

MONOIDAL STREAMS

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PART 0: DATAFLOW PROGRAMMING

MOTIVATION: DATAFLOW PROGRAMMING

Dataflow programming is a paradigm for repeated processes: every declaration is a sequence of values.

$$\begin{aligned} \text{fib} &= 0 \text{ FBY } (1 \text{ FBY WAIT fib} + \text{fib}) \\ \text{nat} &= 0 \text{ FBY } (1 + \text{nat}) \end{aligned}$$

- Elegant recursive dataflow syntax.
- Signal flow, 'trace-like' diagrams.
- Semantics: causal streams for the cartesian case.

E.g. LUSTRE, LUCID.  Ashcroft, Wadge, 85

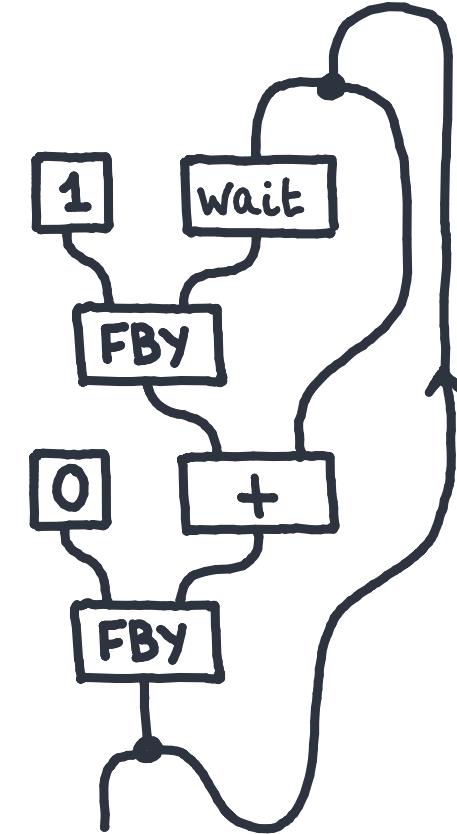


FIG. Signal flow graph.

MOTIVATION: DATAFLOW PROGRAMMING

Dataflow programming is a paradigm for repeated processes: every declaration is a sequence of values.

{"followed by"}

$\text{fib} = 0 \text{ FBY } (1 \text{ FBY WAIT } \text{fib} + \text{fib})$

$\text{nat} = 0 \text{ FBY } (1 + \text{nat})$

"delayed stream"

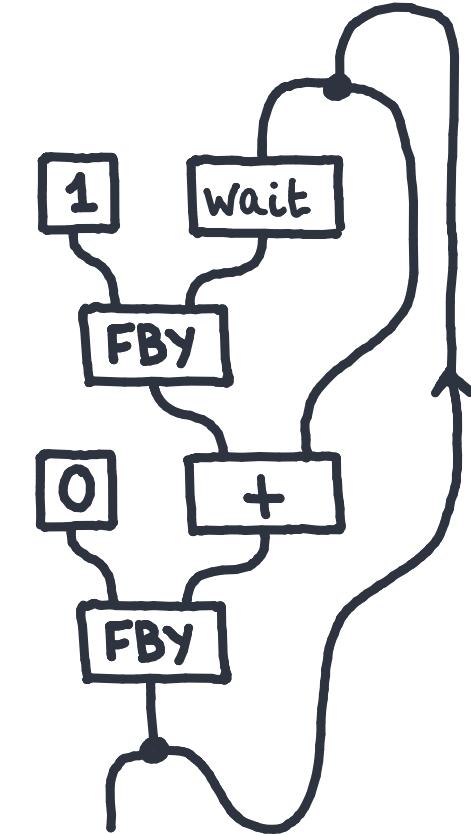


FIG. Signal flow graph.

- Elegant recursive dataflow syntax.
- Signal flow, 'trace-like' diagrams.
- Semantics: causal streams for the cartesian case.

E.g. LUSTRE, LUCID.

CAUSAL STREAM FUNCTIONS

DEFINITION. A *causal stream function* $f: \mathbb{X} \rightarrow \mathbb{Y}$ is a family of functions

$$f_n: X_0 \times \dots \times X_n \rightarrow Y_n.$$

$$f_0: X_0 \rightarrow Y_0$$

$$f_1: X_0 \times X_1 \rightarrow Y_1$$

$$f_2: X_0 \times X_1 \times X_2 \rightarrow Y_2$$

...

These form a monoidal category, the cokleisli category of the non-empty list monoidal comonad,

$$\text{List}^+: [\mathbf{N}, \mathbf{SET}] \rightarrow [\mathbf{N}, \mathbf{SET}], \quad \text{List}^+(\mathbb{X})_n = \prod_{i=0}^n X_i.$$

We have

- a delay functor taking $\mathbb{X} = (X_0, X_1, X_2, \dots)$ into $\partial\mathbb{X} = (1, X_0, X_1, \dots)$;
- a trace-like operator taking $\partial S \otimes \mathbb{X} \rightarrow S \otimes \mathbb{Y}$ into $\mathbb{X} \rightarrow \mathbb{Y}$;
- coalgebraic reasoning and coinductive arguments.



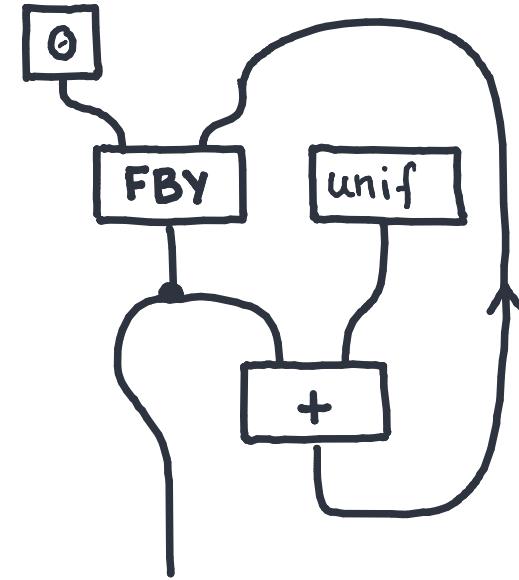
MONOIDAL DATAFLOW PROGRAMMING

What about the non-cartesian case?

$$\text{walk} = \emptyset \text{ FBY UNIFORM}\{-1,1\} + \text{walk}$$

We imagine what the syntax should be, but, what should replace streams in the semantics?

These will be monoidal streams.



Can we extend the comonad to monoidal categories? **No**. We need a different solution.

THEOREM (DLdFR). The non-empty list functor $\text{List}^+(\mathbb{X})_n = \bigotimes_{i=0}^n \mathbb{X}_i$ is a monoidal comonad if and only if (\otimes) is a cartesian product.

MOTIVATION

Today, given any symmetric monoidal category $(\mathcal{C}, \otimes, I)$, we will build a symmetric monoidal category of stream processes $\text{Stream}(\mathcal{C})$ such that

- $\text{Stream}(\mathcal{C})$ has an id-on objs functor from $[N, \mathcal{C}]$;
- $\text{Stream}(\mathcal{C})$ has a delay monoidal functor, \mathcal{D} ;
- $\text{Stream}(\mathcal{C})$ has delayed feedback taking $\mathcal{D}S \otimes X \rightarrow S \otimes Y$ into $X \rightarrow Y$;
- $\text{Stream}(\mathcal{C})$ has a coalgebraic description;
- $\text{Stream}(\mathcal{C})$ is cartesian when \mathcal{C} is;
- $\text{Stream}(SET)$ is the classical causal streams;
- $\text{Stream}(STOCH)$ is causal discrete stochastic processes.
- $\text{Stream}(\mathcal{C})$ is symm. premonoidal, effectful or Freyd when \mathcal{C} is.

Three definitions in terms of universal properties, and three constructions.

SYNOPSIS

Three definitions from universal properties, and three explicit constructions.
Each one a quotient of the previous.

1. Intensional streams, a first naïve version. Fail to form a category.
2. Extensional streams, a free category with feedback.
3. Observational streams, definitive solution to a fixpoint equation.

Two known particular cases, and an avenue for more.

1. Cartesian monoidal streams (Set, \times) are causal functions
(as in Uustalu-Vene, Sprunger-Jacobs).
2. Stochastic streams $(\text{Kl}(\mathcal{D}), \times)$ are controlled stochastic processes
(classical in the literature).
3. Kleisli streams of strong monads. Freyd categories in general.

Extra: implementing signal flow graphs and dataflow programs.

(Intensional)

PART 1 : MONOIDAL STREAMS

STREAMS AND STREAM FUNCTIONS

"A **stream** of types $A = (A_0, A_1, A_2, \dots)$ is an element of A_0 together with a **stream** of types $A^+ = (A_1, A_2, A_3, \dots)$."

$$S(A) \cong A_0 \times S(A^+).$$

STREAMS AND STREAM FUNCTIONS

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$$S(A) \cong A_0 \times S(A^+).$$

By **Adámek's Theorem**, the candidate solution is

$$\lim_{n \in \mathbb{N}} (1 \leftarrow A_0 \leftarrow A_0 \times A_1 \leftarrow A_0 \times A_1 \times A_2 \leftarrow \dots) = \prod_{n=0}^{\infty} A_n;$$

and it is a solution, $A_0 \times \prod_{n=1}^{\infty} A_n \cong \prod_{n=0}^{\infty} A_n$.



STREAMS AND STREAM FUNCTIONS

“A stream function from $\mathbb{X} = (X_0, X_1, X_2, \dots)$ to $\mathbb{Y} = (Y_0, Y_1, Y_2, \dots)$ is a function $X_0 \rightarrow Y_0$ communicating along a memory channel M with a stream function from $\mathbb{X}^+ = (X_1, X_2, X_3, \dots)$ to $\mathbb{Y}^+ = (Y_1, Y_2, Y_3, \dots)$.”

$$T(\mathbb{X}; \mathbb{Y}) = \sum_{M \in \text{SET}} \text{hom}(X_0, M \times Y_0) \times T(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

By Adamek's Theorem, the candidate solution is

$$\lim_{n \in \mathbb{N}} (1 \leftarrow \text{hom}(X_0, Y_0) \leftarrow \text{hom}(X_0, Y_0) \times \text{hom}(X_0 \times X_1, Y_1) \leftarrow \dots) = \prod_{n=0}^{\infty} \text{hom}(X_0 \times \dots \times X_n, Y_n);$$



MONOIDAL STREAMS

"A monoidal stream from $\mathbb{X} = (X_0, X_1, X_2, \dots)$ to $\mathbb{Y} = (Y_0, Y_1, Y_2, \dots)$ is a morphism $X_0 \rightarrow Y_0$ communicating along a memory channel M with a monoidal stream from $\mathbb{X}^+ = (X_1, X_2, X_3, \dots)$ to $\mathbb{Y}^+ = (Y_1, Y_2, Y_3, \dots)$."

$$T(\mathbb{X}; \mathbb{Y}) = \sum_{M \in SET} \text{hom}(X_0, M \otimes Y_0) \times T(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

By Adamek's Theorem, the candidate solution is

$$\lim_{n \in \mathbb{N}} (1 \leftarrow \sum_n \sum_{M_0} \text{hom}(X_0, M_0 \otimes Y_0) \leftarrow \sum_{M_0, M_1} \text{hom}(X_0, M_0 \otimes Y_0) \times \text{hom}(M_0 \otimes X_1, M_1 \otimes Y_1) \leftarrow \dots) = \\ \sum_{M: [N, C]} \prod_{n \in \mathbb{N}} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n).$$

MONOIDAL STREAMS

DEFINITION (DLdFR). An (intensional) **monoidal stream** $\mathbb{X} \rightarrow \mathbb{Y}$ is a family of objects M_0, M_1, M_2, \dots and a family of morphisms $f_n : M_{n-1} \otimes X_n \rightarrow M_n \otimes Y_n$.

$$T(\mathbb{X}, \mathbb{Y}) = \sum_{M: [N, C]} \prod_{n \in N} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n).$$

THEOREM (DLdFR). The set of monoidal streams, depending on inputs and outputs, is the terminal fixpoint of

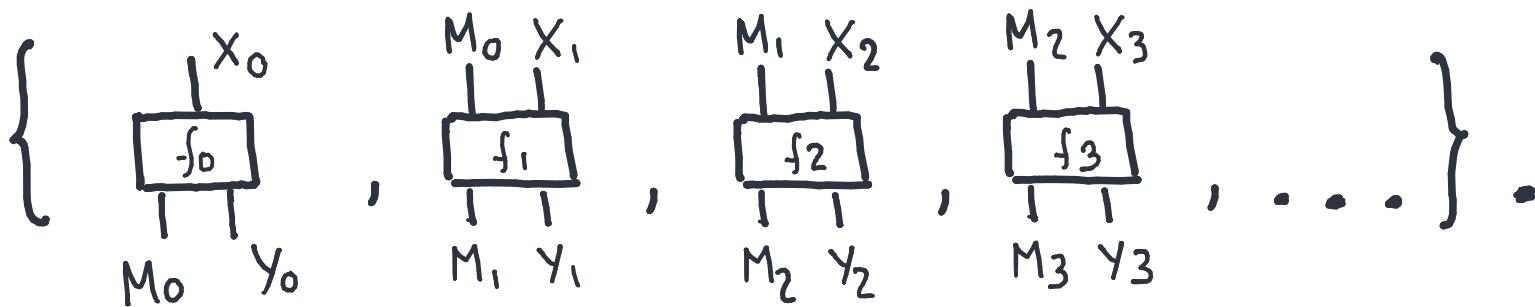
$$T(\mathbb{X}, \mathbb{Y}) = \sum_{M \in \text{SET}} \text{hom}(X_0, M \otimes Y_0) \times T(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

MONOIDAL STREAMS

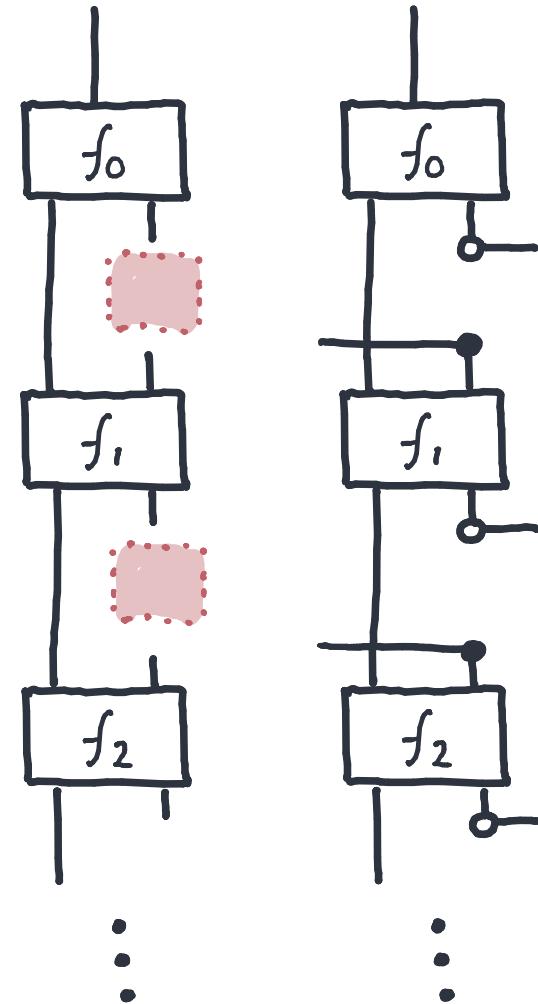
How to interpret a monoidal stream? In diagrams,

$$(f_n: M_{n-1} \otimes X_n \rightarrow M_n \otimes Y_n)$$

is



and yields the following "open diagram".



(Extensional)

PART 2 : MONOIDAL STREAMS

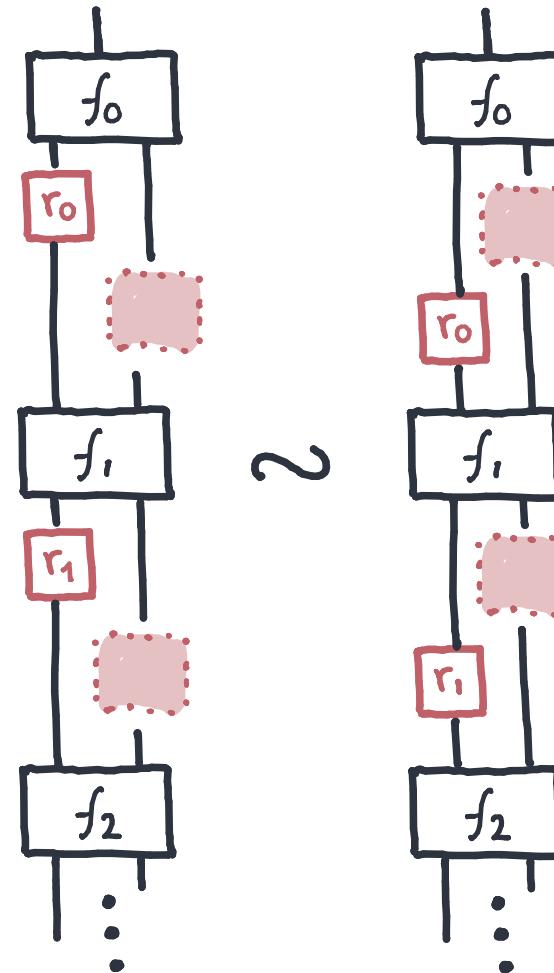
EXTENSIONAL STREAMS

Monoidal streams are too explicit: e.g. having memories $M_n = A_n \otimes (B_n \otimes C_n)$ is different from having memories $M_n = (A_n \otimes B_n) \otimes C_n$. This makes them fail to form a category.

DEFINITION. An **(extensional) monoidal stream** is an equivalence class of intensional streams under the minimal equivalence relation containing (\sim) .

$$\sum_{M: [N, C]} \prod_{n \in N} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n) / \langle \sim \rangle \\ = \\ \int^{M: [N, C]} \prod_{n \in N} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n)$$

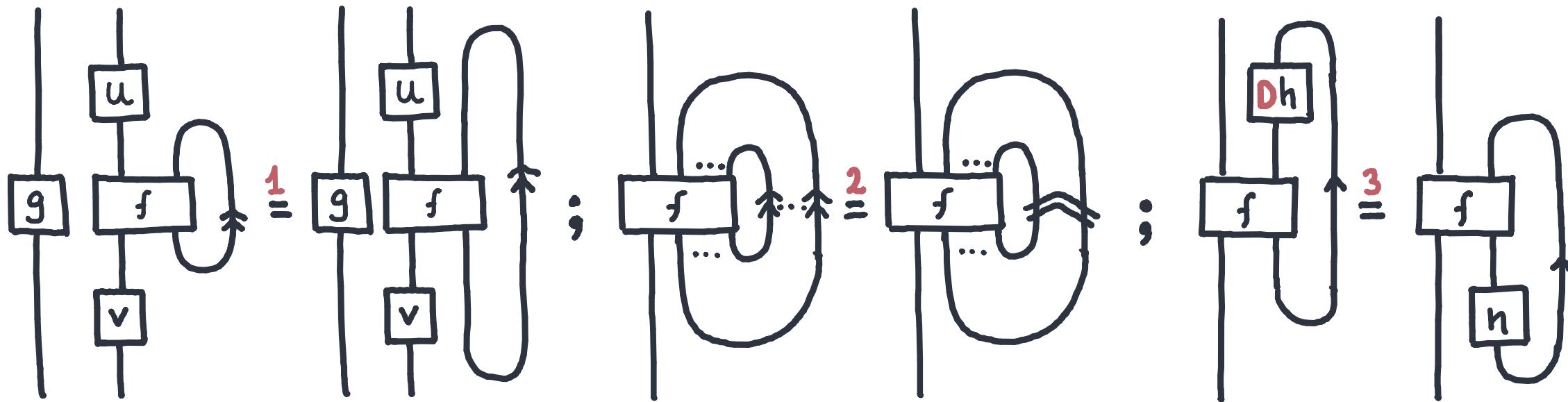
I like **coends**, but you may not; so let me justify them.



FEEDBACK

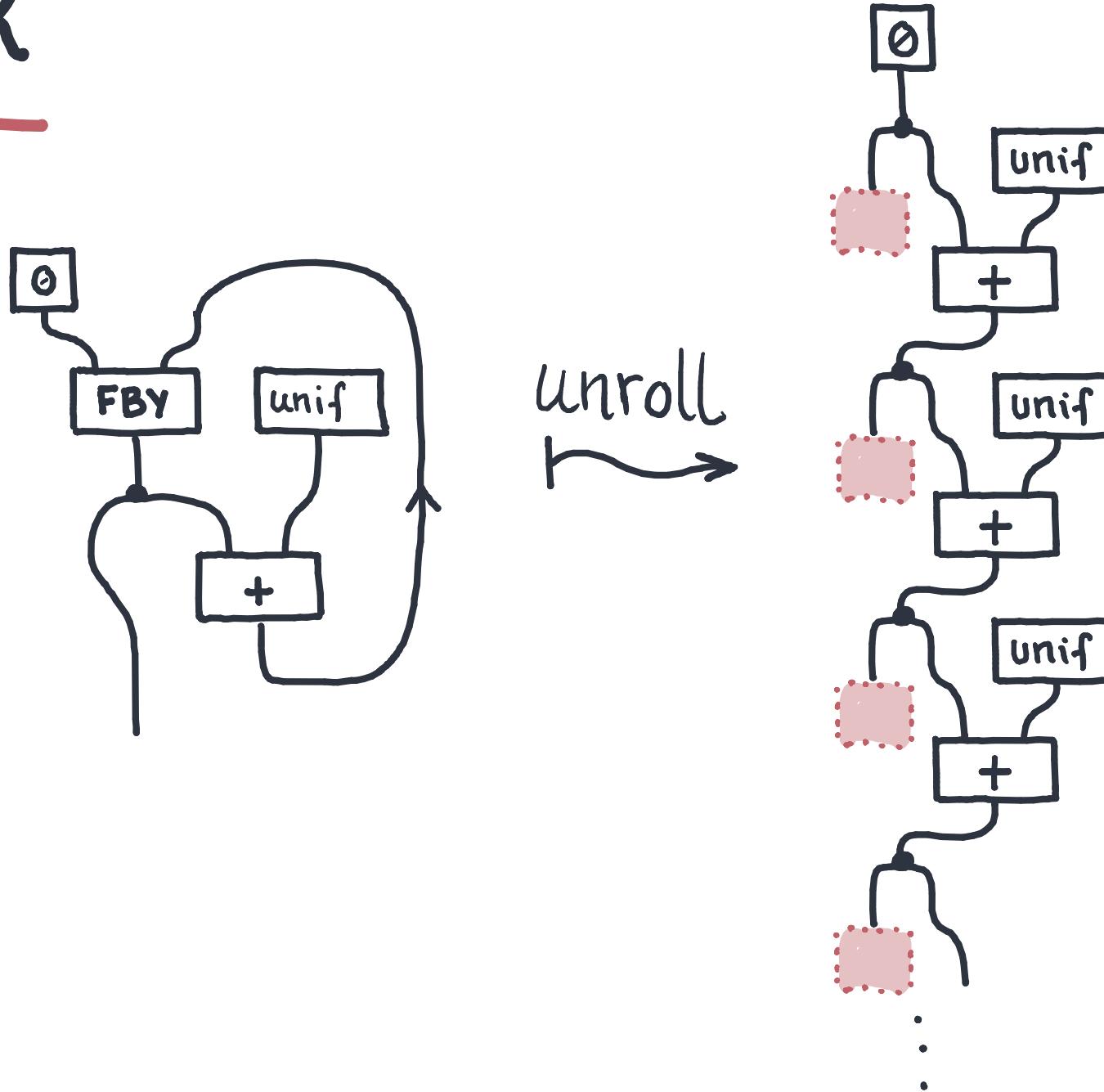
Feedback monoidal categories,  Katis, Sabadini, Walters, axiomatize signal flow graphs using a guarded feedback operator $\text{fbk}: \text{hom}(DS \otimes A, S \otimes B) \rightarrow \text{hom}(A, B)$.

AXIOMS.



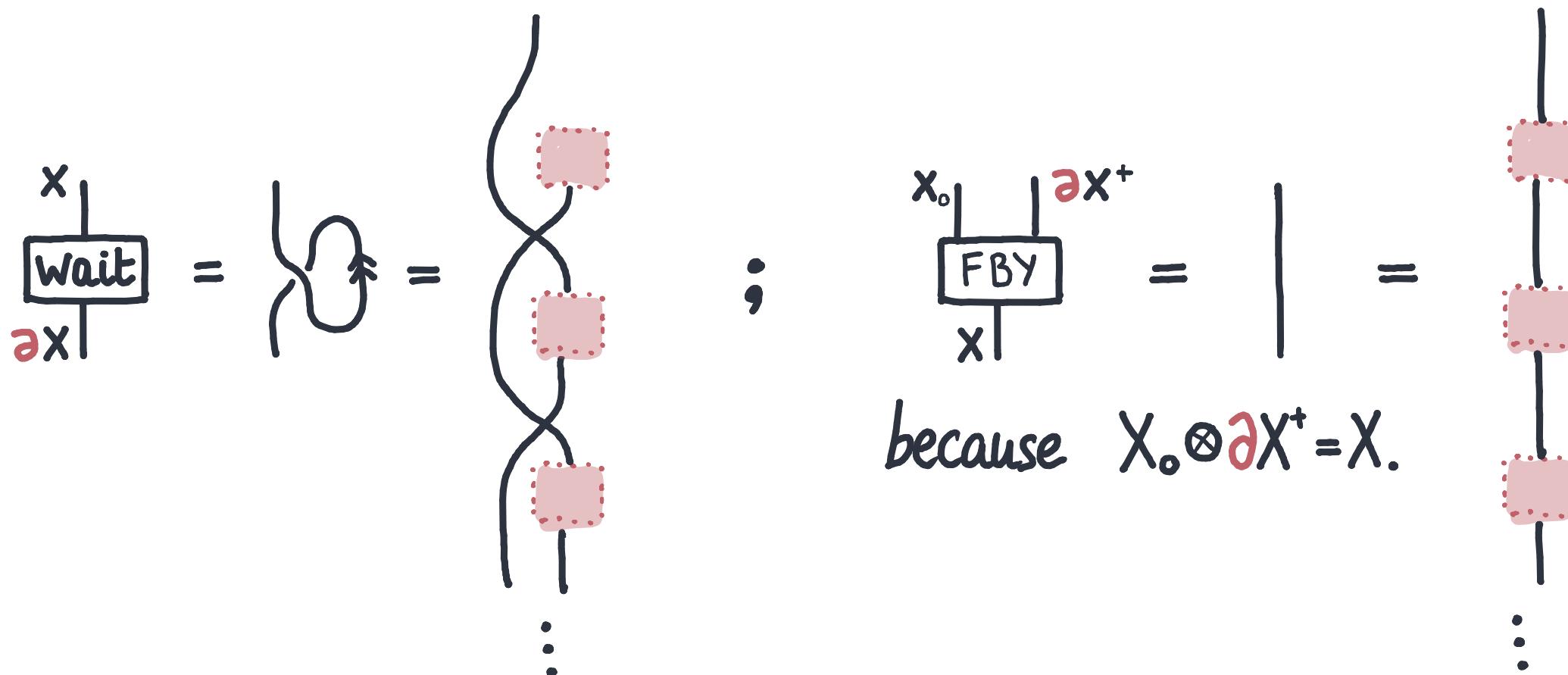
THEOREM (DLdFR). Extensional streams are the morphisms of the free category with feedback over $\partial: [N, C] \rightarrow [N, C]$, $\partial(A_0, A_1, A_2, \dots) = (I, A_0, A_1, \dots)$.

FEEDBACK



FEEDBACK

Dataflow syntax can be derived from [N,C] and feedback.



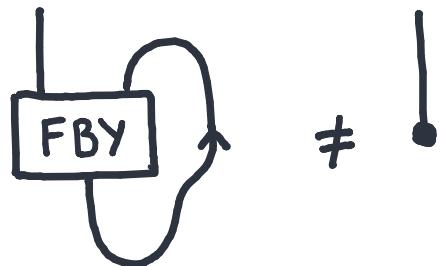
(Coinductive)

PART 3: MONOIDAL STREAMS

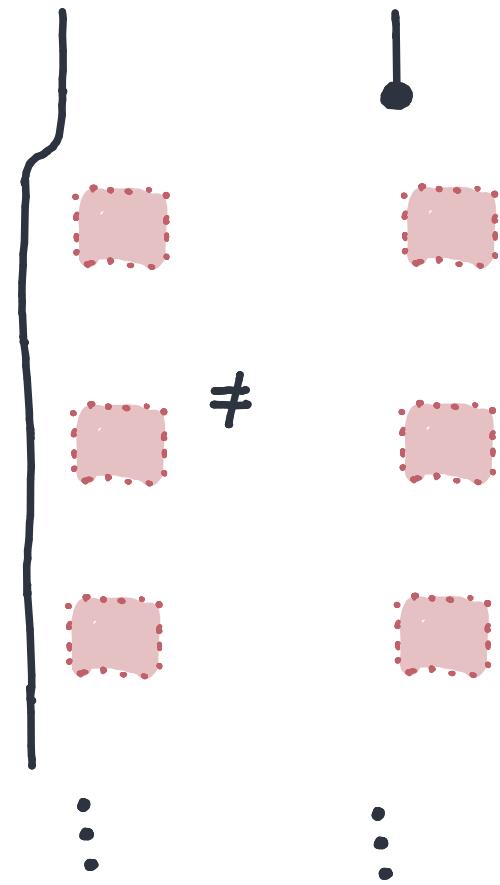
OBSERVATIONAL EQUIVALENCE

So, we want, at least, extensional equivalence. Can we refine it?

Saving to memory without outputting is, observationally, the same as discarding. However, no amount of sliding will help us equating these two.



=



Two streams are observationally equal if their nth truncations can be made equal.

COINDUCTIVE MONOIDAL STREAMS

Reasoning with monoidal streams in well-behaved categories is easy: they are a final coalgebra.

THEOREM (DLdFR). Monoidal streams (with observational eq.) are the final coalgebra of

$$Q(X, Y) \cong \int^{M:C} \text{hom}(X_0, M \otimes Y_0) \times Q(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

DEFINITION (DLdFR). A monoidal stream $f \in \text{Stream}(X_0, X_1, \dots; Y_0, Y_1, \dots)$ is

- a memory $M(f) \in C$
- a $\text{now}(f) : X_0 \rightarrow M(f) \otimes Y_0$,
- and a $\text{later}(f) \in \text{Stream}(M \otimes X_1, X_2, \dots; Y_1, Y_2, \dots)$.

Quotiented by $f \approx g$, meaning

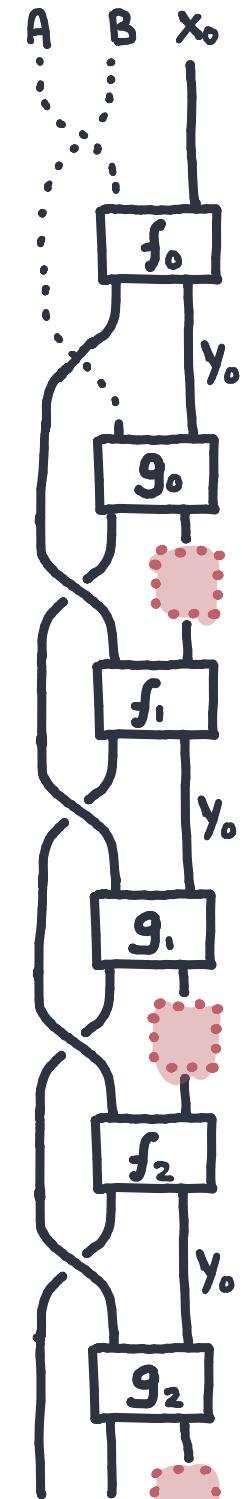
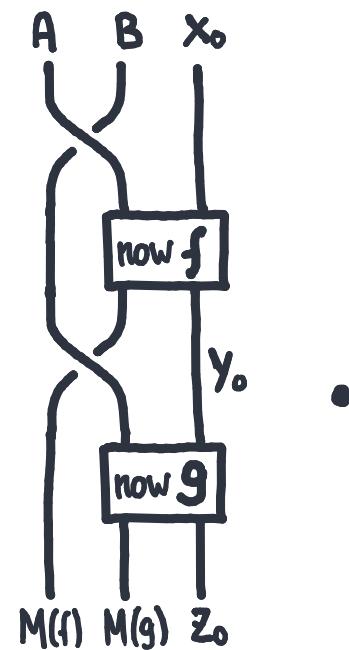
- the existence of $r : M(f) \rightarrow M(g)$,

- such that $\text{now}(f); (r \otimes \text{id}) = \text{now}(g)$,
- and such that $\text{later}(f) \approx r \cdot \text{later}(g)$.

COINDUCTIVE MONOIDAL STREAMS

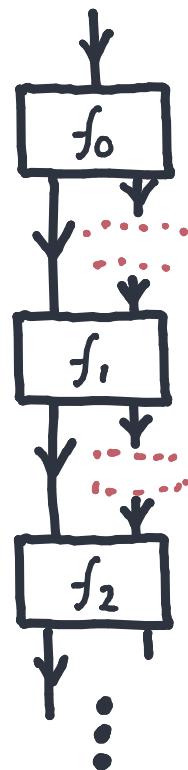
SEQUENTIAL COMPOSITION WITH MEMORY of $f \in \text{Stream}(A \cdot X, Y)$ and $g \in \text{Stream}(B \cdot Y, Z)$ is written as $(f^A; g^B) \in \text{Stream}(A \otimes B \cdot X, Z)$, and defined by

- $M(f^A; g^B) = M(f) \otimes M(g)$;
- $\text{later}(f^A; g^B) = \text{later}(f)^{M(g)} ; \text{later}(g)^{M(f)}$, by coinduction;
- $\text{now}(f^A; g^B) =$



PART 4 : EXAMPLES

CARTESIAN MONOIDAL STREAMS



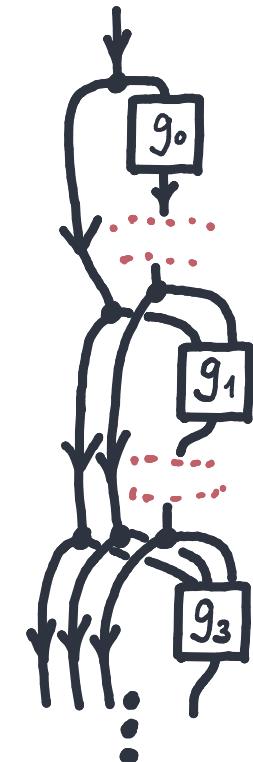
$S(X, Y)$

$$\cong \int^{M:C} \text{hom}(X_0, M \times Y_0) \times S(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$

$$\cong \int^{M:C} \text{hom}(X_0, M \times Y_0) \times S(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$

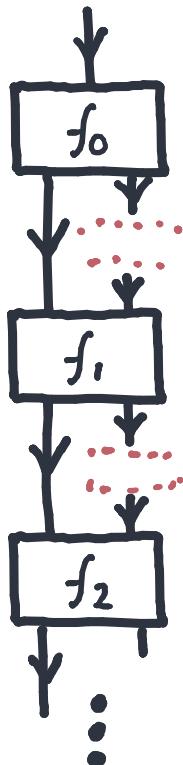
$$\cong \int^{M:C} \text{hom}(X_0, M) \times \text{hom}(X_0, Y_0) \times S(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$

$$\cong \text{hom}(X_0, Y_0) \times S(X_0 \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

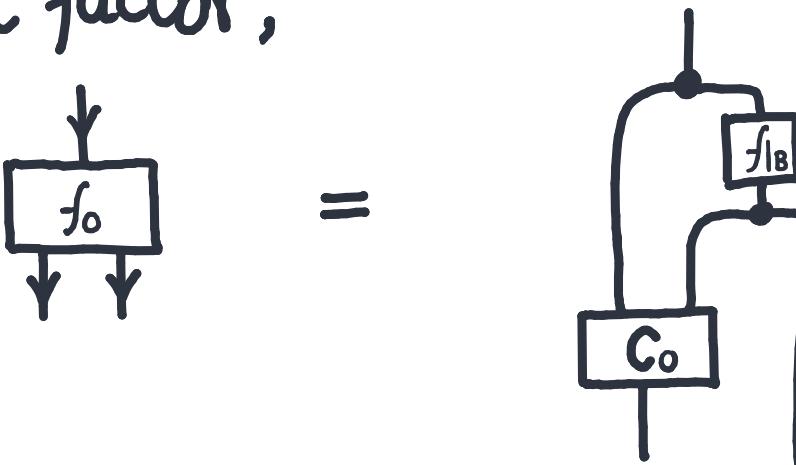


THEOREM. In cartesian monoidal categories, monoidal streams are causal stream functions.

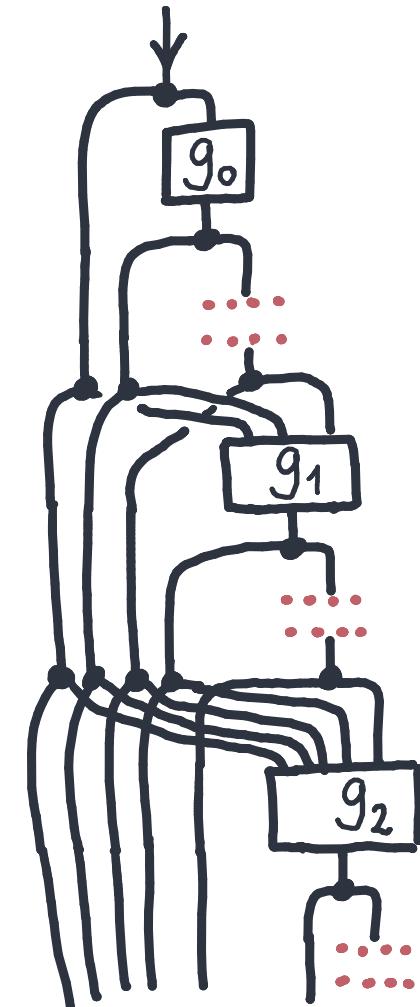
STOCHASTIC MONOIDAL STREAMS



In **Markov categories** with conditionals,
we can factor,



We use this to show that monoidal streams of stochastic functions are the same as **controlled stochastic processes**.



STOCHASTIC PROCESSES

DEFINITION. A **controlled stochastic process** $f: \mathbb{X} \rightarrow \mathbb{Y}$ is a family of stochastic functions $f_n: X_0 \times \dots \times X_n \rightarrow D(Y_0 \times \dots \times Y_n)$ satisfying

$$\begin{array}{ccc} X_0 \times \dots \times X_{n+1} & \xrightarrow{f_{n+1}} & D(Y_0 \times \dots \times Y_{n+1}) \\ \downarrow^n & & \downarrow D^n \\ X_0 \times \dots \times X_n & \xrightarrow{f_n} & D(Y_0 \times \dots \times Y_n). \end{array}$$

causality: the future X_{n+1} should not influence the past Y_0, \dots, Y_n .

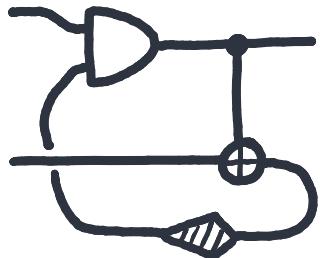
THEOREM (DLdFR). Monoidal streams over $KL(D)$ coincide with controlled stochastic processes.

PROOF. Non trivial. Somehow, the causality condition means that the family can be written *uniquely* as a monoidal stream.

FURTHER WORK



Carette, de Visme, Perdrix.



Can we compare
with the graphical
language here?

Delayed Trace.



Kaye, Sprunger, Ghica

Better treatment of the finite
memory case.



Cruttwell, Gallagher, Lemay, Pronk
Blute, Cockett, Lemay, Seely

Can we preserve the differential
structure from cartesian to
monoidal?



Spivak Myers Shapiro, Spivak
Smithie Hornischer.

How much can we recover in terms
of (continuous) dynamical systems?
How much of the coalgebra in terms
of polynomial functors?



Power, Robinson

Premonoidal streams are arguably
more interesting.



Román. Open Diagrams.

MONOIDAL STREAMS FOR DATAFLOW PROGRAMMING

ArXiv: 2202.02061, to be presented at LiCS'22.



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END

RELATED WORK



Katis-Sabadini-Walters. Categories with feedback, missing delay.



Sprunguer-Katsumata, Ghica-Kaye. Finite memory or cartesian streams.



Uustalu-Vene. Cartesian streams, distributive laws for effects.



Hughes-Paterson. ArrowLoop are similar, but for traces.



Carette-De Visme-Perdrix. Syntax for similar streams.



Many others. Categorical dataflow. Functional reactive programming.

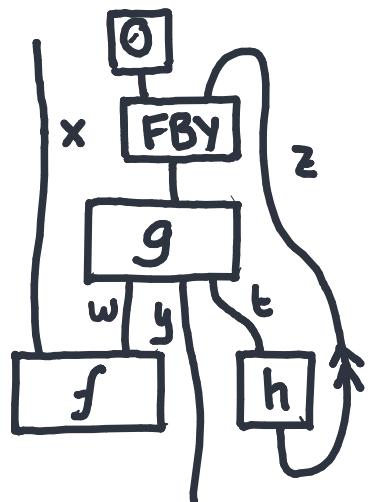


Román. Open diagrams via Coend Calculus.

EXTRA : IMPLEMENTATION

IMPLEMENTATION

Type theory for sym. monoidal categories with feedback.



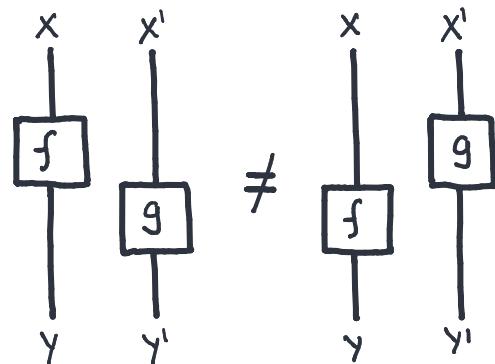
FBK z.
SPLIT $g(0 \text{ FBY } h(z)) \rightarrow [w, y, t]$ IN
SPLIT $f \times w \rightarrow []$ IN
RETURN y.

Obvious candidate: Haskell **Arrows** give notation for Set-based Freyd categories.

- **ArrowLoop** is for traced categories, in theory; it works for feedback.
- Github: [mroman42/arrow-streams](https://github.com/mroman42/arrow-streams).

PREMONOIDAL CATEGORIES

A sym. premonoidal category $(\mathcal{C}, \otimes, I)$ is a sym. monoidal category without the interchange law.



They usually have a family of "pure" morphisms that do satisfy interchange, forming a monoidal \mathbb{V} .

$$\mathbb{V} \rightarrow \mathcal{C}$$

PURE — id-on-objects functor → EFFECTFUL

This is called a Freyd category.

DEFINITION. The set of premonoidal streams in a Freyd category $\mathbb{V} \rightarrow \mathcal{C}$ is the final fixpoint of

$$Q(X, Y) \cong \int^{M: \mathbb{V}} \text{hom}_{\mathcal{C}}(X_0, M \otimes Y_0) \times Q(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

Only pure morphisms should slide.

THEOREM. If \mathbb{V} is cartesian, and \mathcal{C} is weakly cartesian then this final coalgebra is constructed by observational streams.

EXTRA : COINDUCTION

COINDUCTIVE MONOIDAL STREAMS

DEFINITION (DLdFR). A monoidal stream $f \in \text{Stream}(X_0, X_1, \dots; Y_0, Y_1, \dots)$ is

- a memory $M(f) \in \mathcal{C}$
- a $\text{now}(f) : X_0 \rightarrow M(f) \otimes Y_0$,
- and a $\text{later}(f) \in \text{Stream}(M \otimes X_1, X_2, \dots; Y_1, Y_2, \dots)$.

Quotiented by $f \approx g$, meaning

- the existence of $r : M(f) \rightarrow M(g)$,
- such that $\text{now}(f); (r \otimes \text{id}) = \text{now}(g)$,
- and such that $\text{later}(f) \approx r \cdot \text{later}(g)$.

COINDUCTIVE MONOIDAL STREAMS

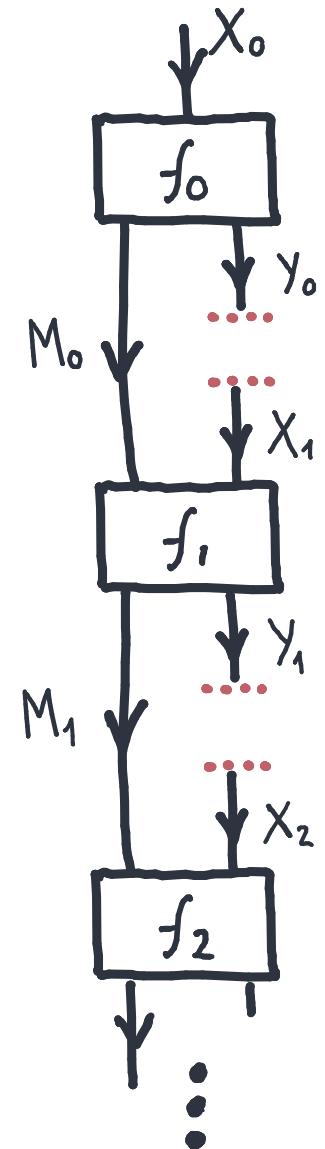
Reasoning with monoidal streams is easy: they are a final coalgebra.

$$S(X, Y) \cong \int^{M:C} \text{hom}(X_0, M \otimes Y_0) \times S(M \otimes X_0, X_1, X_2, \dots; Y_0, Y_1, Y_2, \dots).$$

Let me write $X \in [N, C]$ for X_0, X_1, \dots ; write X^+ for X_1, X_2, \dots ; and write $M \cdot X$ for $M \otimes X_0, X_1, X_2, \dots$; the equation becomes

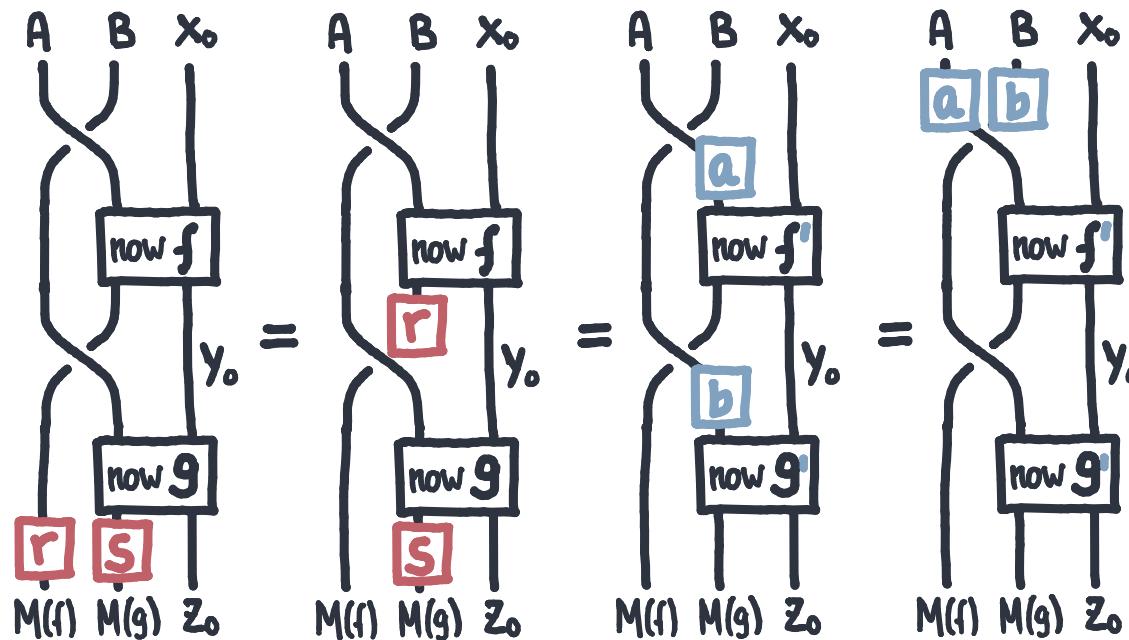
$$S(X, Y) \cong \int^{M:C} \text{hom}(X_0, M \otimes Y_0) \times S(M \cdot X^+; Y^+).$$

The coend connects the M to the next step.



COINDUCTIVE MONOIDAL STREAMS

SEQUENTIAL COMPOSITION is well-defined. Given generators $f \approx^r a \cdot f'$ and $g \approx^s b \cdot g'$, we can show that $(f^A; g^B) \stackrel{r \otimes s}{\approx} (a \otimes b) \cdot (f'^A; g'^B)$.



By coinduction,

$$\text{later}(f) \stackrel{M(f)}{\approx} \text{later}(g) \stackrel{M(g)}{\approx} \approx \\ (\text{r} \otimes \text{s}) \cdot (\text{later}(f') \circ \text{later}(g')).$$

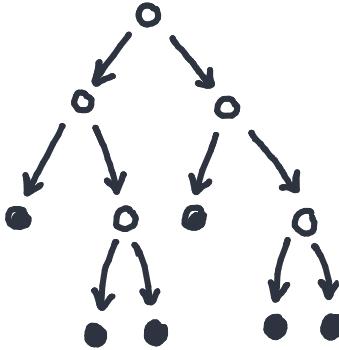
using $\text{later}(f) \approx \text{r} \cdot \text{later}(f')$
 $\text{later}(g) \approx \text{s} \cdot \text{later}(g')$.

When $a = \text{id}_A$, $b = \text{id}_B$, we have $(f \approx^r f') \wedge (g \approx^s g') \Rightarrow f^A; g^B \stackrel{r \otimes s}{\approx} f'^A; g'^B$.

ALGEBRA



Finite lists.
 $L \cong A \times L + 1$



Finite trees.
 $T \cong T^2 + 1$

1
2
3
⋮

Natural numbers.
 $N \cong N + 1$

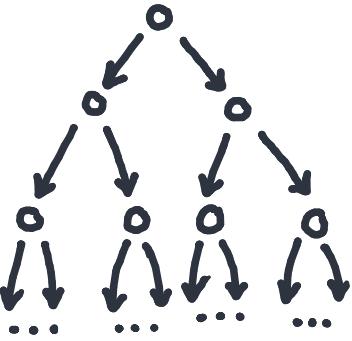
Mathematics of syntax.

- Find the **initial** fixpoint of a functor, $FX \cong X$.
- Reason inductively.

COALGEBRA



Infinite lists.
 $L \cong A \times L$



Infinite trees.
 $T \cong T^2$



Natural numbers.
 $N \cong N + 1$

Algebra of state and transitions.

- Find the *final* fixpoint of a functor, $FX \cong X$.
- Reason coinductively.

COALGEBRA

THEOREM (LAMBEK). If the **final coalgebra** exists, it is a **final fixpoint**.

THEOREM (ADAMEK). If the following limit is a fixpoint, it is final.

$$\lim_{n \in \mathbb{N}} (1 \leftarrow F1 \xleftarrow{F!} FF1 \xleftarrow{FF!} FFF1 \leftarrow \dots).$$

$$\begin{array}{ccc} X & \xrightarrow{f} & U \\ \alpha \downarrow & \parallel & \downarrow \cong \\ FX & \xrightarrow[Ff]{} & FU \end{array}$$

That is, to compute a fixpoint, repeatedly apply F and it will converge. Hopefully you will arrive to the fixpoint.

Initial algebras work too, but they will be less interesting.

COINDUCTION

Reverse an infinite tree.

$$\text{reverse}(a; l, r) := (a, \text{reverse}(l), \text{reverse}(r))$$

$$\text{rev} \left(\begin{array}{c} \circ \\ \Delta \quad \Delta \end{array} \right) = \text{rev}(\Delta) \text{ rev}(\Delta)$$

Reverse is self-inverse.

Coinduction
Hypothesis

$$\text{rev} \left(\text{rev} \left(\begin{array}{c} \circ \\ \Delta \quad \Delta \end{array} \right) \right) = \text{rev} \left(\text{rev}(\Delta) \text{ rev}(\Delta) \right) = \text{revrev}(\Delta) \text{ revrev}(\Delta) = \begin{array}{c} \circ \\ \Delta \quad \Delta \end{array} .$$

EXTRA : OBSERVATIONAL STREAMS

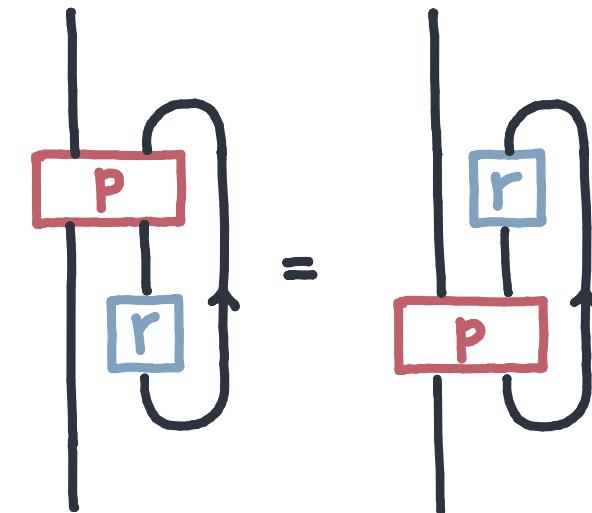
PROCESS INTERPRETATION

We think of functors $\mathcal{C}^{\text{op}} \times \mathcal{C} \rightarrow \text{SET}$ as indexing families of processes, $P(M, N)$, by **input M** and **output N**. How to plug the output to the input?

Given $r: N \rightarrow M$,

- $P(\text{id}, r)(p) \in P(M, M)$, translate **after reading**,
- $P(r, \text{id})(p) \in P(N, N)$, translate **before writing**.

These are "morally the same": **dinaturally equivalent**.



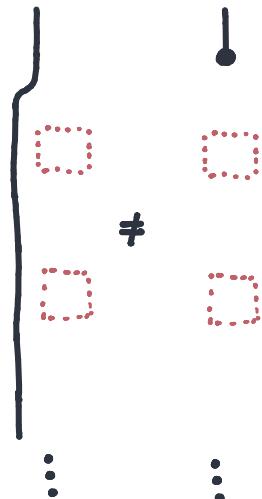
We write the set $\int^{x \in \mathcal{C}_{\text{obj}}} P(x, x)$ for $\sum_{x \in \mathcal{C}_{\text{obj}}} P(x, x) / \sim$, the **coend** of P ,

- $P(\text{id}, r)(p) \sim P(r, \text{id})(p)$.

OBSERVATIONAL EQUIVALENCE

So, we want, at least, extensional equivalence. Can we refine it?

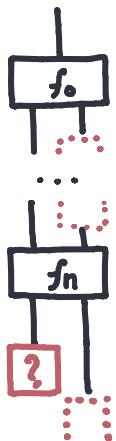
Saving to memory without outputting is, observationally, the same as discarding. However, no amount of sliding will help us equating these two.



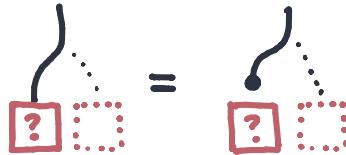
OBSERVATIONAL EQUIVALENCE

So, we want, at least, extensional equivalence. Can we refine it?

DEFINITION. The n th-truncation of an extensional stream $\langle f_n \rangle$ is the first n components, up to any continuation.



Two streams are **observationally equal** if their n th truncations are equal. For instance,



This is not only a reasonable-sounding rule. This makes observational streams a canonical fixpoint.

OBSERVATIONAL STREAMS

Intensional streams were the canonical fixpoint of the equation

$$T(X, Y) \cong \sum_{M \in C} \text{hom}(X_0, M \otimes Y_0) \times T(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

THEOREM (DLdFR). *Observational streams*, in reasonably well-behaved categories (**productive**) are the canonical fixpoint of the equation

$$Q(X, Y) \cong \int^{M \in C} \text{hom}(X_0, M \otimes Y_0) \times Q(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

Why not in all categories? You could craft a category where there is no way to go from X_0 to Y_0 without knowing the future!

I.e. there are infinitely descending chains for a Loebner-like order $\frac{\sqsupseteq}{\sqsubset} = \frac{\sqsupseteq_{fin}}{\sqsubset}$.

OBSERVATIONAL STREAMS

Why not in **all categories**? You could craft a category where there is no way to go from X_0 to Y_0 without knowing the future! Adamek could fail.

$$\int^{M:C} \text{hom}(X_0, M \otimes Y_0) \times \lim_{n \in N} \int^{M_1, \dots, M_n} \prod_{i=1}^n \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i)$$

$\cong \checkmark$ fine

$$\int^{M:C} \lim_{n \in N} \int^{M_1, \dots, M_n} \text{hom}(X_0, M \otimes Y_0) \times \prod_{i=1}^n \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i)$$

$\cong \times$ only discrete coproducts commute with connected limits

$$\lim_{n \in N} \int^{M:C} \int^{M_1, \dots, M_n} \text{hom}(X_0, M \otimes Y_0) \times \prod_{i=1}^n \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i)$$

I.e. there are infinitely descending chains for a Loebner-like order $\frac{\square}{f^n} = \frac{\square}{f^{n+1}}$.

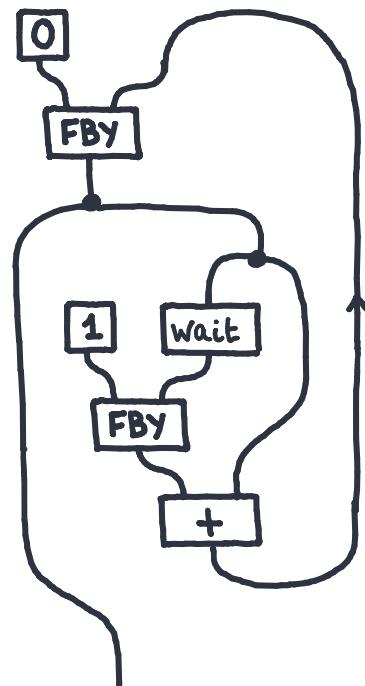
Nothing to worry in semi cartesian, compact closed and freely generated monoidal.

EXTRA : EXAMPLE

MOTIVATION: DATAFLOW PROGRAMMING

$\text{fib} = 0 \text{ FBY } (\text{fib} + 1 \text{ FBY } \text{WAIT fib})$

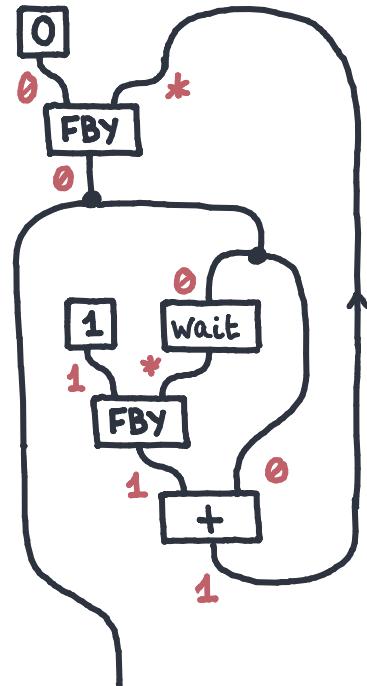
Time.	fib	WAIT(fib)	1FBYWAIT fib
0			
1			
2			
3			
4			
:			



MOTIVATION: DATAFLOW PROGRAMMING

$\text{fib} = 0 \text{ FBY } (\text{fib} + 1 \text{ FBY } \text{WAIT fib})$

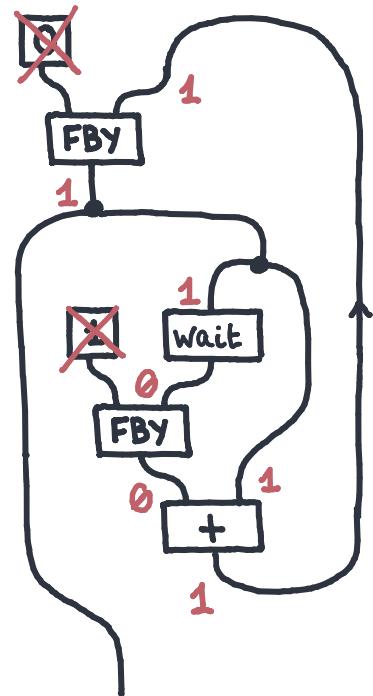
Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	
1			1
2			
3			
4			
:			



MOTIVATION: DATAFLOW PROGRAMMING

$\text{fib} = 0 \text{ FBY } (\text{fib} + 1 \text{ FBY } \text{WAIT fib})$

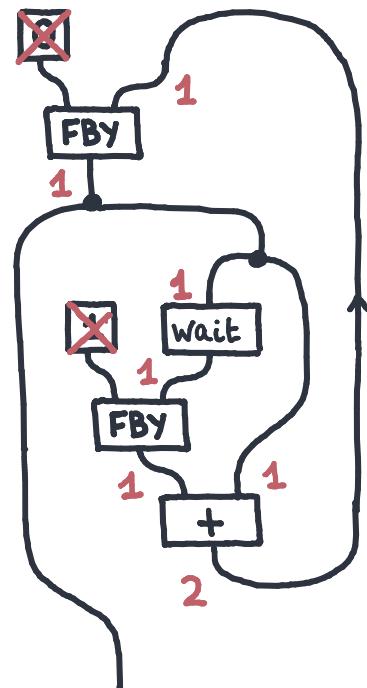
Time.	fib	WAIT(fib)	$1_{\text{FBYWAIT fib}}$
0	0	*	1
1	1	0	0
2			
3			
4			
:			



MOTIVATION: DATAFLOW PROGRAMMING

$\text{fib} = 0 \text{ FBY } (\text{fib} + 1 \text{ FBY } \text{WAIT fib})$

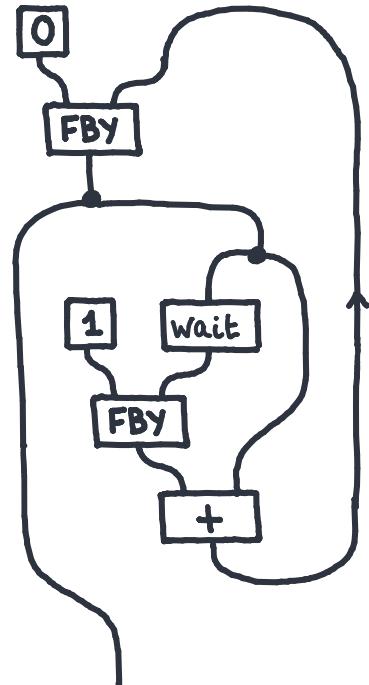
Time.	fib	WAIT(fib)	$1_{\text{FBYWAIT fib}}$
0	0	*	1
1	1	0	0
2	1	1	1
3			
4			
:			



MOTIVATION: DATAFLOW PROGRAMMING

$\text{fib} = 0 \text{ FBY } (\text{fib} + 1 \text{ FBY } \text{WAIT fib})$

Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1	1	0	0
2	1	1	1
3	2	1	1
4	3	2	2
:	:	:	:

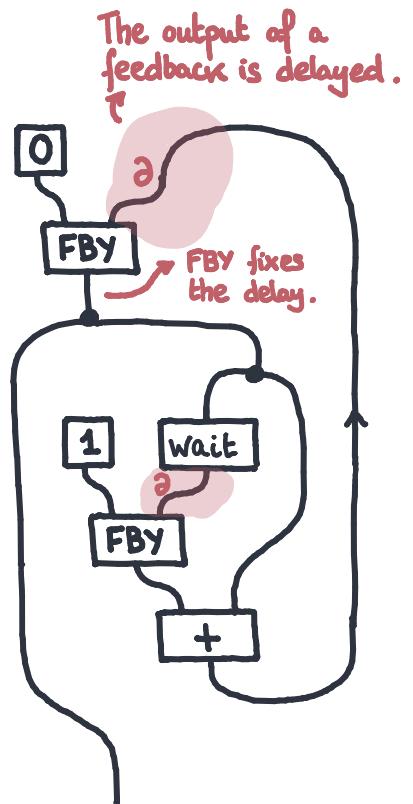


MOTIVATION: DATAFLOW PROGRAMMING

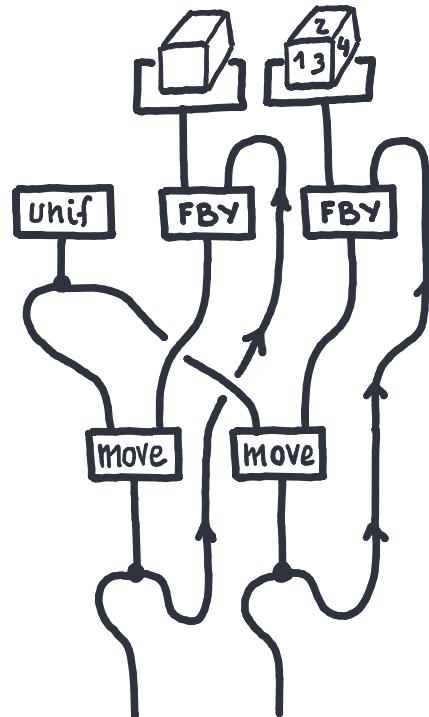
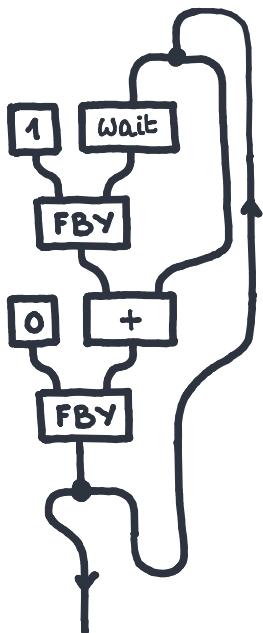
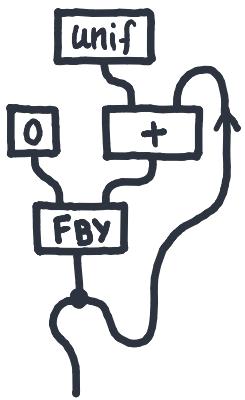
$\text{fib} = 0 \text{ FBY } (\text{fib} + 1 \text{ FBY } \text{WAIT fib})$

Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1	1	0	0
2	1	1	1
3	2	1	1
4	3	2	2
:	:	:	:

How to ensure the output is well-defined? **Delayed types.**



EXAMPLES



EXTRA : LENSES

DINATURALITY AND COENDS

Given $P: \mathcal{C}^{\text{op}} \times \mathcal{C} \rightarrow \text{SET}$, consider the set of all processes. $\sum_{x \in \mathcal{C}_{\text{obj}}} P(x, x)$.
Dinatural equivalence is the smallest equivalence relation generated by

$$P(\text{id}, r)(p) \sim P(r, \text{id})(p).$$

We write the set $\int^{x \in \mathcal{C}_{\text{obj}}} P(x, x)$ for $\sum_{x \in \mathcal{C}_{\text{obj}}} P(x, x)/\sim$, the **coend** of P .

“The coend, $\int^{x \in \mathcal{C}_{\text{obj}}}$, connects both X 's.”

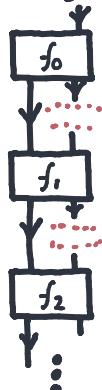
MOTIVATION

In the process interpretation of monoidal categories, morphisms $A \rightarrow B$ are processes with an **input A** and an **output B**.

However, most processes (servers, drivers, agents,...) are continuously taking inputs and producing outputs,



closed diagram vs



open^[1], repeated^[2] diagram.



Román.^[1] Open Diagrams via Coend Calculus. ACT'20.

Román.^[2] Comb Diagrams for Discrete-Time Feedback. Preprint.

MOTIVATION

Lenses can be used to describe a single exchange,

$$\text{Lenses}(A_0, A_1; B_0, B_1) = \int^M \text{hom}(A_0, B_0 \times M) \times \text{hom}(M \times A_1, B_1) \cong \text{hom}(A_0, B_0) \times \text{hom}(A_0 \times A_1, B_1);$$

but "fixpointing" the exchange, we get causal stream functions.

$$\text{Stream}(A; B) = \int^M \text{hom}(A_0, B_0 \times M) \times \text{Stream}(M \cdot A^+; B^+) = \text{hom}(A_0, B_0) \times \text{Stream}(A_0; A^+; B^+).$$

$$\text{Stream}(A; B) \cong \text{Optic}(\text{Set}, \text{Stream})((A_0, A^+); (B_0, B^+)).$$

Given the category Stoch of stochastic functions, the category of stochastic processes is the terminal fixpoint of

$$\text{StochProc}(A; B) \cong \text{Optic}(\text{Stoch}, \text{StochProc})((A_0, A^+); (B_0, B^+))$$

EXTRA : EXPRESSIVITY

EXPRESSIVITY

Orthogonal to the rest of the paper. What is the expressivity of the feedback syntax over some generators? The $\text{St}(\cdot)$ construction answers this.

- k -Linear functions: hidden multivariable linear recurrence equations.

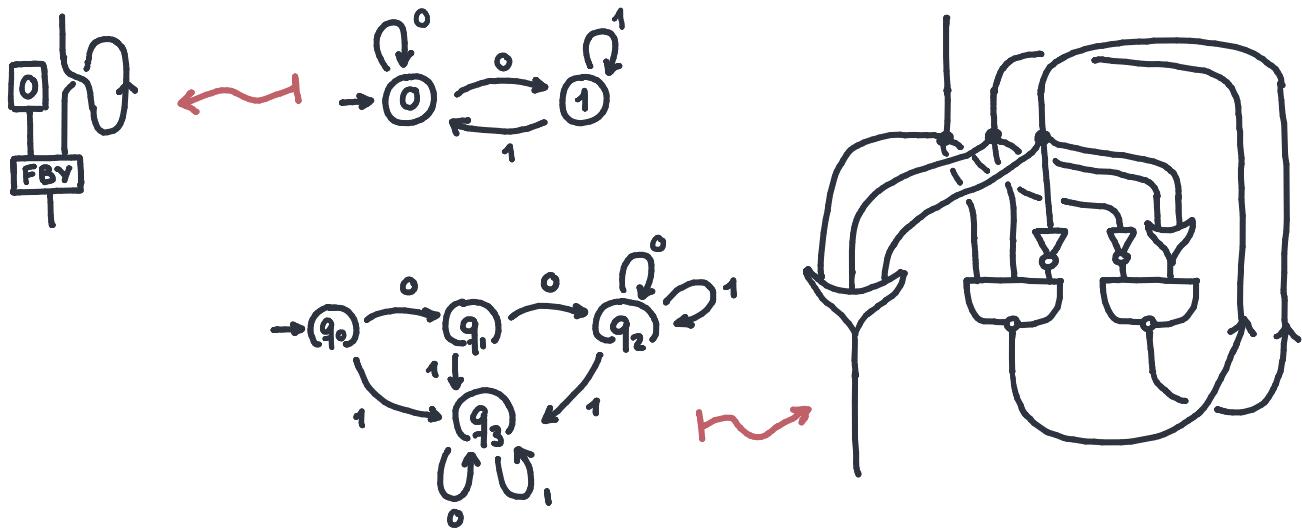
$$\begin{pmatrix} s_1 \\ \vdots \\ s_n \end{pmatrix}_{t+1} = \begin{pmatrix} \lambda_{11} & \dots & \lambda_{1n} & \mu_{11} & \dots & \mu_{1k} \\ \vdots & & \vdots & \vdots & & \vdots \\ \lambda_{n1} & \dots & \lambda_{nn} & \mu_{n1} & \dots & \mu_{nk} \end{pmatrix} \begin{pmatrix} s_1 \\ \vdots \\ s_n \\ a_1 \\ \vdots \\ a_k \end{pmatrix}_t$$

$$\begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}_t = \begin{pmatrix} \Psi_{11} & \dots & \Psi_{1n} & \Psi_{11} & \dots & \Psi_{1k} \\ \vdots & & \vdots & \vdots & & \vdots \\ \Psi_{n1} & \dots & \Psi_{nn} & \Psi_{n1} & \dots & \Psi_{nk} \end{pmatrix} \begin{pmatrix} s_1 \\ \vdots \\ s_n \\ a_1 \\ \vdots \\ a_k \end{pmatrix}_t$$

EXPRESSIVITY

Orthogonal to the rest of the paper. What is the expressivity of the feedback syntax over some generators? The $\text{St}(\cdot)$ construction answers this.

- Boolean circuits: controlled deterministic automata (w/ boolean IO).



EXPRESSIVITY

Monoidal streams over total relations can be interpreted as Büchi automata.

$$\textcircled{+} : A + A \rightarrow A \quad \text{merge}$$

$$\textcircled{\lrcorner} : 0 \rightarrow A \quad \text{unreachable}$$

$$\textcircled{\lrcorner} : A \rightarrow A + A \quad \text{choose}$$

$$\textcircled{x} : A \rightarrow A \quad \text{concat "x"}$$

$$\textcircled{\bullet} : A \rightarrow A \quad \text{token}$$

EXAMPLE: $0^*1(0^*11)^\omega$

Park's equations.

$$X \Rightarrow 0X + 1Y$$

$$Y \Rightarrow Z$$

$$Z \Rightarrow 0Z + 1W$$

$$W \Rightarrow 1Y$$

