Breaking records

Structural subtyping as a language design principle

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Introduction

• People use dynamically typed languages {Python, Lua, ...}.

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- Static typing is a great idea!
- \implies We should improve {optional} static type systems for those languages.

Duck typing is a common idiom in dynamic languages. We should aim to check it statically.

def quack(x):
 return x.quack()

Clearly, x needs to be an object with a quack method. Notionally:

 $\mathsf{x} \leqslant \{\texttt{quack}: () \rightarrow \alpha\}$

Quack!

We need this to work in more complex cases, e.g. involving higher-order functions:

```
def quack(x, is_duck):
    if random.randint(0, 1):
        f = lambda y: y.quack()
    else:
        f = lambda y: y.honk()
    return f(x)
```

x needs to have both a quack and a honk.

```
\mathsf{x} \leqslant \{\texttt{quack}: (\texttt{)} \rightarrow \alpha, \texttt{honk}: (\texttt{)} \rightarrow \alpha\}
```

Question. What typing discipline do we follow?

Nominal, structural, dynamic

In nominal type systems, we compare types by name.

In structural type systems, we compare types by defined **structure**.

```
let map (f : 'a -> 'b) (x : [< `None | `Some of 'a ]) =
match x with
| `None -> `None
| `Some x -> `Some (f x)
```

With dynamic typing, we only check types at runtime.

```
let map f x =
  match x with
  | `None -> `None
  | `Some x -> `Some (f x)
```

Claim. **Structural** type systems have a special role in statically typing existing dynamic languages.

- *Generally,* we can **translate** a nominally typed language to a structurally typed one by **erasing names**.
- Afterwards, **erase types** entirely to move to a dynamically typed language. For *well-behaved* programs, **type inference** can recover types.
- Moving along this gradient we make the type system less restrictive more programs type check.

nominal $\xrightarrow{\text{erase names}}$ structural $\xrightarrow{\text{erase types}}$ dynamic

Questions. Can these translations be formalised? Do they have an interesting form?

Contribution

Translation from **Featherweight Java** {Igarashi et al.} into a structurally typed **record calculus** {Cardelli and Mitchell}.

The source and target languages of this translation serve as **prototypical languages**:

- **FJ** {a core calculus of Java} nominally typed OOP language.
- Record calculus language with structurally typed records.
- Untyped record calculus dynamic OOP lang. {a core of Python, Lua, JavaScript, ...}.

All of these rely on a notion of subtyping ($A \leq B$ – an A can be used in place of a B).

Here is a simple example program in Featherweight Java:

```
class Bird extends Object {
    String name;
    Bird(String name) { super(); this.name = name; }
    String name() { return this.name; }
}
class Duck extends Bird {
    Duck(String name) { super(name); }
    String quack() { return "quack"; }
}
```

(new Duck("mallard")).quack()

Break on through

Translation preserving well-typedness into record calculus – λ calculus with extensible records { $\{\ell = e \mid r\}$ updates r with $\ell = e$ }. The translation uses a prototype-based style.

$$Object_{proto} = \{\}$$

 $Object = \lambda o. \lambda(). o$

$$Bird_{proto} = \{name = \lambda this. \lambda(). this.name\}$$

Bird = $\lambda o. \lambda name. \{name = name \mid Object o()\}$

 $\begin{aligned} \text{Duck}_{\text{proto}} &= \{ \text{quack} = \lambda \text{this. } \lambda(). \text{"quack"} \mid \text{Bird}_{\text{proto}} \} \\ \text{Duck} &= \lambda o. \, \lambda \text{name. Bird } o \text{ name} \\ \text{Duck}_{\text{quack}} &= \lambda o. \, o. \text{quack } o() \end{aligned}$

Duckquack (Duck Duckproto "mallard")

We have seen we can usefully translate from nominal to structural typing. Ponder. Why are types in static languages mostly nominal?

Nominal types are a convenient assumption.

- It is natural to give names to things.
- Can be what you want {e.g. primitives} want nominal and structural {Binder et al.}.
- Easier type inference unification, Hindley-Milner.

Structural typing, especially in the presence of **subtyping**, is tricky to include in a language – it introduces **complexity**.

Question. What abstraction helps us manage this complexity?

Algebraic subtyping

Subtyping \leq is a partial order on types τ .

We usually consider type systems with an implicit coercion rule:

$$\frac{\Gamma \vdash e : \tau \quad \tau \leqslant \tau'}{\Gamma \vdash e : \tau'}$$

In algebraic subtyping, we consider \leq which form a *distributive lattice* algebra – we have a meet \land (least upper bound) and join \lor (greatest lower bound) with axioms.

$$\tau \leqslant \tau' \iff \tau = \tau \wedge \tau' \iff \tau' = \tau \vee \tau'$$

Nice algebraic properties lead us to nice properties of the type system: like ML-style principal type inference {orig. due to Dolan in **MLsub**; Parreaux: simple(r) constraint solving}.

 τ

(top, bottom)	$::= \top \mid \bot$
(primitives)	int $ $ float
(functions)	$ \tau \to \tau$
(records)	$ \{\ell : \tau, \dots \}$

au	π	$\tau \wedge \pi$	$\tau \vee \pi$
int	int	int	int
int	float	\perp	Т
$\mathrm{int} \to \mathrm{int}$	$\bot \to \top$	$\operatorname{int} \to \operatorname{int}$	$\bot \to \top$
$\{\ell: \mathrm{int}\}$	$\{\ell': \mathrm{float}\}$	$\{\ell : int, \ell' : float\}$	{}
$\{\ell: \mathrm{int}\} \to \mathrm{int}$	$\{\ell':\mathrm{float}\}\to\top$	$\{\} \to \mathrm{int}$	$\{\ell: \mathrm{int}, \ell': \mathrm{float}\} \to \top$

$$\Gamma \vdash e : \tau$$

Type inference from a Curry-Howard perspective: what is the statement τ proven by e? Determine constraint system for expression e, then find general solution for its type τ . Sketch of constraint solver {Pottier; Parreaux}:

- Intro type variables α, β, \ldots and track bounds $\alpha_{lo} \leq \alpha \leq \alpha_{hi}$ (constraint graph).
- Factor: $a \lor b \leqslant c \iff (a \leqslant c) \& (b \leqslant c) \text{ and } a \leqslant b \land c \iff (a \leqslant b) \& (a \leqslant c).$
- Take transitive closure: $(a \leq b) \& (b \leq c) \implies a \leq c$. Check $\alpha_{lo} \leq \alpha_{hi}$.

expression e	\rightsquigarrow	constraints c	\rightsquigarrow	type $ au$
expression e $\lambda x. \text{ if } x. \text{flag}$ then $x. \text{foo}$ else $x. \text{bar} + x. \text{baz}$	~~	$constraints c$ $x \leq \{ flag : \beta \}$ $\beta \leq bool$ $x \leq \{ foo : \iota \}$ $x \leq \{ bar : \iota_1 \}$ $x \leq \{ bar : \iota_2 \}$	~>	flag : bool, foo : ι , bar : int, baz : int} $\rightarrow \iota \lor int$
		$ \begin{bmatrix} \iota_1, \iota_2 \leqslant \text{int} \end{bmatrix} $		

There are limitations {Dolan's MLsub}: the polarity restriction.

Recent work {Parreaux's MLstruct} improves on this by considering a Boolean lattice.

However, we still cannot type common record operations (in FJ translation!) without **row polymorphism**, as done for systems without subtyping {preliminarily: Marques et al.}.

Type inference with lattice homomorphisms

Contribution

(Meta)functions on types – **type lattice homomorphisms** with "adjoints" – work in type inference \implies can infer types for extensible records via $\operatorname{drop}_{\ell}$ homomorphisms:

$$drop_{foo}(\{foo:int, bar: float\}) = \{bar: float\}$$

Example. Take the flag field of a record *a* and update it to the result of not: $\diamond \vdash \lambda a. \{ \text{flag} = a.\text{flag.not}() \mid a \setminus \text{flag} \}$ $: \alpha \land \{ \text{flag} : \{ \text{not} : () \rightarrow \nu \} \} \rightarrow \text{drop}_{\text{flag}}(\alpha) \land \{ \text{flag} : \nu \}$

 $\{\{\ell = e \mid r\} \text{ extends } r \text{ with } \ell = e; r \setminus \ell \text{ removes } \ell \text{ from } r.\}$

Future work. General, constraint-based formulation of type inference for algebraic subtyping with this extension – prior art focuses on specific cases.

Language design – Fabric

Fabric

- purely functional imperative mutability is hard as always!
- statically typed with a focus on structural types and subtyping
- features usual extensible records and variants, and richer arrays.
- admits ML-style type inference thanks to algebraic subtyping.
- compiles to WEBASSEMBLY.

Principle. Replicate flexibility of dynamic languages, but safely (structural subtyping).

Goal. Extend existing languages - or their tooling - with Fabric's features.

Prototype compiler in OCaml, making ideas come to life.

- I implemented Parreaux's Simple-sub/MLstruct-style algebraic subtyping type inference. Difficulty: type simplification.
- WEBASSEMBLY code generation using the Binaryen toolchain (now with GC!). Can optimize and lower further to native code. Difficulty: unstable toolchain.

WebAssembly is a modern portable target with interesting verification/design work.

Future work. Investigate performance implications of different runtime representations for record and variant types, which admit structural subtyping.

Structuring arrays

We look at **array programming** as a practical reason for revisiting structural typing. Array programs might look like this (matrix multiplication):

$$C = \Phi i. \Phi j. \Sigma k. A[i, k] \cdot B[k, j]$$

$$C = \text{sum}^{(1)} \left(\text{expand}^{(2)}(A) \cdot \text{expand}^{(0)}(B) \right)$$

$$C = \text{map} A \left(\lambda a. \text{map} B^T \left(\lambda b. \text{sum} \left(\text{map}_2 \left(\times \right) a b \right) \right) \right)$$
(combinator-based)

Type checking array programs is tricky. There are array type systems, but most resort to dependent types {type-level arithmetic}. Practitioners stick to blissful untypedness.

Question. Can structural typing help construct a type system for array programming?

Existing systems rely on *n*-dimensional arrays (tensors) – a *shape* is a tuple of integers.

$$\mathrm{shape} \, \begin{bmatrix} (0,0) & (0,1) & (0,2) \\ (1,0) & (1,1) & (1,2) \end{bmatrix} = (2,3)$$

Contribution

Novel array calculus: **Star**. Features algebraic, structurally typed array shapes, admitting ML-style type inference via algebraic subtyping.

Key idea. **product** $\{|\ell: s, \ell': s', \ldots|\}$ and **concatenation** $[[T: s, T': s', \ldots]]$ shapes – closely tied to structural record and variant types, which are used for indexing.

Under review for ARRAY 2025.

An array of shape of type:

 $\{ \operatorname{Irow} : \llbracket \operatorname{Top} : \#, \operatorname{Mid} : \#, \operatorname{Bot} : \# \rrbracket, \operatorname{col} : \llbracket \operatorname{Left} : \#, \operatorname{Mid} : \#, \operatorname{Right} : \# \rrbracket \}$

is indexed by values of the type of records-of-variants (e.g. $\{row : Top 5, col : Mid 4\}$):

 $\{row: [Top:int, Mid:int, Bot:int], col: [Left:int, Mid:int, Right:int]\}$

We can visualise this shape as a *padded matrix*, composed of 9 regions:

This is much more familiar than tracking a shape (t + n + b)(l + m + r) (polynomial!).

Conclusions

- **Structural subtyping** is a promising direction to *revisit* for designing optional static type systems for dynamic languages formalise why via translations.
- Algebraic subtyping would enable type inference for such type systems. We can find novel extensions, and e.g. type records with type lattice homomorphisms.
- **Designing languages** like Fabric is a useful way of playing around with extensions for existing systems, even if the language is not meant for practical use.
- **Revisiting old problems** and rephrasing them can be good there is an interesting structural type system for array programs, without dependent types.

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Thank you!