A declarative approach to specifying distributed algorithms using three-valued modal logic,

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Decentralised algorithms as axiom-systems

Decentralised algorithms are algorithms that run across a system of participants, without central control.

I may use 'decentralised' and 'distributed' synonymously, but they're not: distributed algorithms may still be centrally controlled.

Either way, decentralised/distributed algorithms are hard: hard to design; hard to understand; and hard to verify.

Blockchain consensus algorithms are decentralised. Academic examples include Paxos and Bracha Broadcast.

I've been studying how to represent these algorithms *declaratively* as *axiomatic theories*, thus capturing their logical structure in a new, high-level way.

I have found this personally helpful for understanding decentralised algorithms. It has also been applied to detect two errors in the proposed Heterogeneous Paxos protocol.

By the end of this talk, I hope you'll have a flavour of what *declarative Bracha Broadcast* looks like.

An axiomatisation of Paxos is submitted for publication: A declarative approach to specifying distributed algorithms using three-valued modal logic https://arxiv.org/abs/2502.00892.



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I present Bracha Broadcast here for brevity; the treatment of Paxos is just a matter of scaling up.

A toy protocol

Fix a pair (P, Open) of a set of participants P and a set of quorums Open \subseteq powerset(P). Secretly, this is a semitopology — we'll come back to that.

Toy is as follows:

- 1. *Propose.* Any participant *p* may broadcast a propose message to all participants.
- 2. Accept. If a participant receives a propose message, then it responds with accept.
- 3. *Decide.* If the participant *p*, having broadcast its propose message, receives an accept message, then it declares decide.

(I made this up; it's loosely based on a 1-value version of Paxos.)

Background 1. Modal logic

We will model **Toy** using a modal logic, meaning that the truth-value of a predicate depends on a *possible world*, which consists of a time and/or a place. For example:

"It's raining" is a predicate.

"It's raining *now*" and "It's raining *here*" are modal predicates, because validity depends on the time and place.

"It's raining *somewhere*" is modal: this is typically written as \$\\$raining.

"It's raining *everywhere*" is modal: this is typically written as □raining.

For **Toy**, the possible worlds are participants $p \in P$ (no time; just places).

More formally: the truth-value $[\phi]_w$ is a function of ϕ and w. Write $w \models \phi$ for ' $[\phi]_w$ is a valid truth-value'.

Background 2. Three-valued (modal) logic

We will use *three* truth-values:

1.
$$\mathbf{t}$$
 ('true'). If $[\phi]_w = \mathbf{t}$ then call ϕ true at w .
2. \mathbf{f} ('false'). If $[\phi]_w = \mathbf{f}$ then call ϕ false at w .
3. \mathbf{b} ('byzantine'). If $[\phi]_w = \mathbf{b}$ then call ϕ byzantine at w .
Call $x \in {\mathbf{t}}$ true, $x \in {\mathbf{t}}, \mathbf{f}$ correct, and $x \in {\mathbf{t}}, \mathbf{b}$ valid.
For x a truth-value, define modalities \mathbb{T} , \mathbb{T} , and \mathbb{B} by:
 $\mathbb{T} x = \mathbf{t}$ when $x \in {\mathbf{t}}$ and $\mathbb{T} x = \mathbf{f}$ otherwise;

- $\mathbb{T} x = \mathbf{t}$ when $x \in {\mathbf{t}, \mathbf{f}}$ and $\mathbb{T} x = \mathbf{f}$ otherwise; and
- ▶ $\mathbb{B} x = \mathbf{t}$ when $x \in {\mathbf{t}, \mathbf{b}}$ and $\mathbb{B} x = \mathbf{f}$ otherwise.

Write $w \vDash \phi$ to mean $[\phi]_w \in \{\mathbf{t}, \mathbf{b}\}$. Write $\vDash \phi$ to mean $\forall w.w \vDash \phi$.

Recall Toy

We have participants P and a quorums Open \subseteq powerset(P).

- 1. *Propose.* Any participant *p* may broadcast a propose message to all participants.
- 2. Accept. If a participant receives a propose message, then it responds with accept.
- 3. *Decide.* If the participant *p*, having broadcast its propose message, receives an accept message, then it declares decide.

Let's make this declarative. We propose *three* theories (= set of axioms), corresponding to failure assumptions as follows:

- 1. all participants honest (non-byzantine) and live (uncrashed),
- 2. all participants honest & a quorum of live participants,
- 3. a contraquorum *(defined in later slide)* of live honest participants.

Theory 1. Honest & live

Assume atomic propositions propose, accept, and decide.

Backward rules(SimpAccept?)accept \rightarrow \Diamond propose(SimpDecide?)decide \rightarrow (propose $\land \Diamond$ accept)Forward rules(\Diamond propose) \rightarrow accept(SimpAccept!)(\Diamond propose) \rightarrow accept(SimpDecide!)(propose $\land \Diamond$ accept) \rightarrow decideOther rules(Correct)T [propose, accept, decide]

 $p \vDash \phi \twoheadrightarrow \phi'$ means $p \vDash T \phi \Rightarrow p \vDash T \phi'$ (if ϕ is true then ϕ' is true; material implication). $p \vDash \Diamond \phi$ means $\exists p'.p' \vDash \phi$. (ϕ is valid somewhere). A model (= assignment of truth-values to atomic propositions) satisfies a theory \mathcal{T} when $\vDash (\mathbf{Ax})$ in that model, for every $(\mathbf{Ax}) \in \mathcal{T}$. Theory 2. Quorum of live participants

Backward rules(SimpAccept?) $accept \rightarrow \Diamond propose$ (SimpDecide?) $decide \rightarrow (propose \land \Diamond accept)$ Forward rules($\Diamond propose$) $\rightarrow accept$ (SimpAccept!)($\Diamond propose$) $\rightarrow accept$ (SimpDecide!)($propose \land \Diamond accept$) $\rightarrow decide$ Other rules $\Box \mathbb{F}$ [propose, accept, decide]

$$p \vDash \phi \twoheadrightarrow \phi' \text{ means } p \vDash T \phi \Rightarrow p \vDash T \phi'$$

$$p \vDash \phi \to \phi' \text{ means } p \vDash T \phi \Rightarrow p \vDash T \phi'$$

$$p \vDash \phi \to \phi' \text{ means } \exists p'.p' \vDash \phi.$$

$$p \vDash \phi \text{ means } \exists O \in \text{Open.} \forall p' \in O.p' \vDash \phi.$$

$$(\phi \text{ valid on some quorum}).$$

Theory 3. Contraquorum of honest participants

$$p \vDash \phi \to \phi' \text{ means } p \vDash T \phi \Rightarrow p \vDash \mathbb{B} \phi'$$
$$p \vDash \Diamond \phi \text{ means } \exists p'.p' \vDash \phi.$$
$$p \vDash \odot \phi \text{ means } \exists O \in \text{Open.} \forall p' \in O.p' \vDash \phi.$$

Background: quorums, coquorums, & contraquorums

Recall the semitopology (P, Open) (pprox quorum system) .

- Call $O \in Open$ an open or a quorum.
- Call C ⊆ P closed or a coquorum when C = P \ O for some O ∈ Open.
- Call D ⊆ P dense or a contraquorum when D ∩ O ≠ Ø for every nonempty O ∈ Open (also called a *blocking set*). This is exactly the notion of *dense set* from topology.

In the case that #P = 3f + 1 and $O \in Open$ when O is empty or $\#O \ge 2f + 1$,

C ⊆ P is closed precisely when C = P or #C ≤ f, and
 D ⊆ P is dense precisely when #D ≥ f + 1.

Background: quorums, coquorums, & contraquorums

Have you seen the papers on distributed systems that talk about

- taking a set of participants having size 3f + 1; and then
- quorums are sets of size at least 2f + 1;
- failure sets have size at most f; and
- blocking sets have size at least f + 1, and so on?

These are *topological notions*, corresponding to open sets, closed sets, and dense sets respectively.

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They're doing (semi)topology.

Bracha Broadcast (high-level view)

- A designated sender participant *broadcasts v* to all processes. (We assume all messages arrive.)
- If a participant receives a broadcast v message from the sender — we assume the sender's signature can't be forged — it sends an *echo* v to all processes.

Each participant will echo at most *once*, so if it receives two broadcast messages with different values from a (byzantine) sender, it will only echo one of them.

- If a participant receives a quorum of echo messages for a value v, or a contraquorum of ready messages for a value v, then it sends messages to all processes declaring itself *ready* with v.
- 4. If a process receives a quorum of ready messages for a value v, then the participant *delivers* v.

Declarative Bracha Broadcast

Backward rules (BrDeliver?) (BrReady?) (BrEcho?) Forward rules (BrDeliver!) (BrReady!) (BrEcho!) (BrReady!!) Other rules (BrEcho01) (BrBroadcast1) (BrCorrect) (BrCorrect') (BrCorrect'')

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 \begin{array}{l} \text{dlvr}(v) \rightarrow \boxdot \text{ready}(v) \\ \text{ready}(v) \rightarrow \boxdot \text{echo}(v) \\ \text{echo}(v) \rightarrow \text{brdcst}(v) \end{array}
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 \begin{array}{l} \hline \texttt{ready}(v) \rightarrow \texttt{dlvr}(v) \\ \hline \texttt{echo}(v) \rightarrow \texttt{ready}(v) \\ \Diamond \texttt{brdcst}(v) \rightarrow \texttt{echo}(v) \\ \Diamond \texttt{ready}(v) \rightarrow \texttt{ready}(v) \end{array}
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∃₀ıv.echo(v)
∃ıv.◊brdcst(v)
⊡ 𝔅 [ready,echo,brdcst]
𝔅 [P] ∨ 𝔅 [P] (P ∈ {ready,echo})
□ 𝔅 [brdcst] ∨ □𝔅 [brdcst]
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Some notation

 $\exists_{\mathbf{01}} v.\phi(v) \text{ is shorthand for } \forall v, v'.\phi(v) \rightarrow \phi(v') \rightarrow v = v'.$

- This means $\phi(v)$ is **t** for *at most* one *v*.
- $\phi(v)$ can be **f** or **b** for as many v as it wants!
- In particular, ∃₀₁ v.b is valid.

 $\exists_1 v.\phi(v)$ is shorthand for $\exists_{01} v.\phi(v) \land \exists v.\phi$.

- This means φ(v) is t for at most one v, and is [™] for at least one v.
- ▶ In particular, $\exists_1 v. \mathbf{b}$ is valid (specifically, $[\exists_1 v. \mathbf{b}]_w = \mathbf{b}$ always).

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Correctness properties (informal; from literature)

These correctness properties for Bracha Broadcast are from pages 112 and 117 of *Introduction to reliable and secure distributed programming* (2nd ed):

- 1. Validity: If a correct process broadcasts some value v, then every correct process delivers v.
 - The meaning of 'Correct' is not made immediately formal in the source citation.
- 2. No duplication: Every correct process delivers at most one value.
- 3. Integrity: If some process delivers a message v with sender p, and p is correct, then v was broadcast by p.
- 4. Consistency: If one correct process delivers v and another correct process delivers v', then v = v'.
- 5. Totality: If some correct process delivers v, then every correct process delivers v.

3-twined, axiomatically

Recall that a semitopology consists of a pair (P, Open) of a set of points P and a set of open sets Open $\subseteq pow(P)$.

Call a semitoplogy 3-twined when any three nonempty open sets intersect (also called Q^3 ; see e.g. Definition 2 here).

Lemma: The following are equivalent [Lemma 5.3.1(2)]:

- 1. (P, Open) is 3-twined.
- 2. $\models (\Box \phi \land \Box \psi \land \Box \chi) \Rightarrow \Diamond (\phi \land \psi \land \chi) \text{ (for any } \phi, \psi, \text{ and } \chi).$
- 3. $\models (\Box \phi \land \Box \psi) \Rightarrow \diamondsuit (\phi \land \psi).$
- 4. $\models (\boxdot \mathbb{T} \phi \land \boxdot \phi) \Rightarrow \mathbb{T} \diamondsuit \phi$. Correct on a quorum and valid on a quorum implies true on a contraquorum!
- $p \vDash \Box \phi$ means $\exists O \in \text{Open}. \forall p' \in O. p' \vDash \phi$.

$$p \vDash \phi \Rightarrow \phi'$$
 means $p \vDash \mathbb{B} \phi \Rightarrow p \vDash \mathbb{B} \phi'$
(if ϕ is valid then ϕ' is valid).

Correctness properties (in the logic)

Theorem: Any model of Declarative Bracha Broadcast over a 3-twined semitopology satisfies:

Validity: $\models \Diamond brdcst(v) \rightarrow \Box dlvr(v)$ No duplication: $\models \exists_{01}v.dlvr(v)$ Integrity: $\models dlvr(v) \rightarrow \Diamond brdcst(v)$ Consistency: $\models \exists_{01}v.\Diamond dlvr(v)$ Totality: $\models \Diamond dlvr(v) \rightarrow \Box dlvr(v)$

Note: I don't explicitly represent messages! There are modal predicates evaluating to truth-values. *Note:* p in the informal integrity property corresponds to \Diamond in (Integrity) above. *Note:* asymmetry between (Validity) and (Integrity). *Note:* (BrBroadcast01).

Conclusions

We can present decentralised algorithms as axiomatic theories.

Paragraphs of English text get distilled down to *precise axiomatic assertions*. Difficult reasoning gets reduced to, or at least formalised as, formal logical reasoning.

It's a powerful technique. Axiomatic reasoning is not new, but nobody's thought of doing it in this way for consensus.

... and it works! I find it indispensable for my own understanding, and it's already helped to catch real bugs.

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References

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