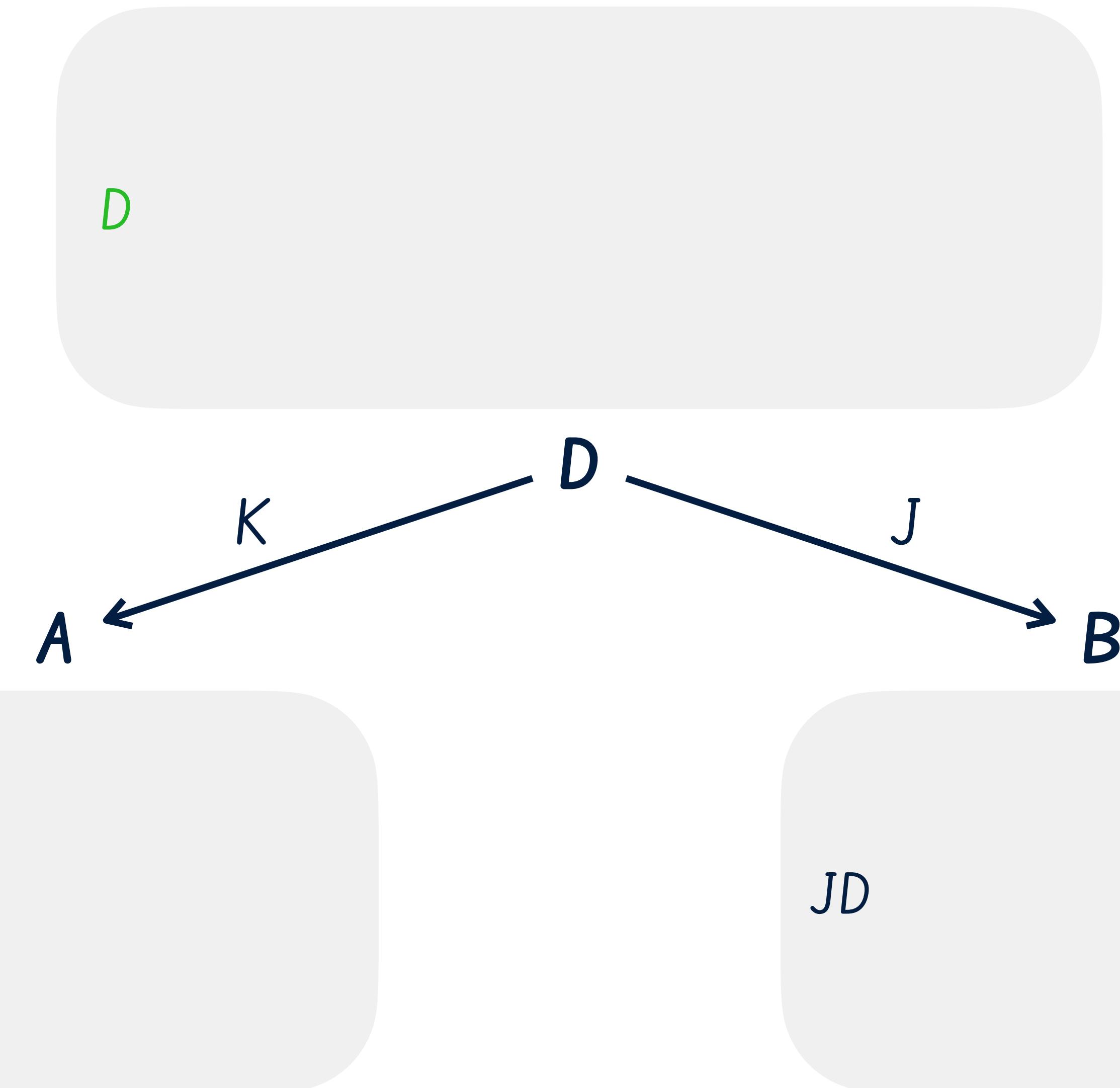
# *Independence*



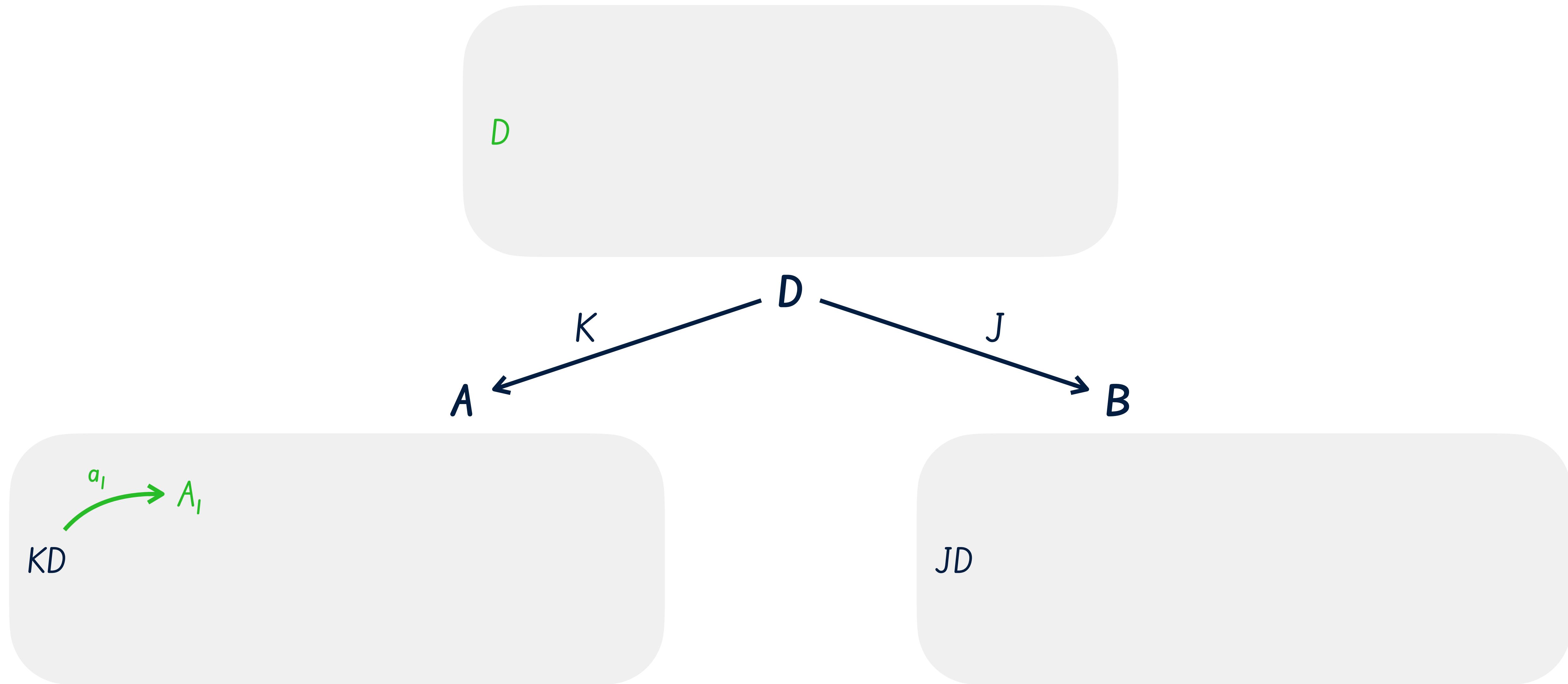
# *Independence*



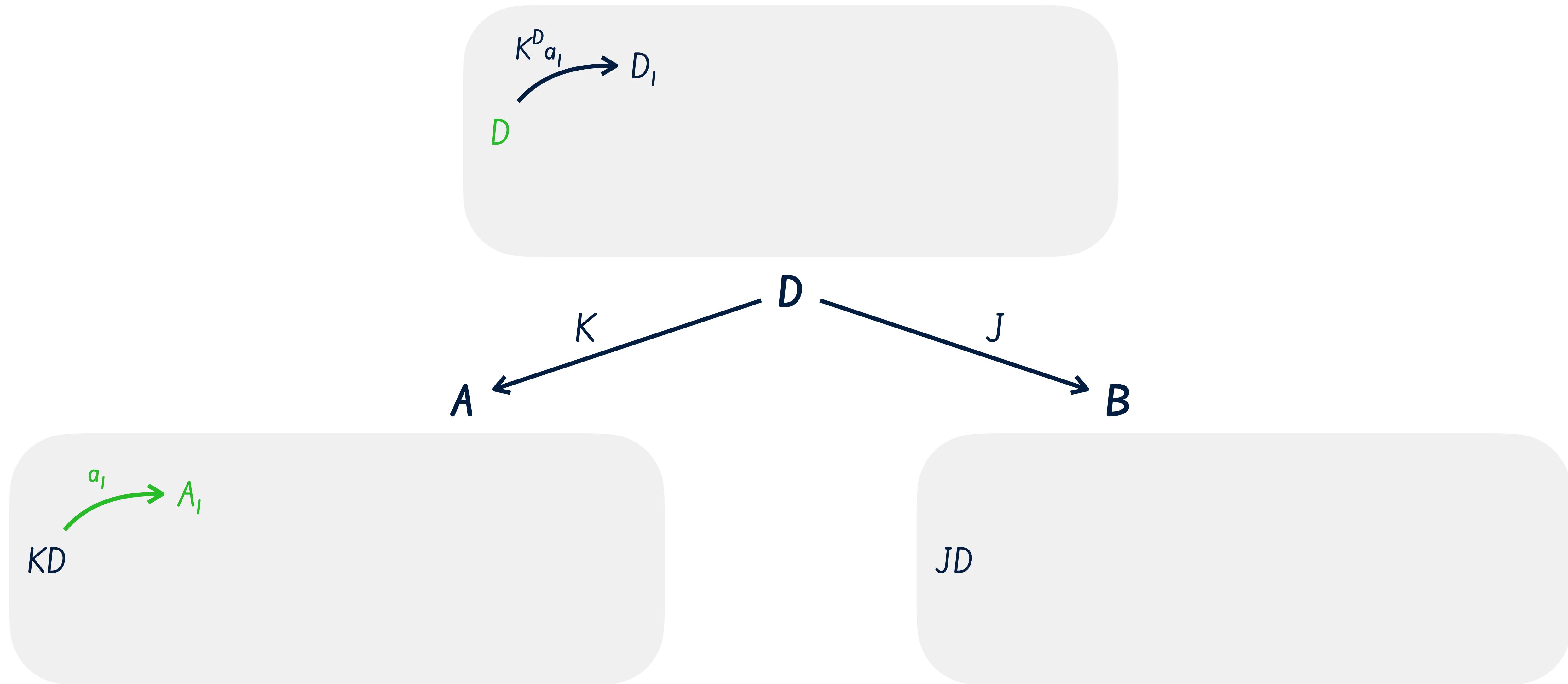
# *Independence*



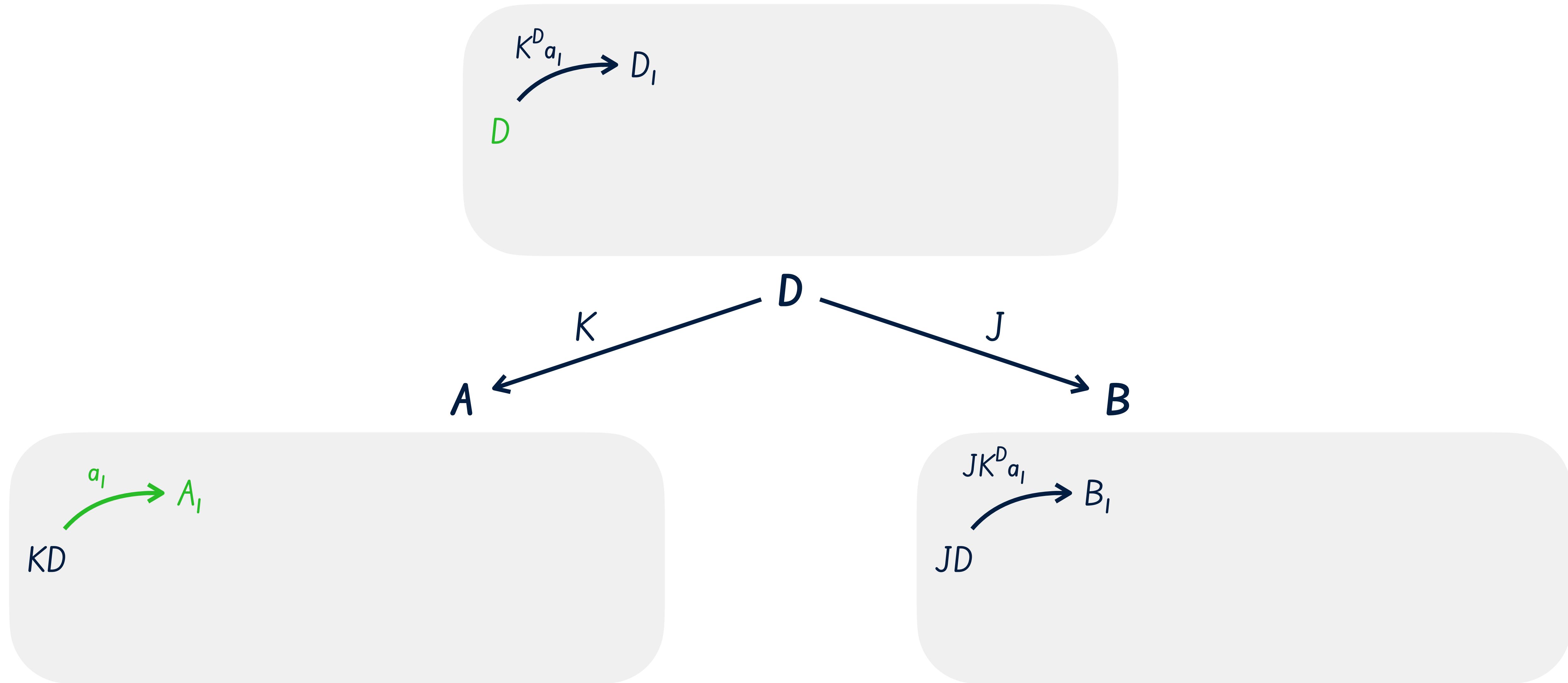
# *Independence*



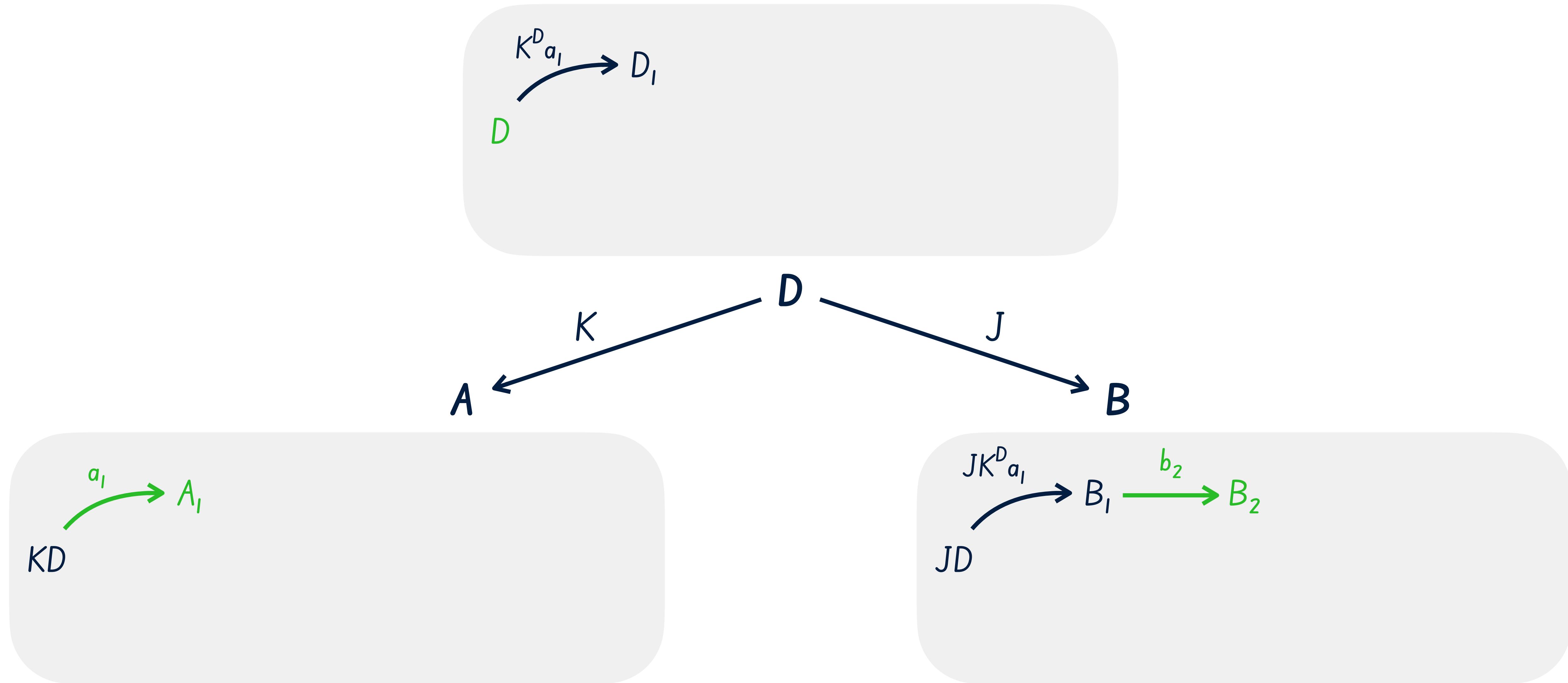
# *Independence*



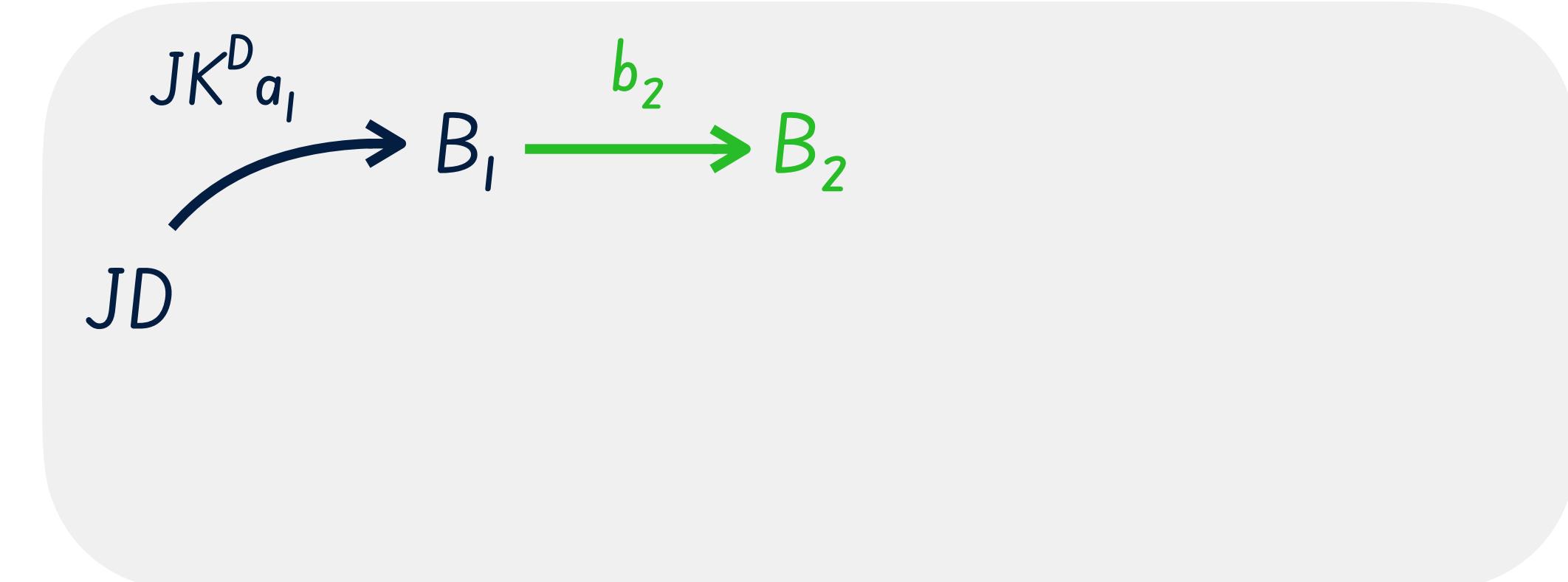
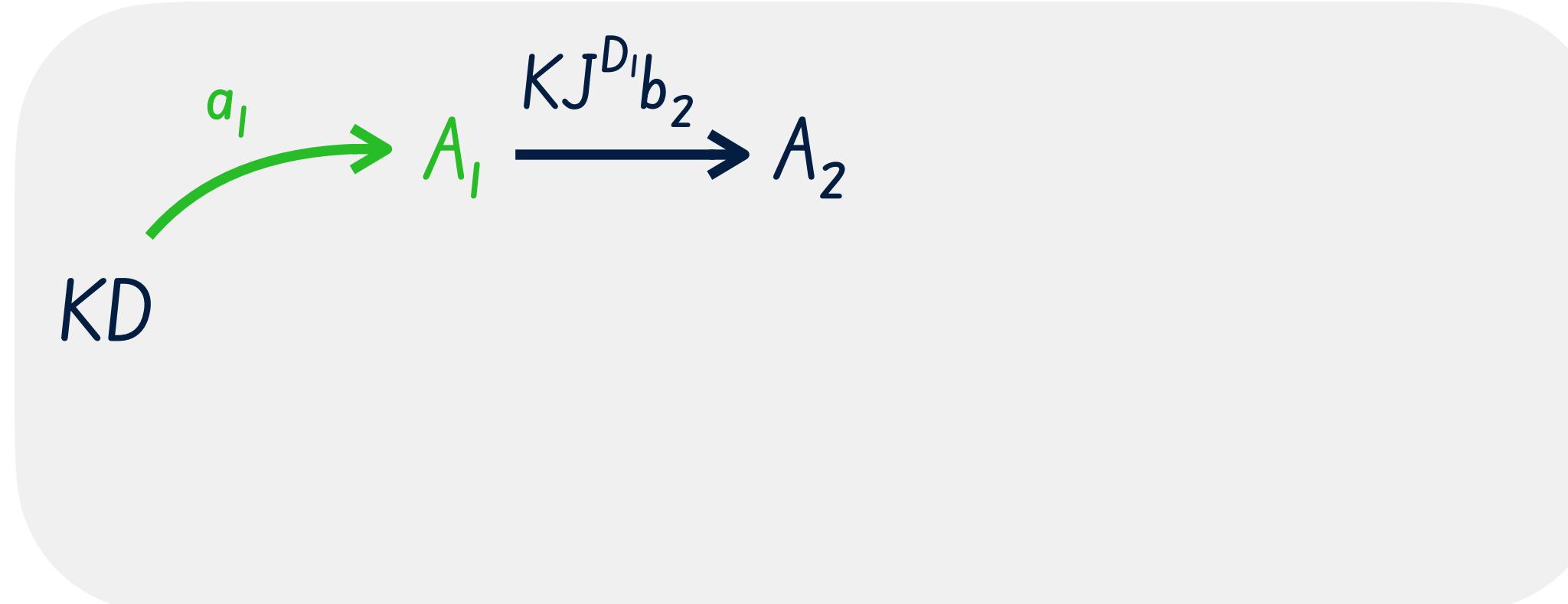
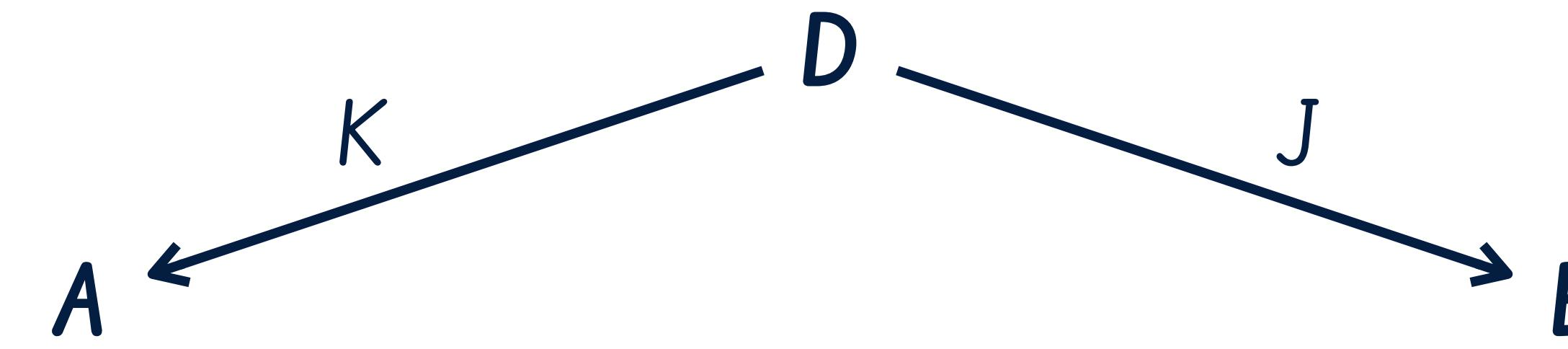
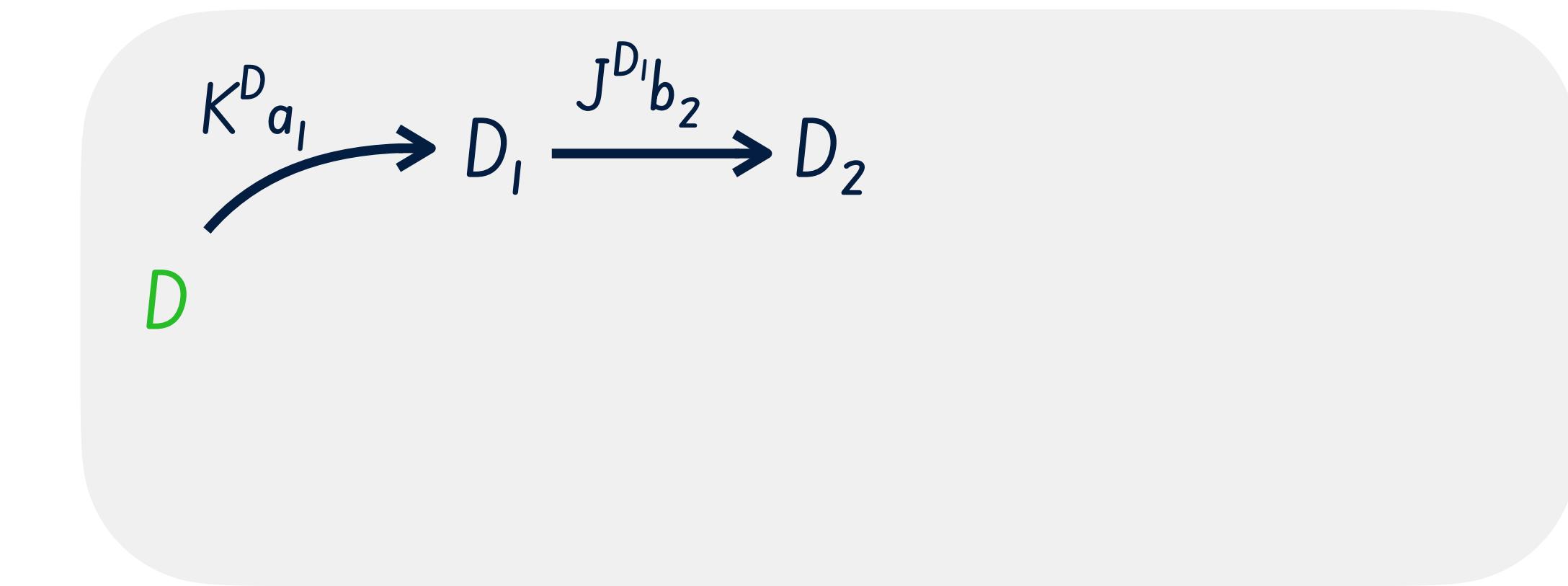
# Independence



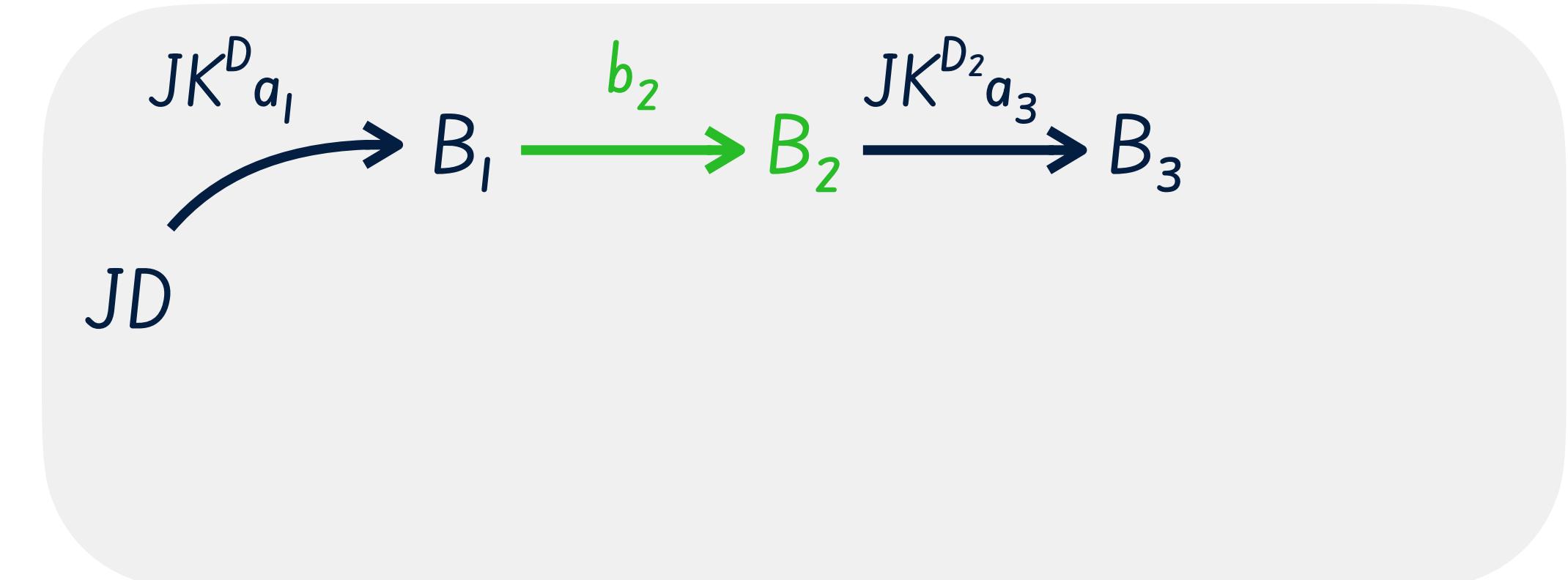
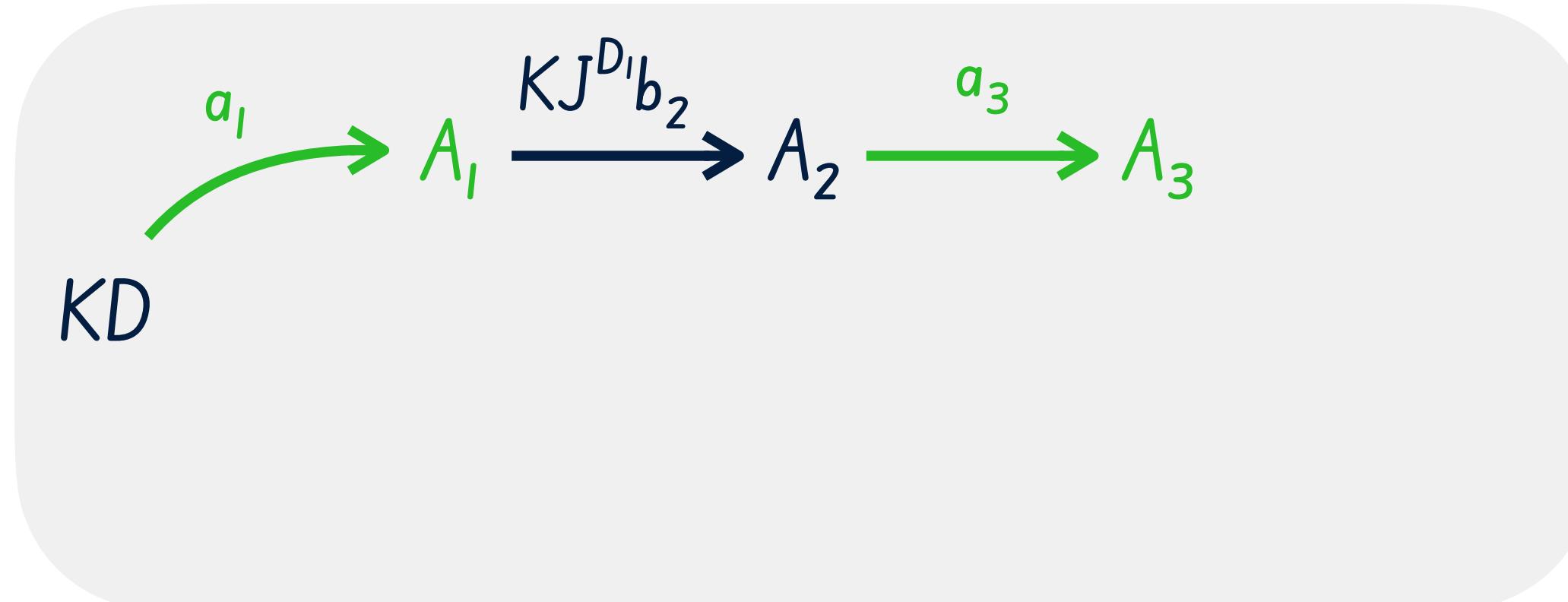
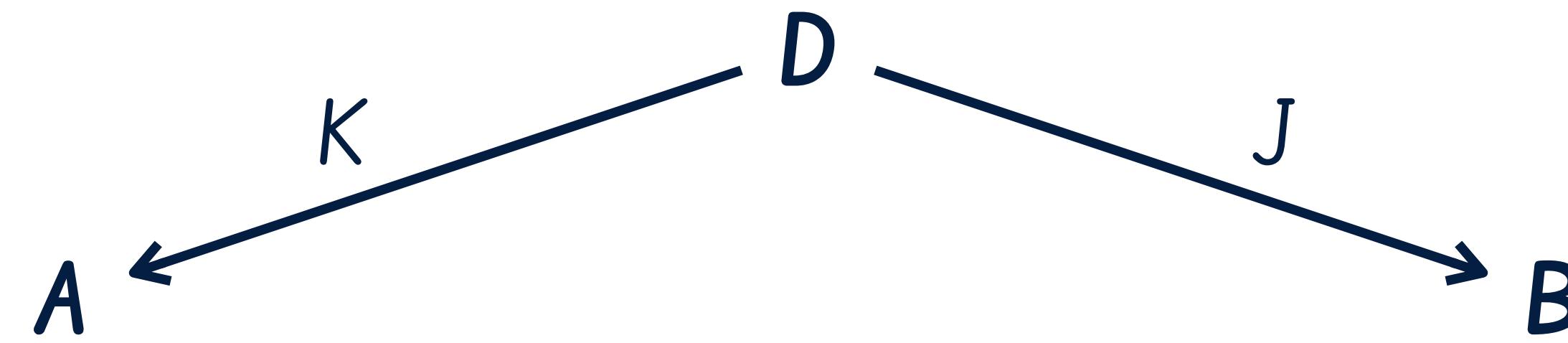
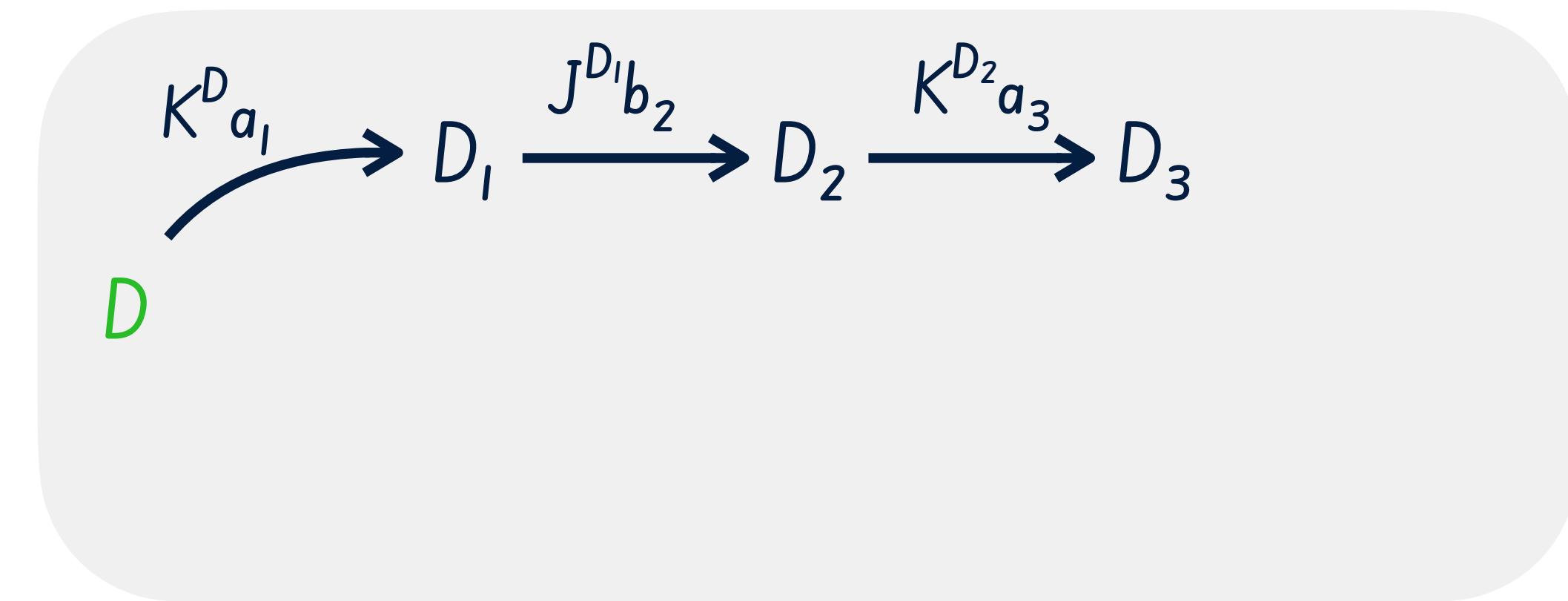
# Independence



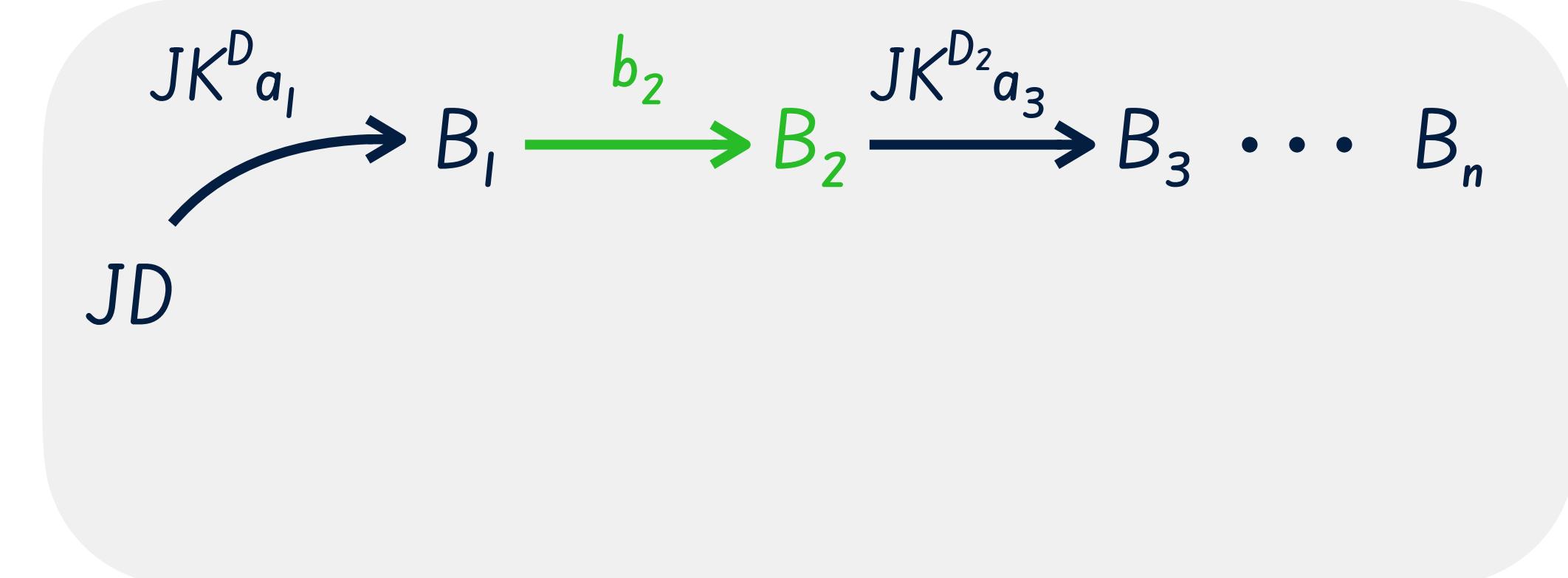
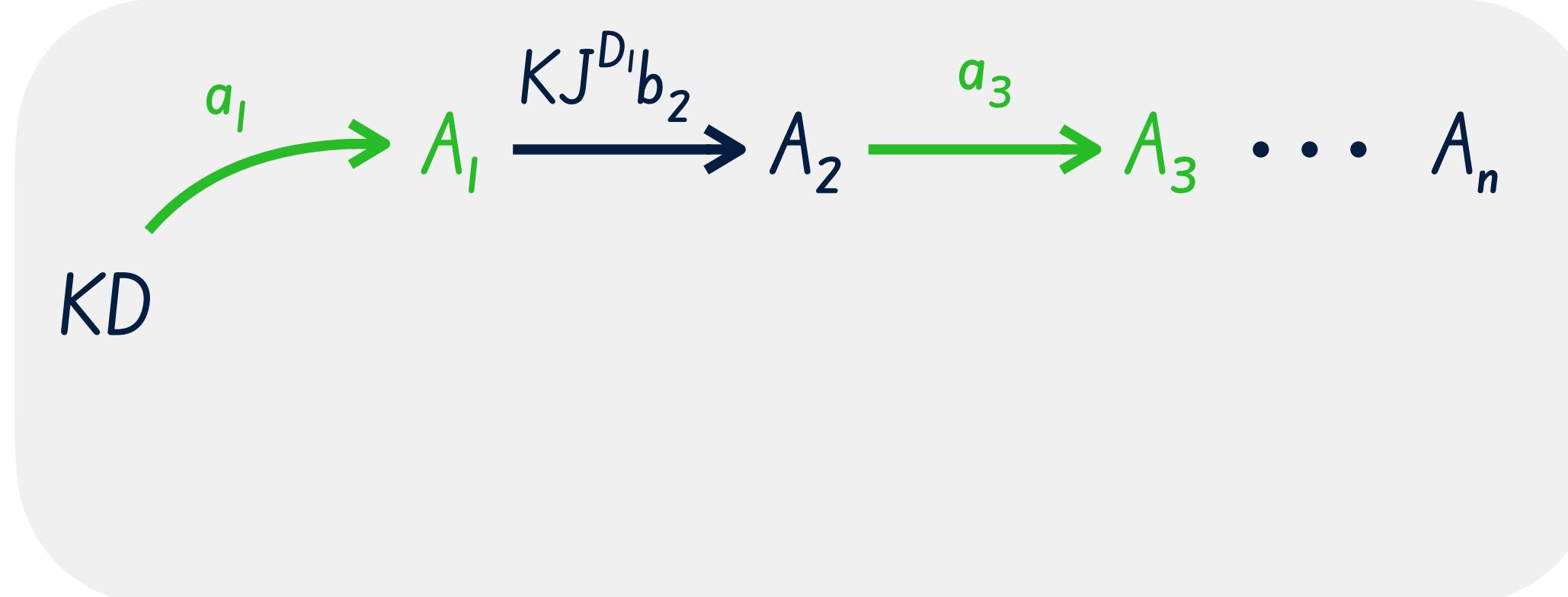
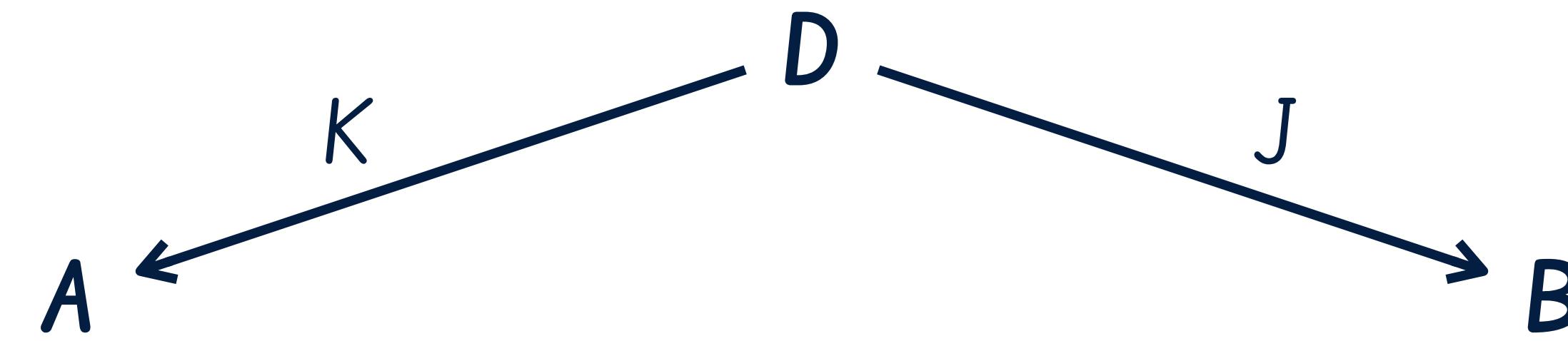
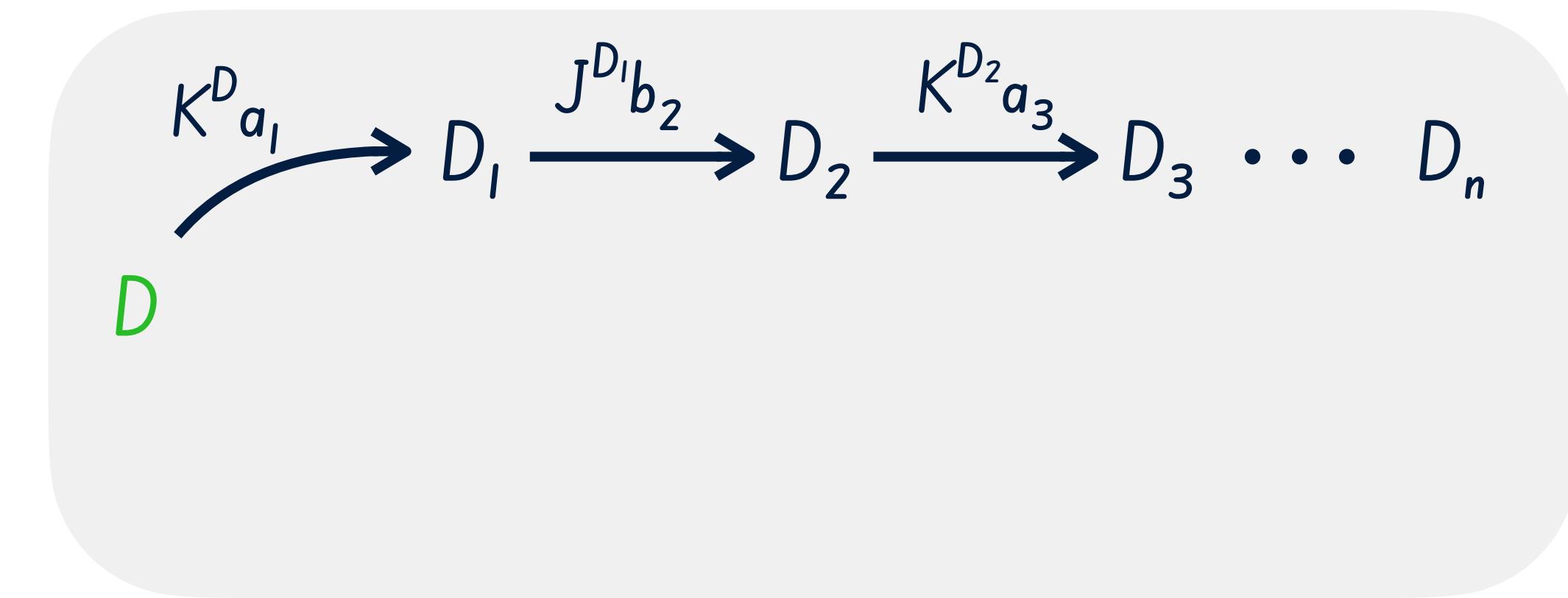
# Independence



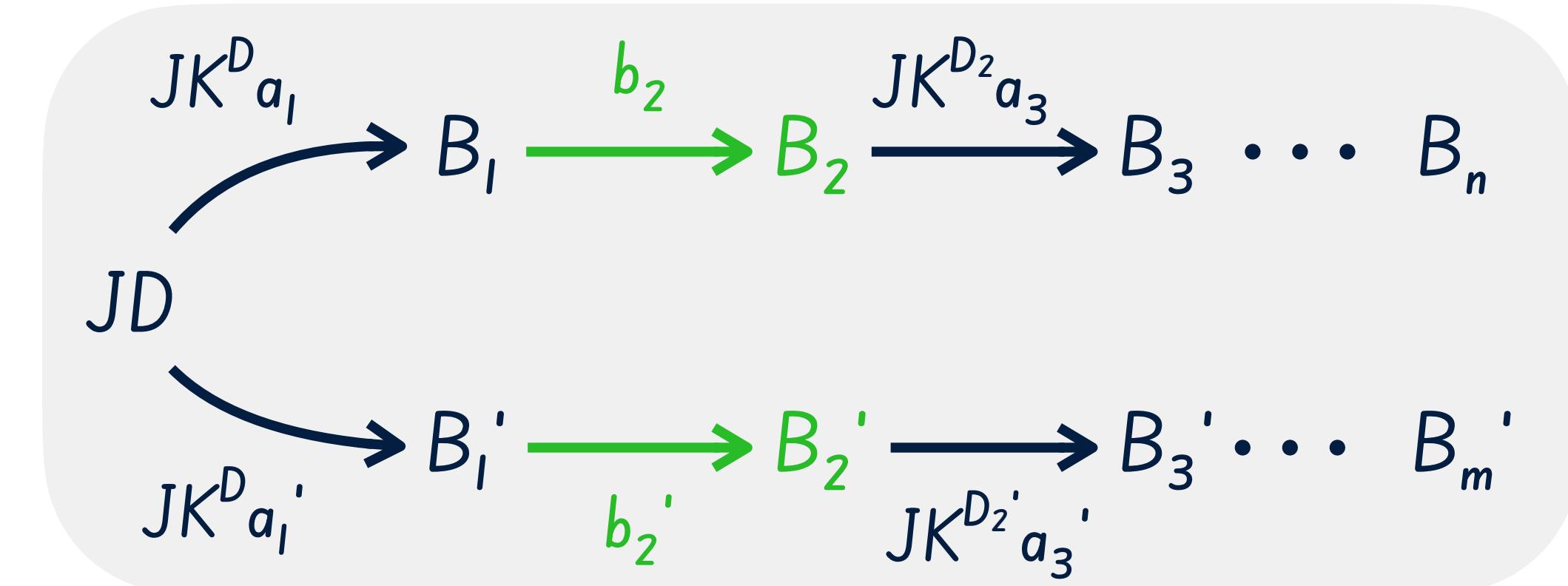
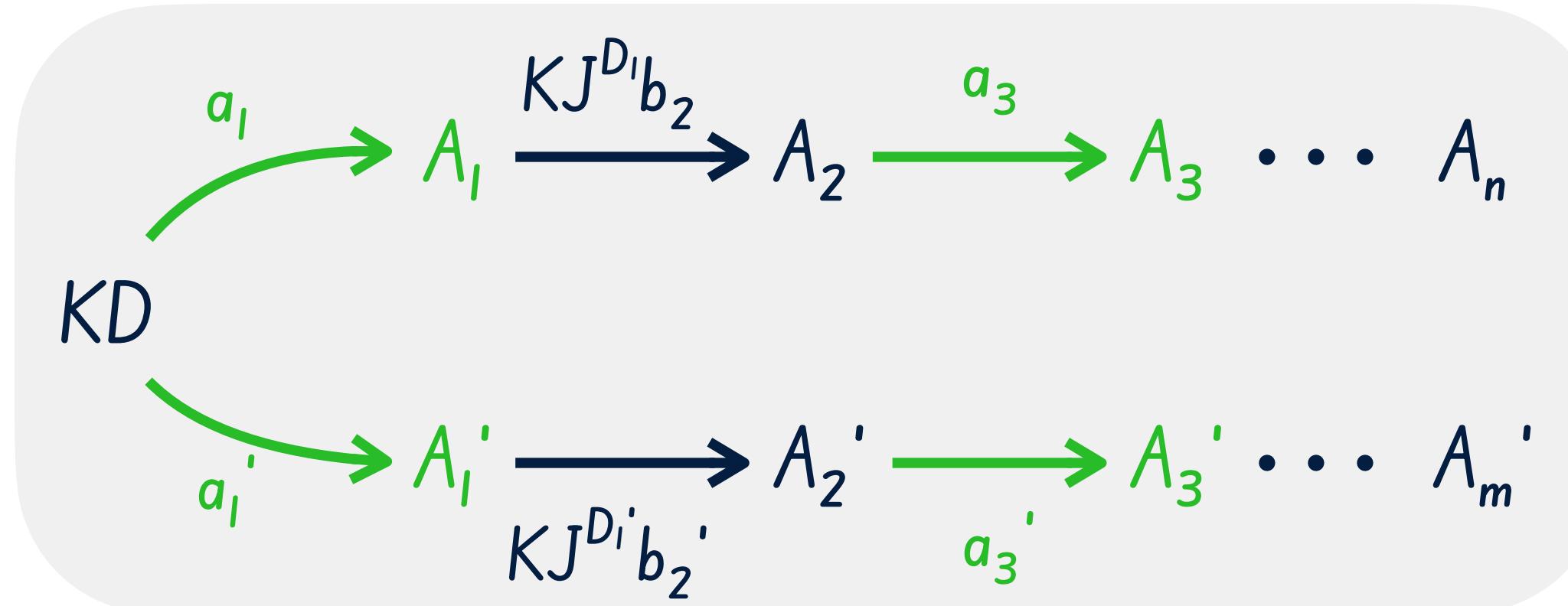
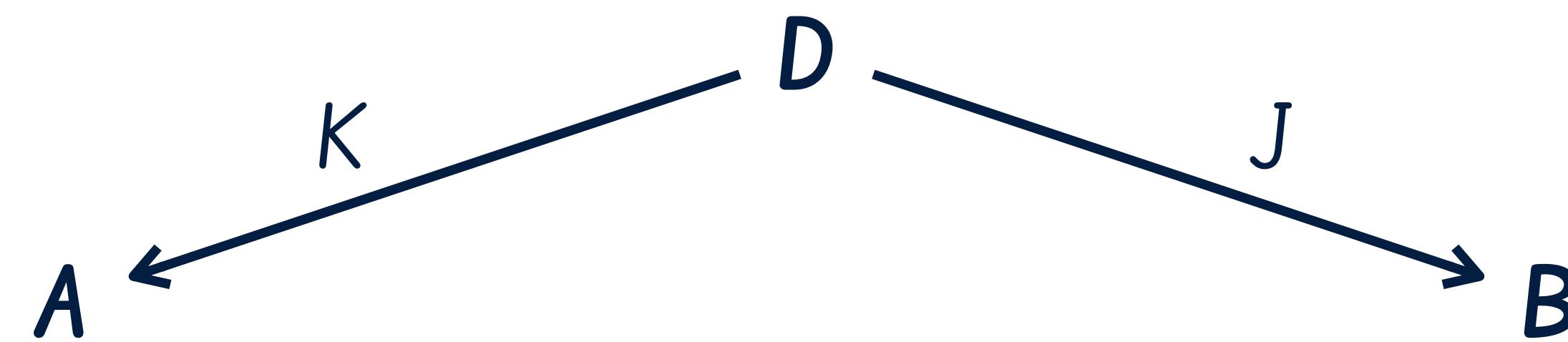
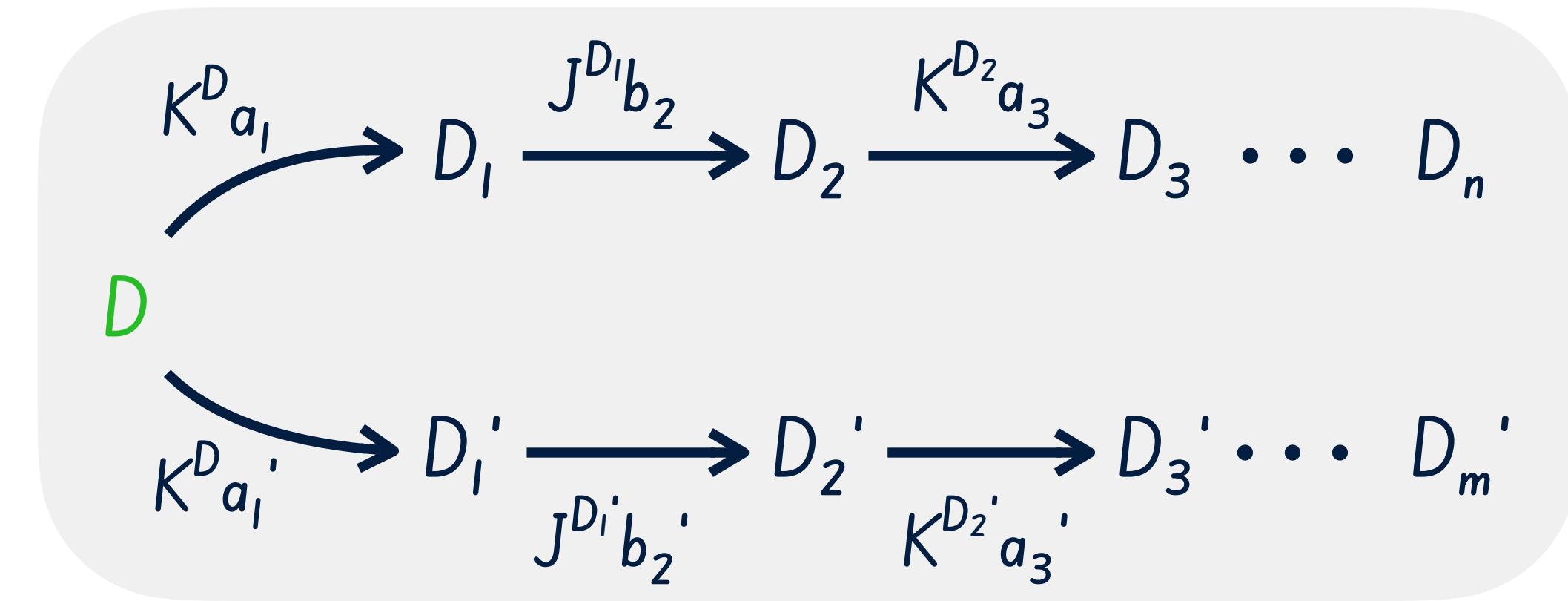
# Independence



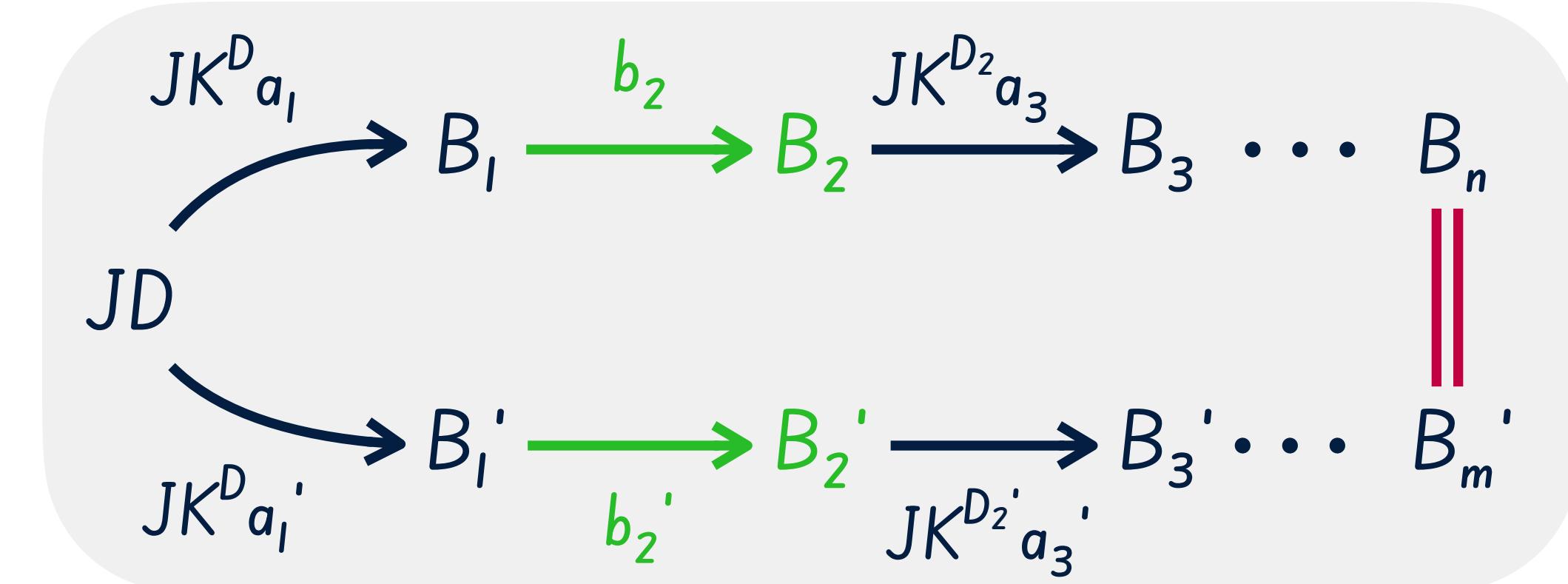
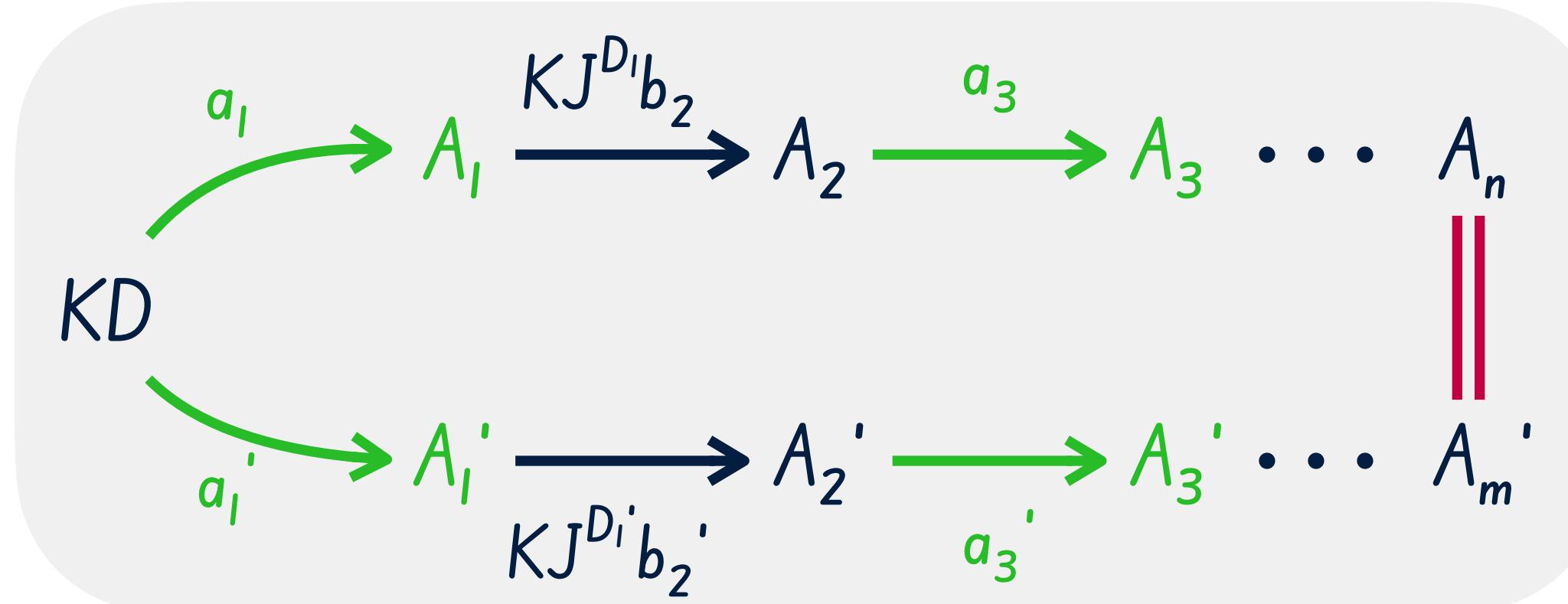
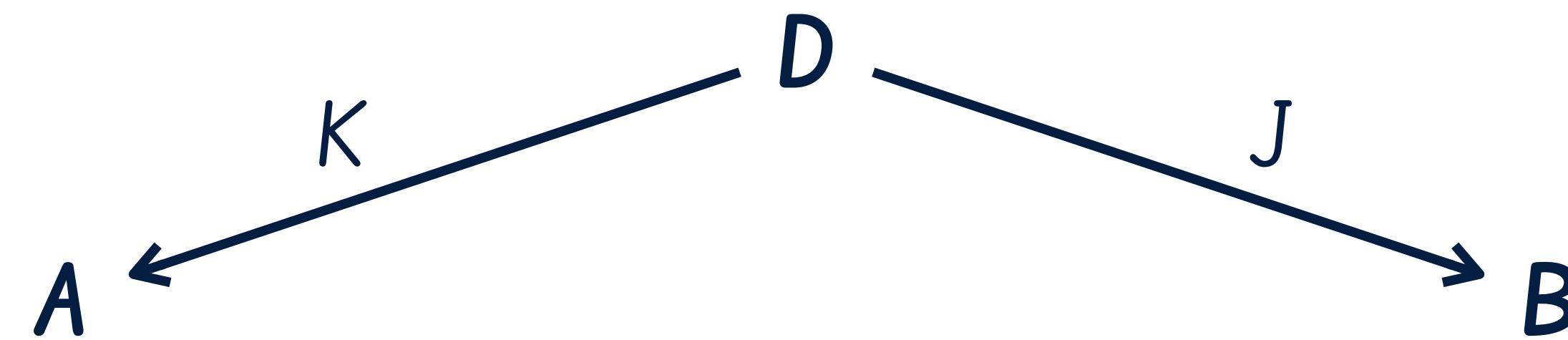
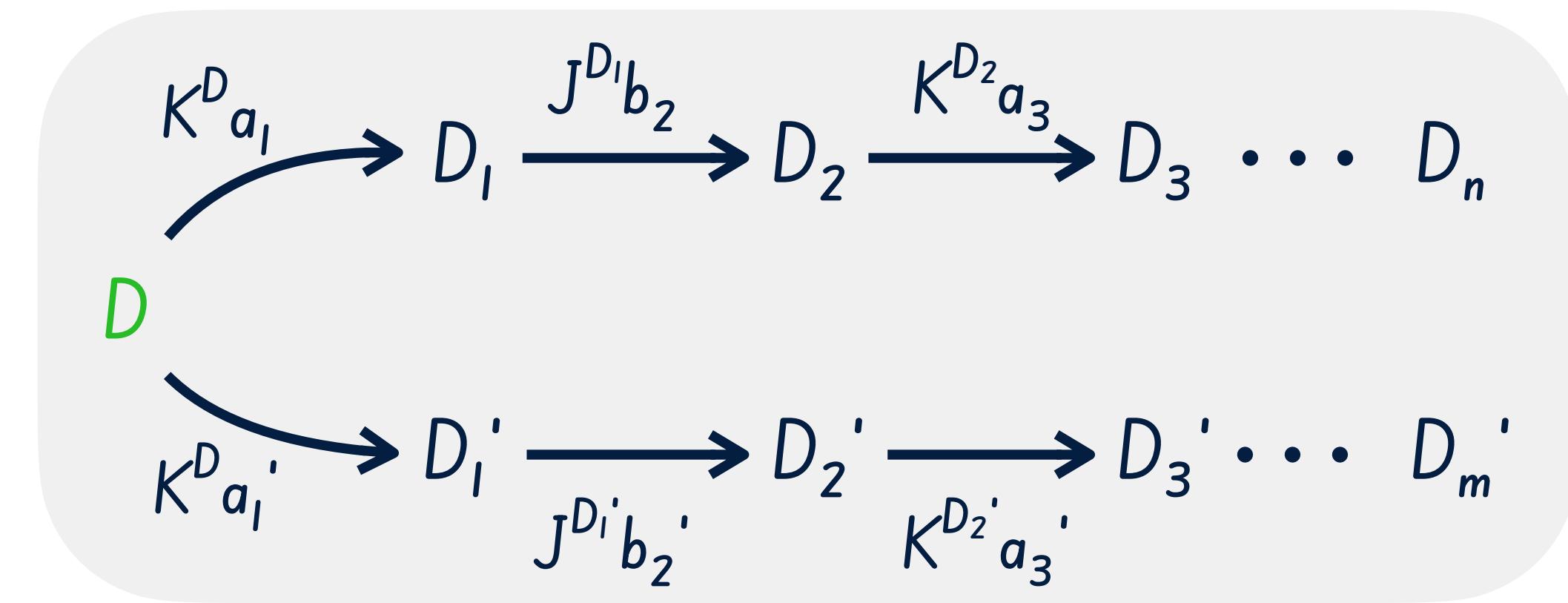
# Independence



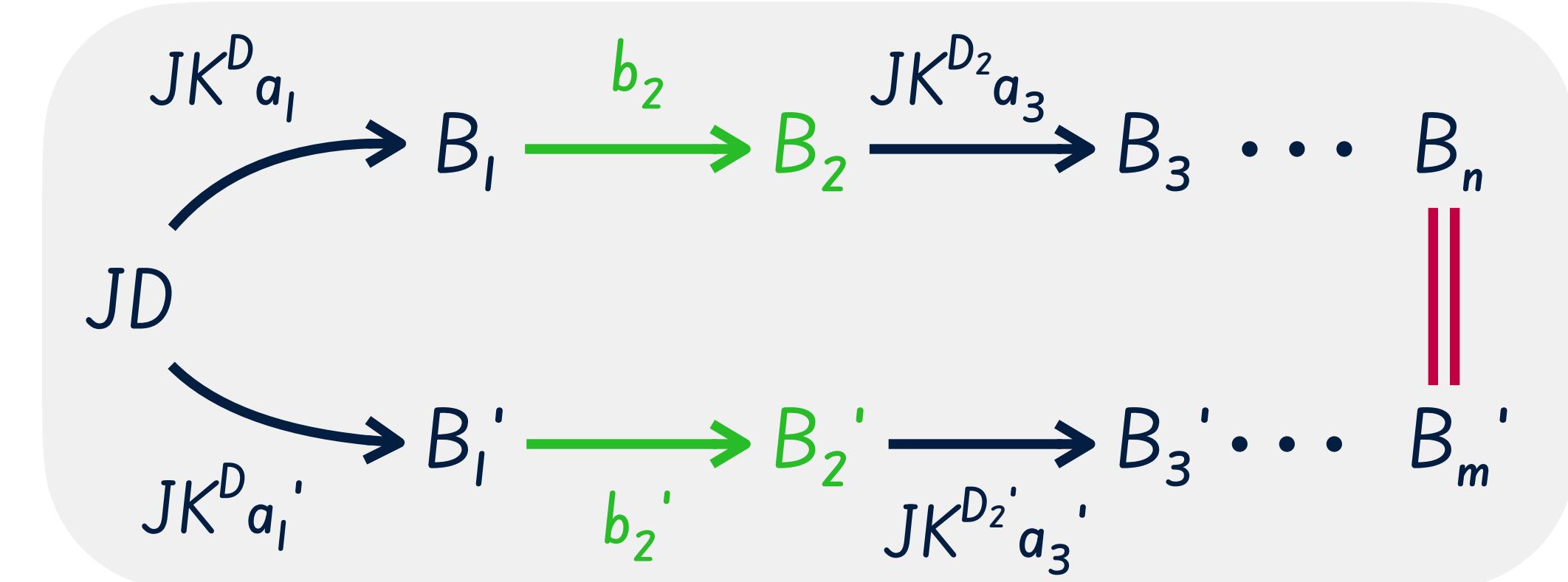
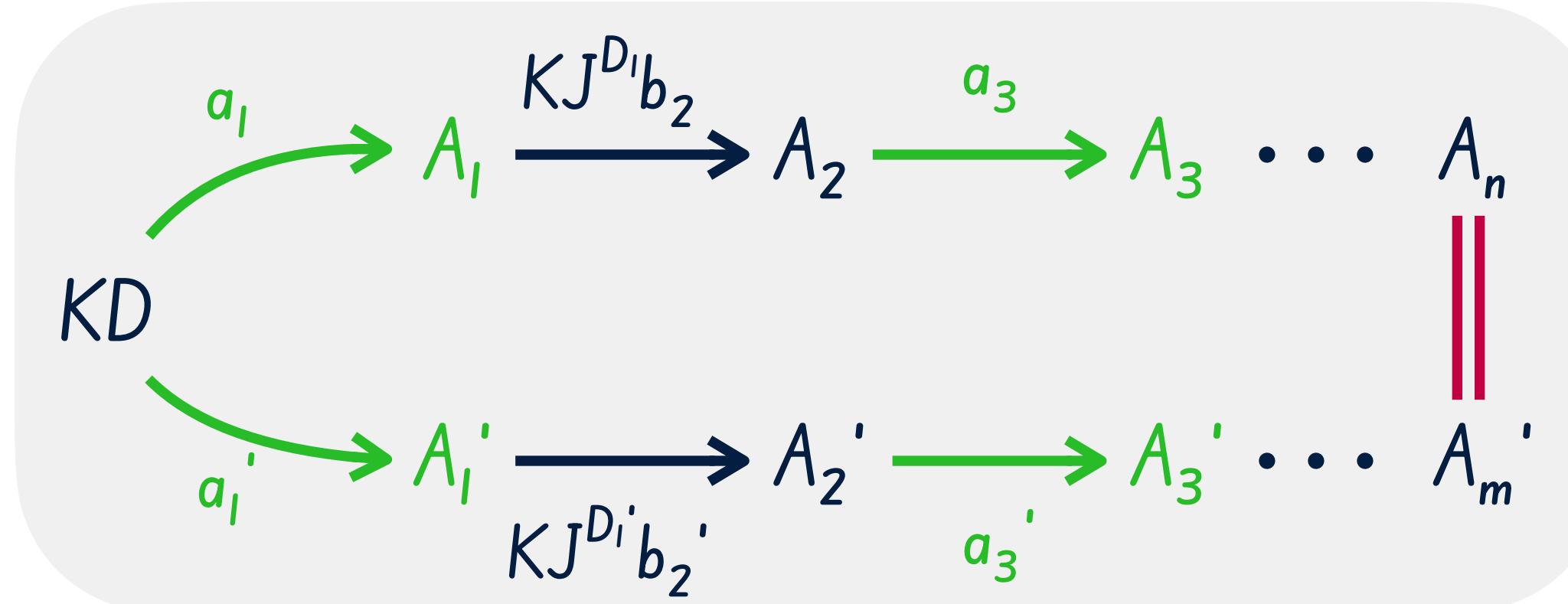
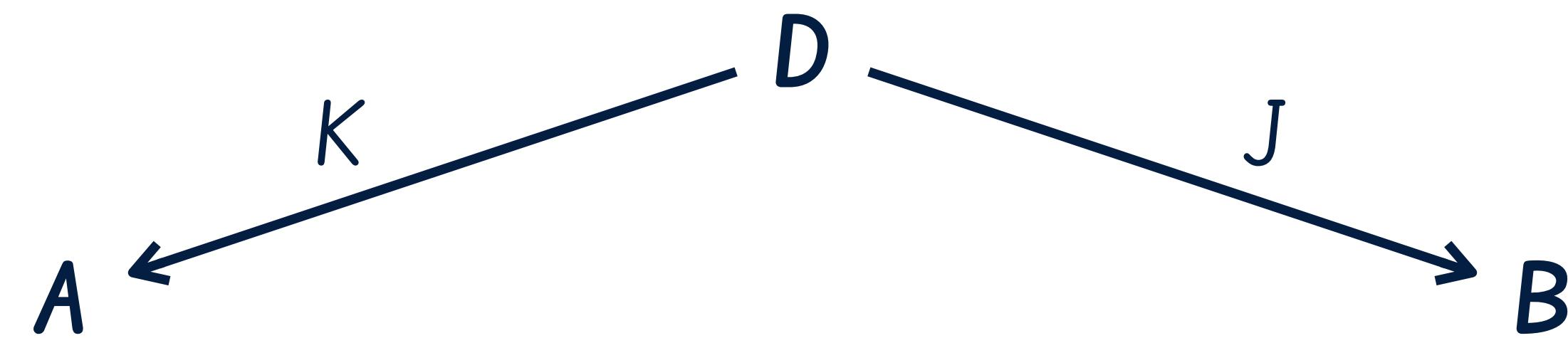
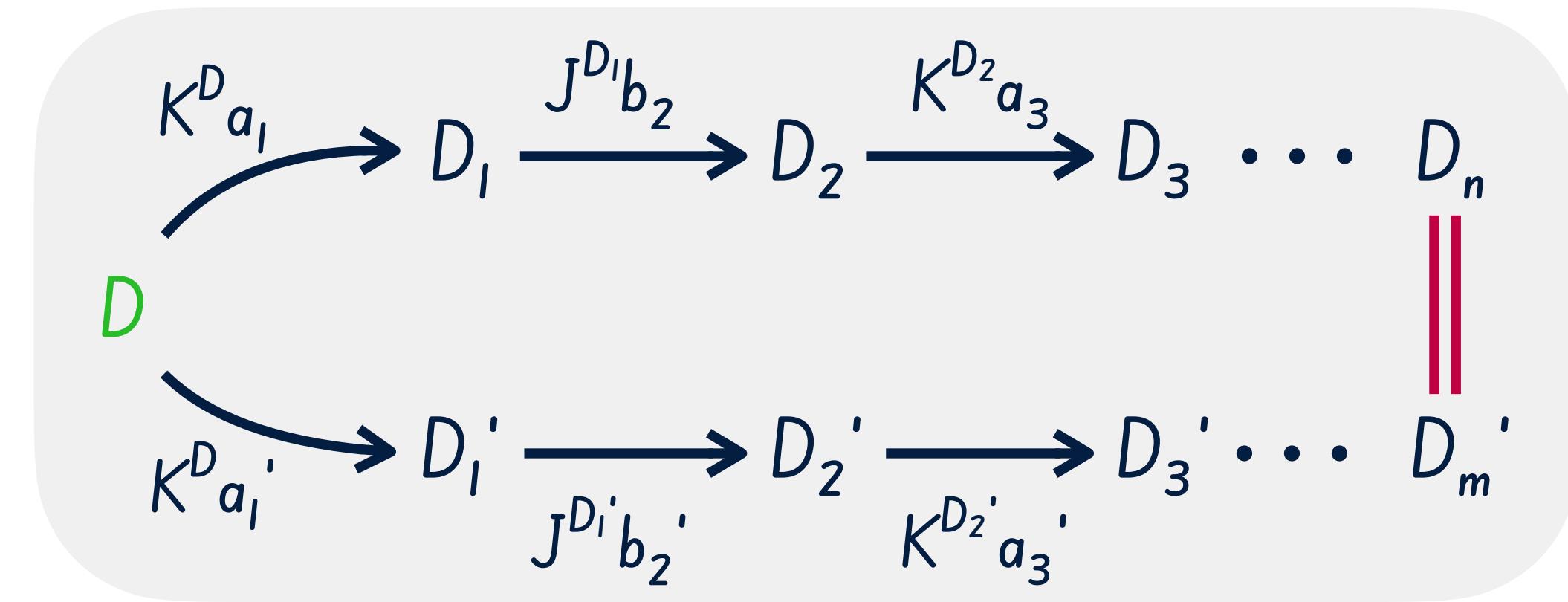
# Independence

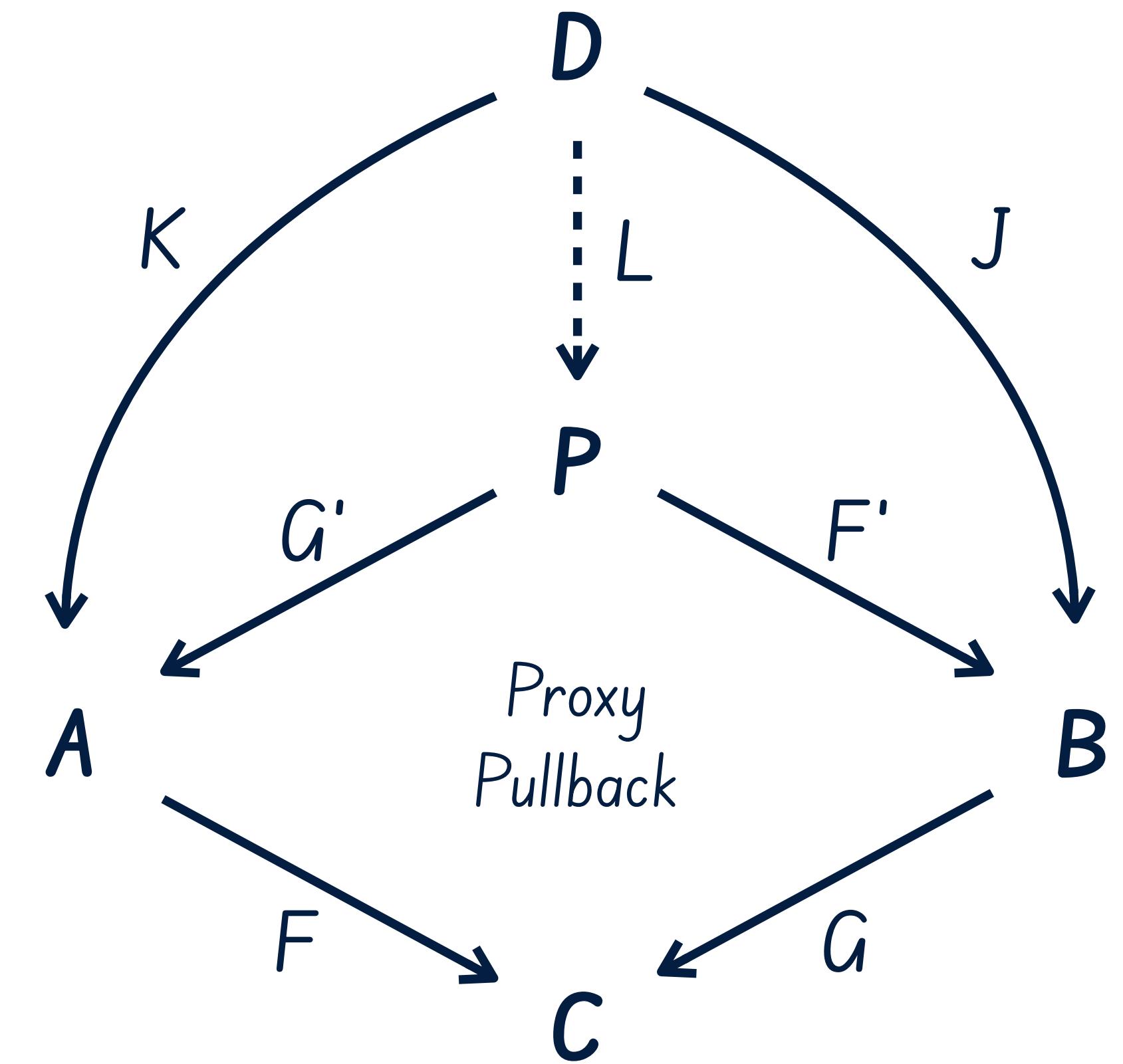


# Independence

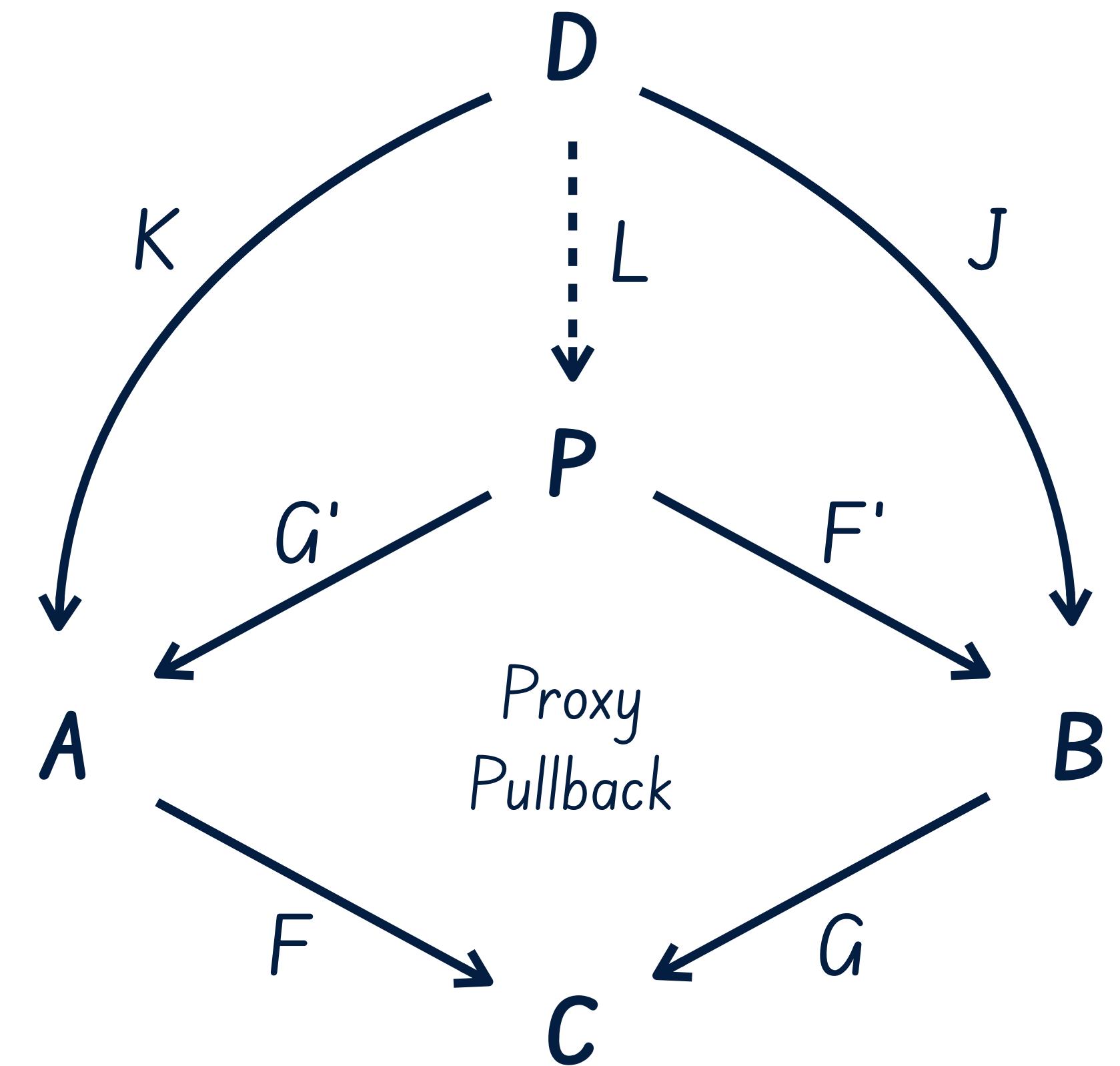


# Independence





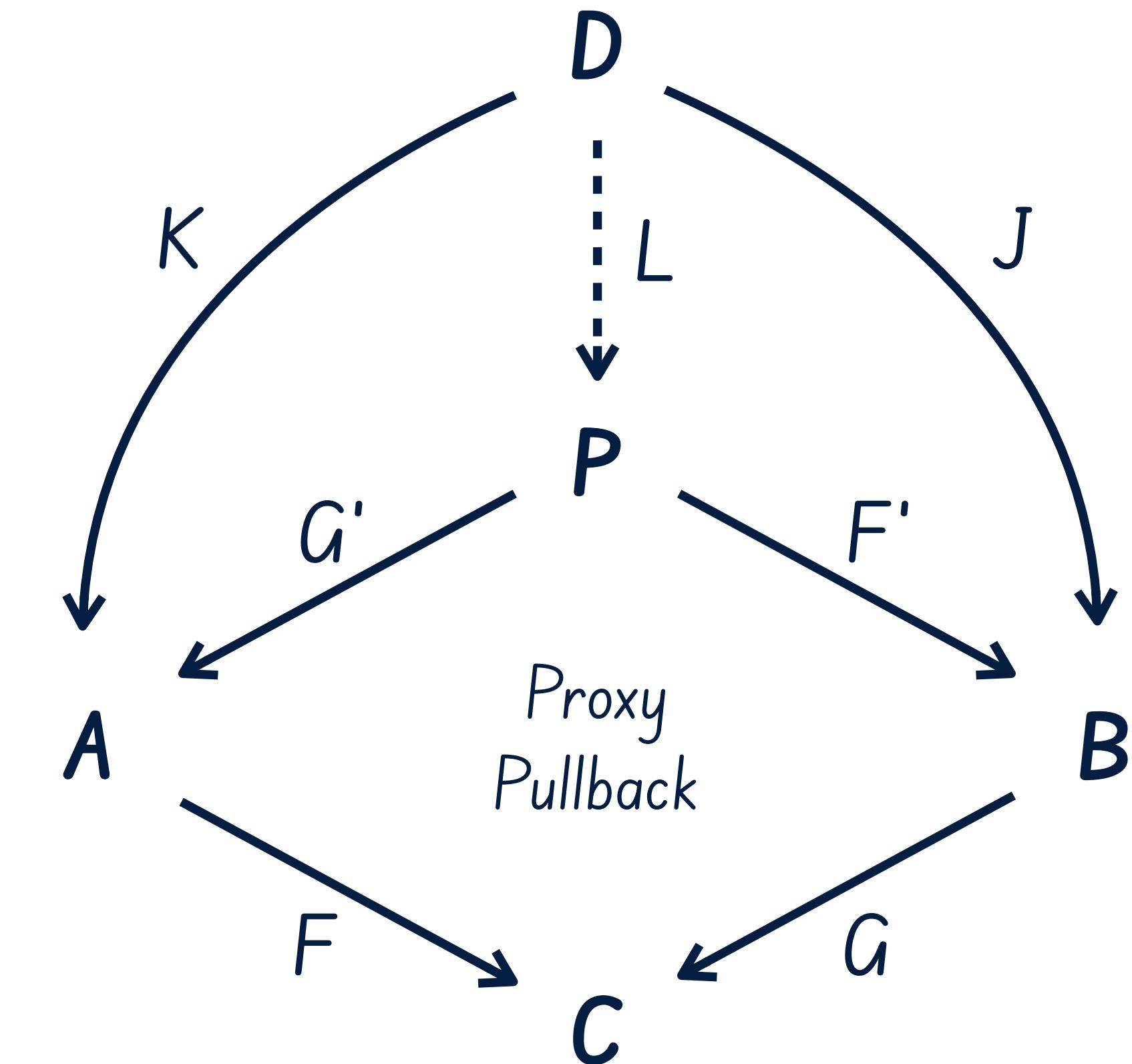
# Sufficient conditions



# Sufficient conditions

$(G', F')$   
sync minimal

$\iff$   
 $L$  exists **for all**  $(K, J)$   
independent and  
compatible with  $(F, G)$



# Conclusion

- *Sync-minimal* lens proxy pullbacks are universal amongst the *independent* and *compatible* lens spans
- This characterisation allowed a better understanding of when lens proxy pullbacks are real pullbacks
- Approach was inspired by Böhm and Simpson's treatment of pullback proxies in other categories