

Creating Synthetic Test Data for Rail Design Tools

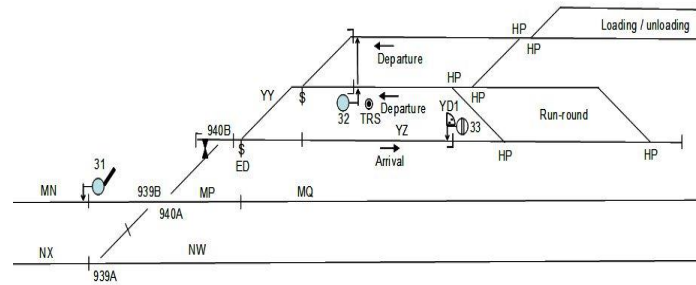
Marek Jezinski

Supervised by: Dr Monika Seisenberger & Professor Markus Roggenbach

Swansea University, Swansea, Wales

Co-funded by Siemens Mobility and UKRI

Terminology



Scheme Plan

Source: Adapted from [1]



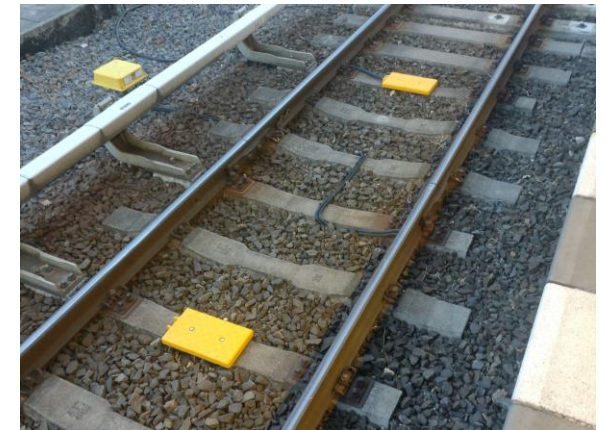
Scheme Plan

Own work



Points

Public domain



Balise(s)

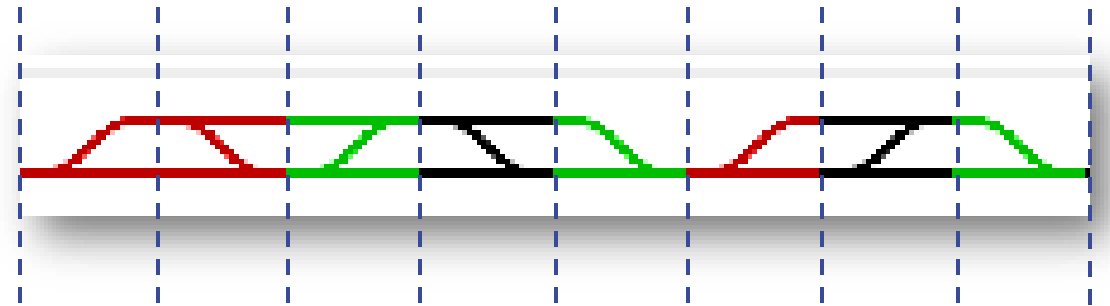
Source: Adapted from [2]

Aim and Motivation

- **Aim:** Generating synthetic railway scheme plans with injected errors at known positions.
- **Motivation:** Scheme plans are labour-intensive to produce manually.
- **Method:** Genetic Algorithm implemented in Python.
- **Purpose:** Testing Rail Design tools, e.g., Siemens' Data Checker [3], Ovado [4, 5] and Luterberget junction tool suite [6]. Later called **System Under Test (SUT)**.
- **Error-Notion:** Violation of ETCS design rules such as "spacing shall be constrained by $\geq 1.0\text{m}$ of distance between **balise** and point toes".

The Basic Principle

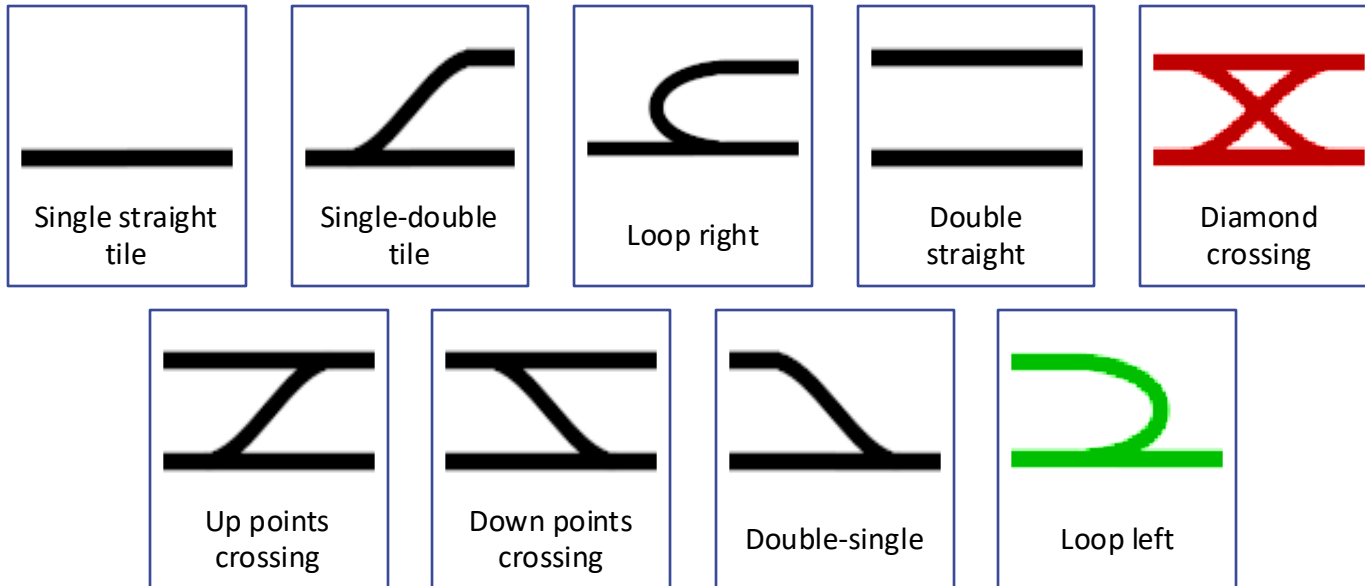
Genetic Algorithm Settings	
Segments	25
Pop Size	25
Tournament Size	4
Selection Count	15
Crossover Rate	0.8
Mutation Rate	0.2
GA Stop Condition	
Avg. Fitness Boundary Value	0.85
Scheme Plan Settings	
Complexity Rate	1.0
Correct Balises	2
Incorrect Balises	2
Passing Loops	4
Loops	2



Input: length n of a 'linear track', number of correct & incorrect balises, passing loops count, ...

Output: set of sequences of n tiles, evaluated to be the best solutions

Scheme Plans, Error Injection and Genetic Algorithms

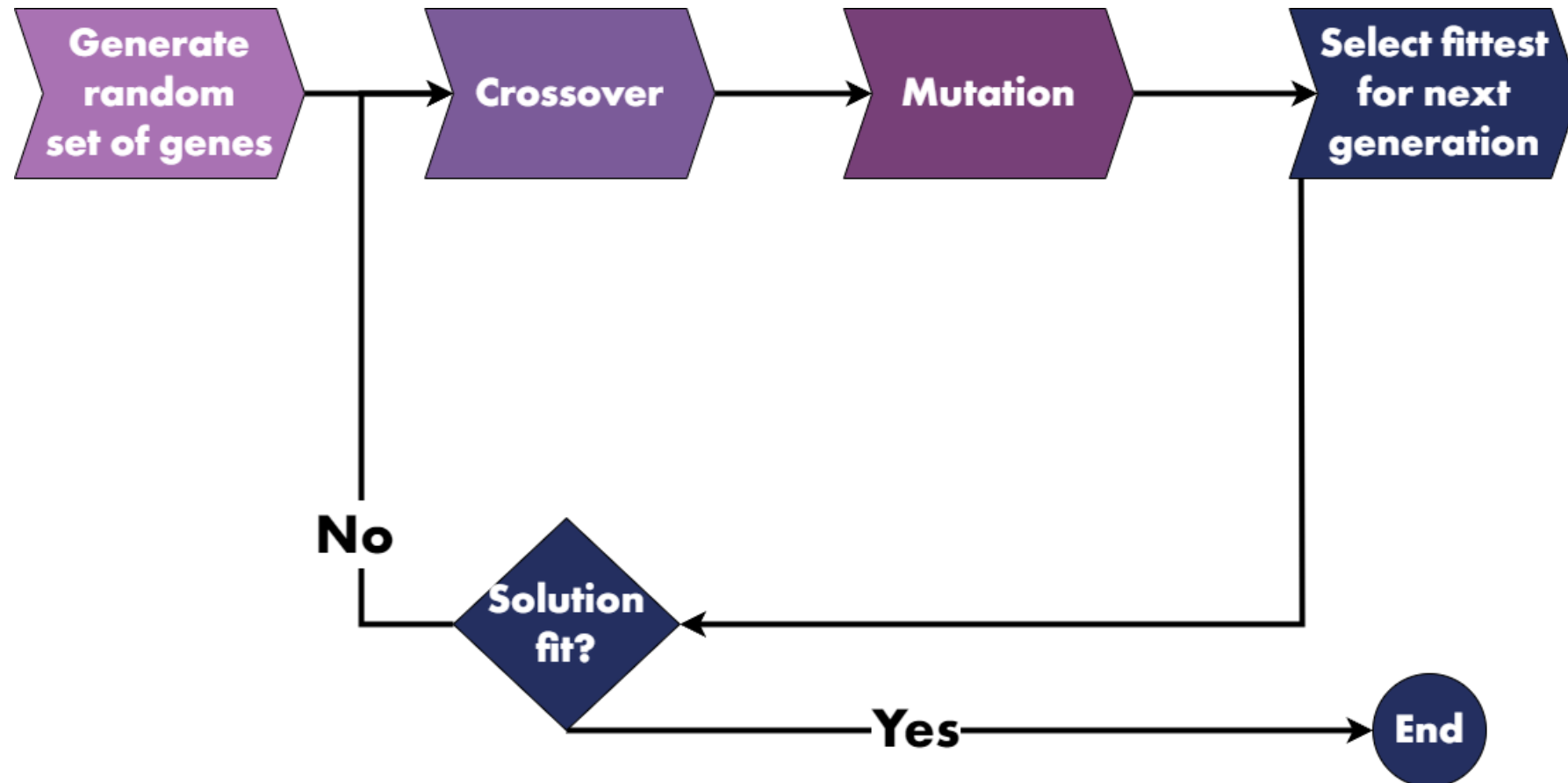


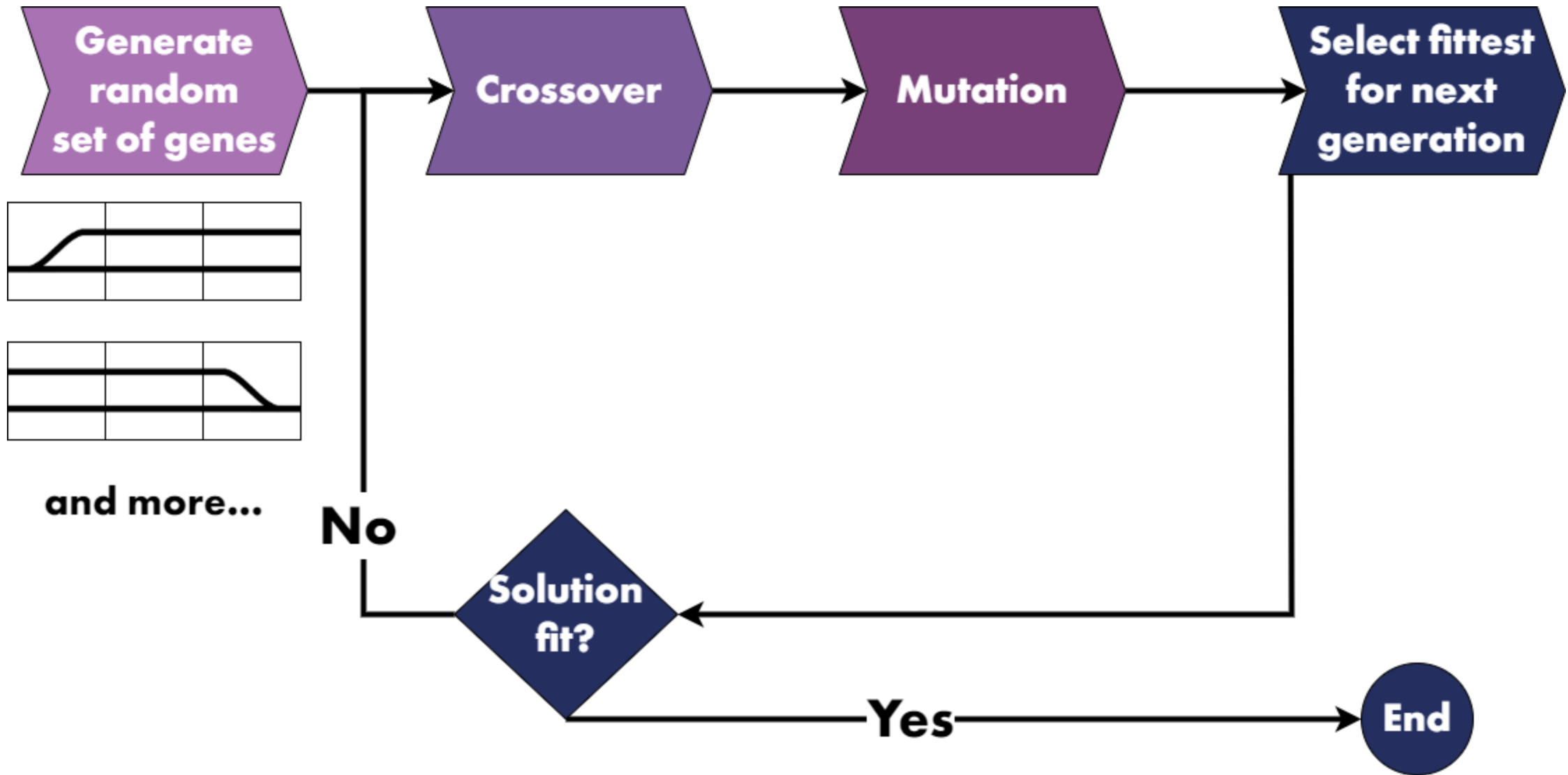
Example tiles

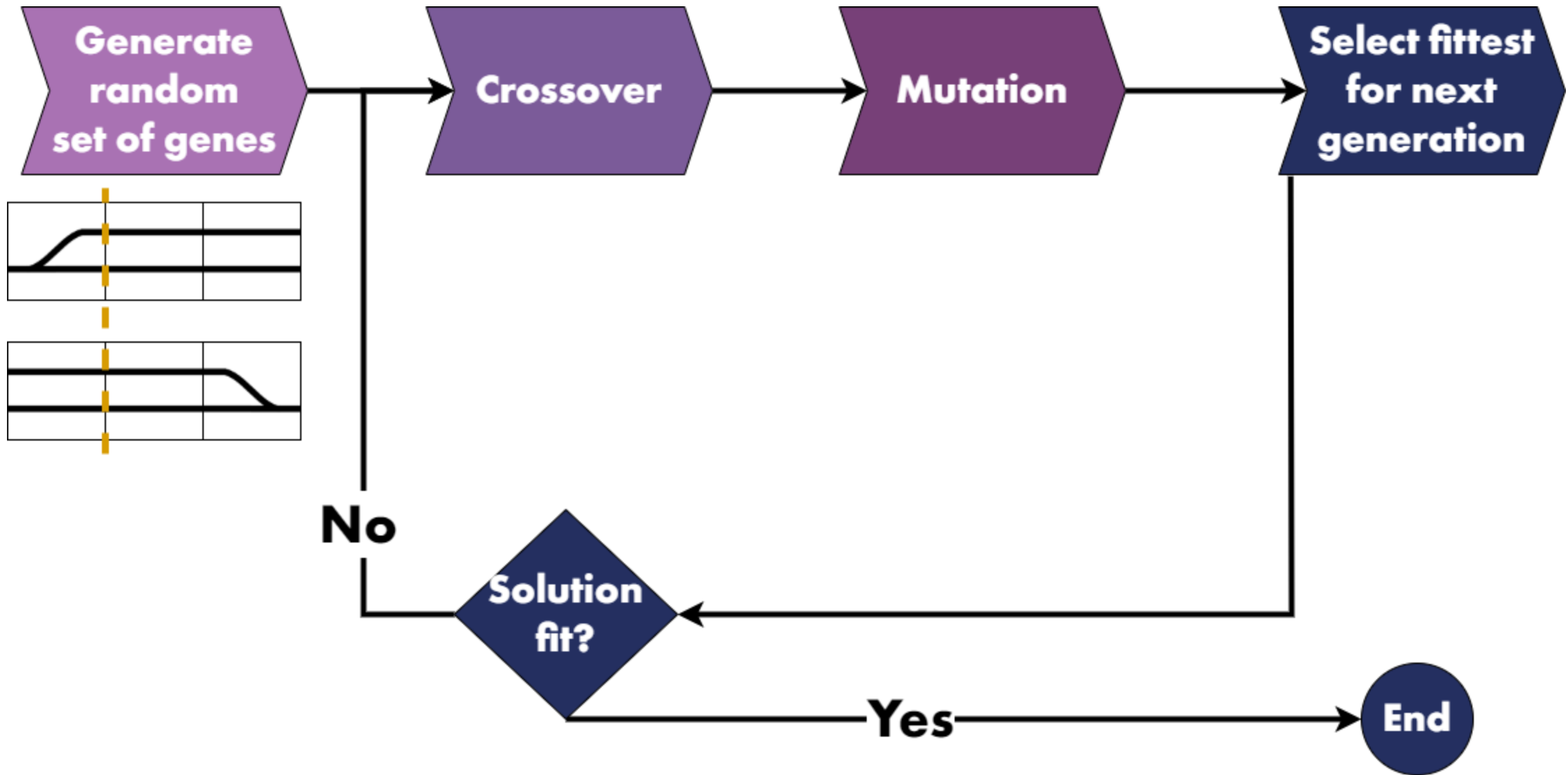
Tiles linked together create a visualisation of a scheme plan with passing loops. Later called “**genes**”.

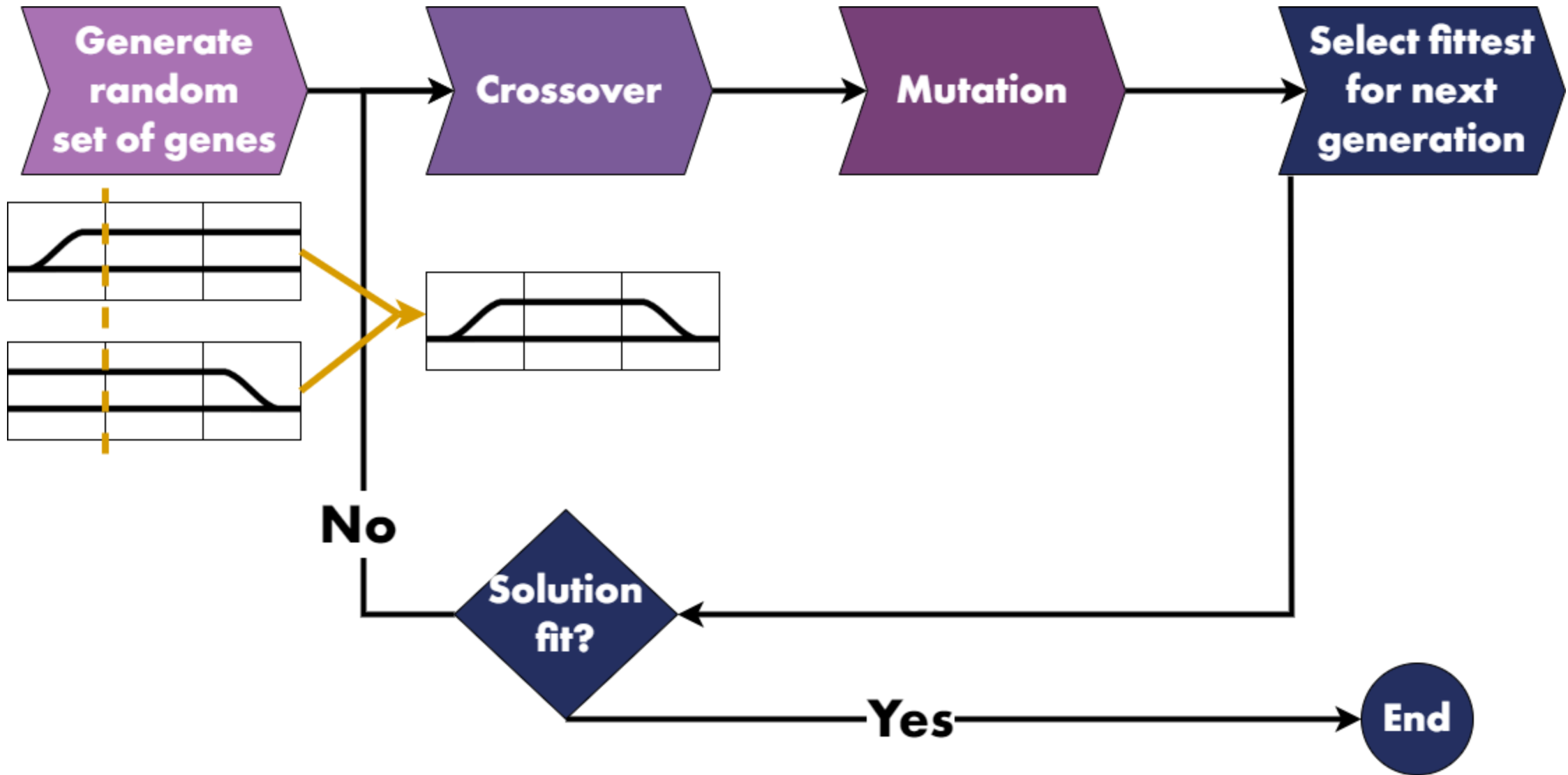
Black - no balises, **green** - rule obeyed (correct balises injected), **red** - rule violated (errors injected).

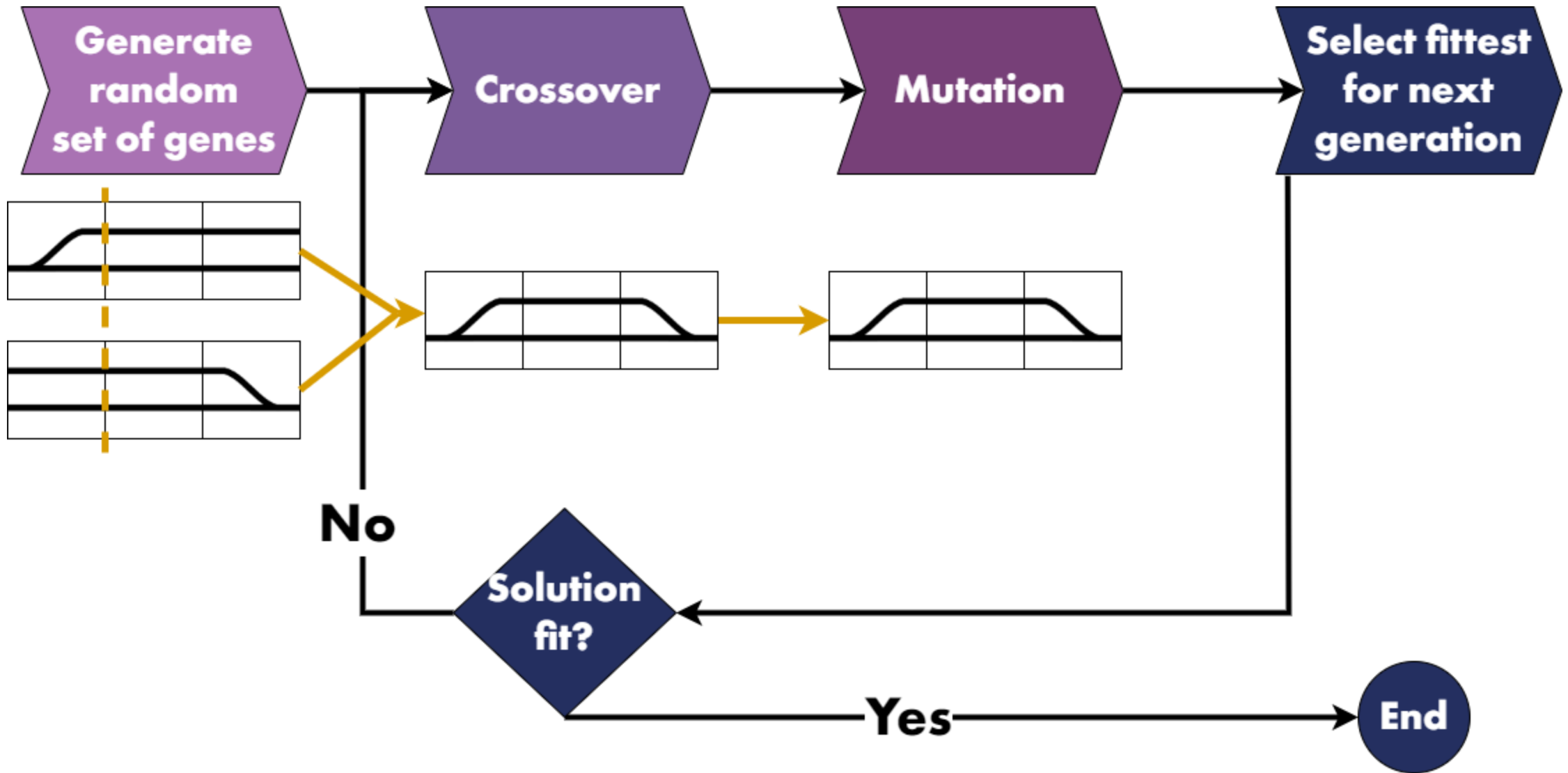
Method for Test Case Generation – Genetic Algorithms

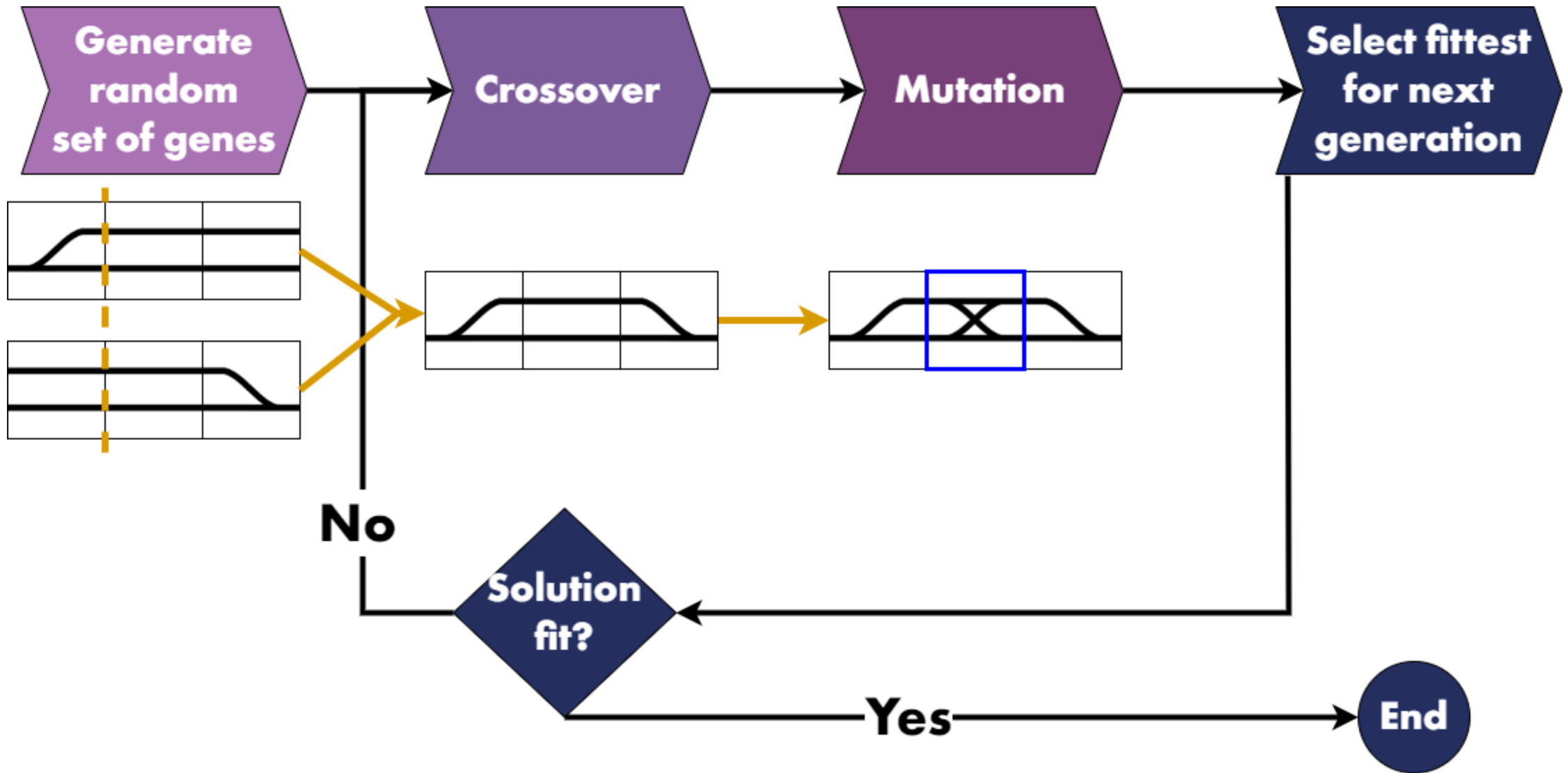


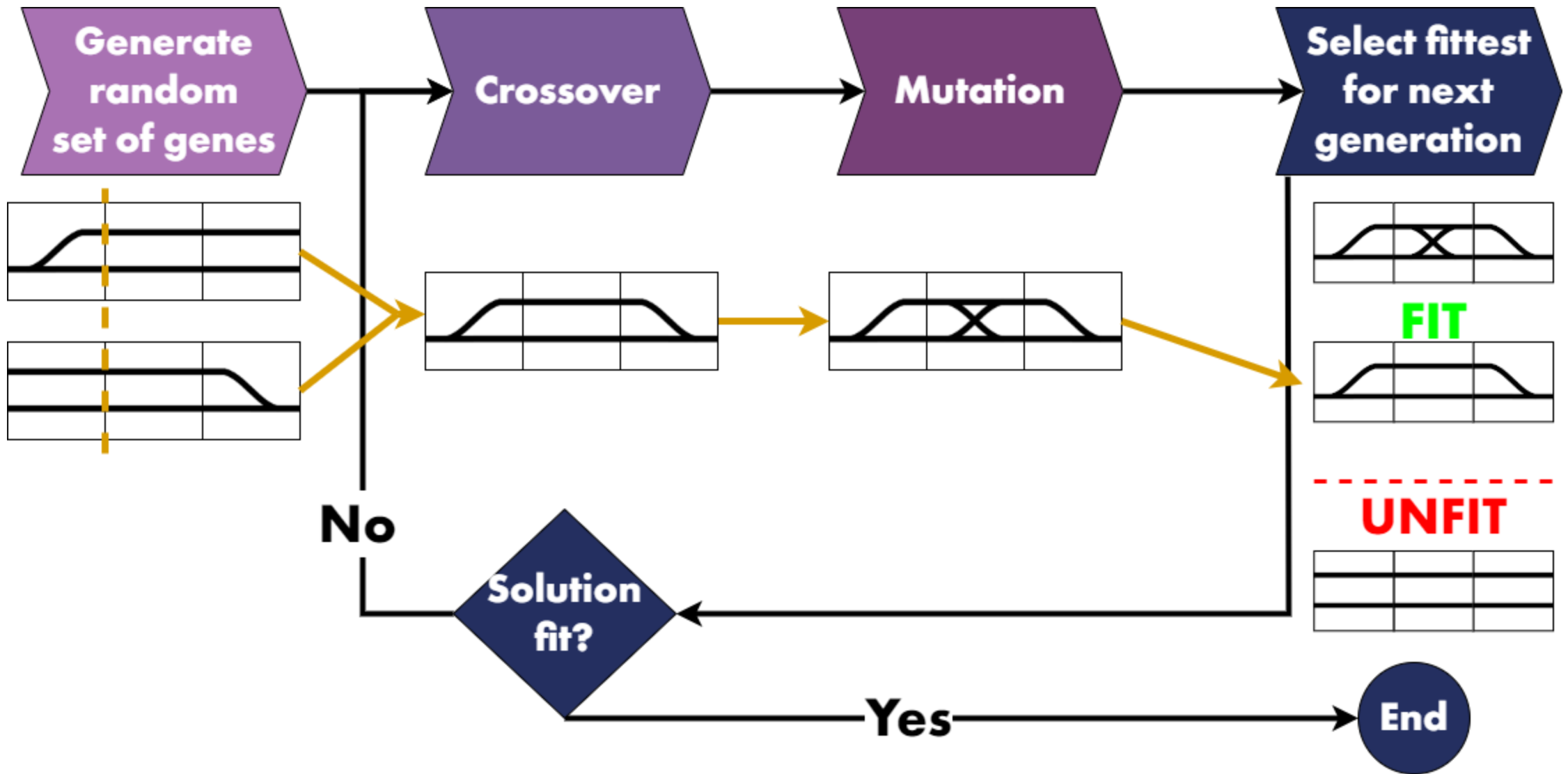












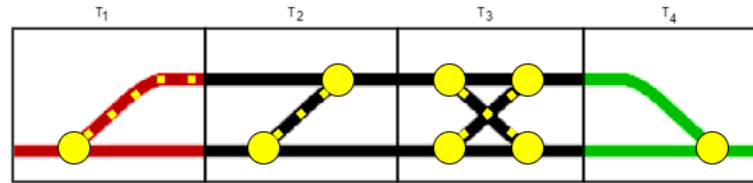
Scheme Plan Fitness Value

Statistics	
Avg. Fitness	0
Max Fitness	0

Helps us to evaluate whether a solution (here: a scheme plan, sequence of genes) is satisfying our requirements set. Crucial for the Genetic Algorithm. Greater value = better.

Scheme Plan Fitness Function

$$Complexity(SP) = \sum_{i=1}^{length(SP)} NewNodes(T_i) + NewTracks(T_i)$$



Example Scheme Plan

1)

$$Complexity(Example) = ((1 + 1) + (2 + 1) + (4 + 2) + (1 + 0)) = 12$$

2)

$$\begin{aligned} IdealComplexity(Example) &= TileLength * 2.5 * complexityRate \\ &= 4 * 2.5 * 1.0 = 10 \end{aligned}$$

3)

$$\begin{aligned} ComplexityPenalty(Example) &= \frac{1}{1 + 0.05 * |IdealComplexity(SP) - Complexity(SP)|} \\ &= \frac{1}{1 + 0.05 * |10 - 12|} = \frac{1}{1 + 0.1} \approx 0.91 \end{aligned}$$

Scheme Plan Fitness Function – Continued

Scheme Plan Settings	
Complexity Rate	1.2
Correct Balises	1
Incorrect Balises	1
Passing Loops	1

4) Example Settings

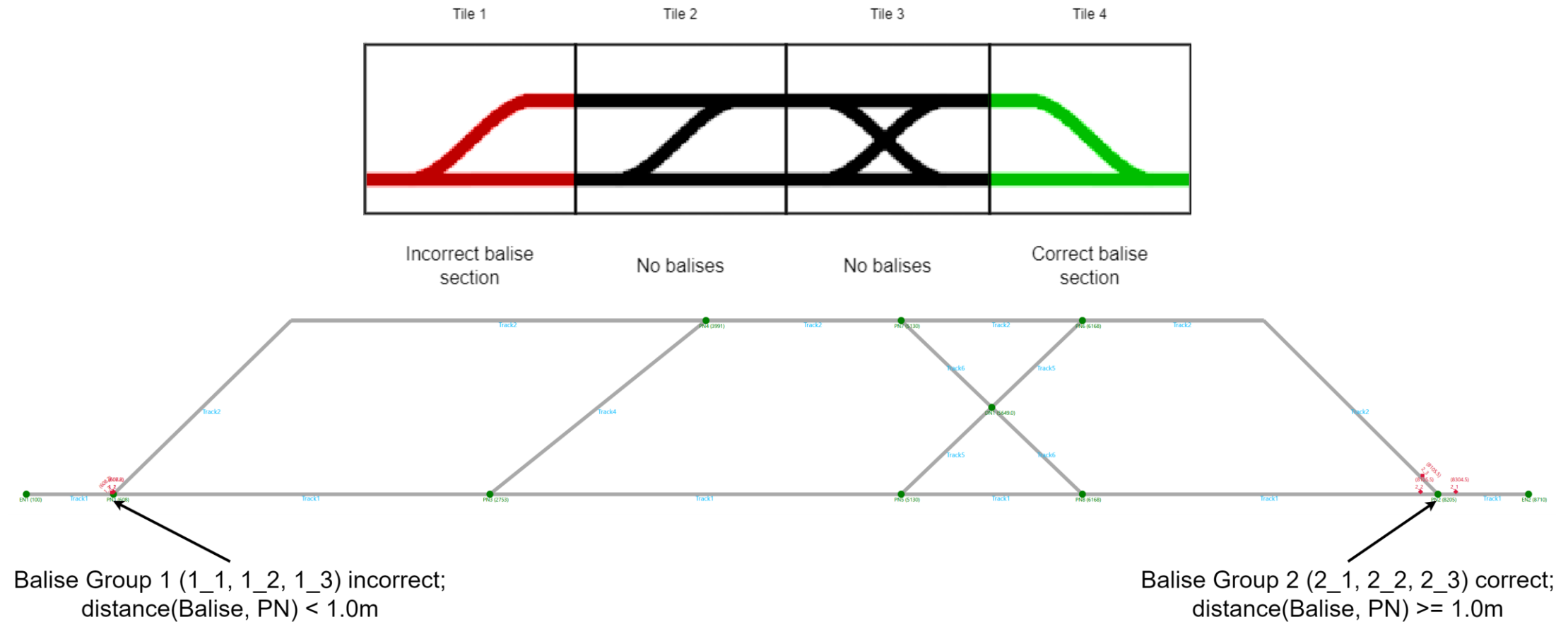
$$\begin{aligned} \text{Deviation}(\text{Example}) &= |\text{idealCorrectBalises} - \text{correctBalises}| + \dots \\ &\quad + |\text{idealPassingLoops} - \text{passingLoops}| = \\ &\quad |1 - 1| + |1 - 1| + |1 - 1| = 0 \end{aligned}$$

$$\begin{aligned} 5) \quad \text{Fitness}(\text{Example}) &= \frac{1}{1 + \text{Deviation}} * \text{ComplexityPenalty} = \\ &= \frac{1}{1 + 0} * 0.91 = 0.91 \end{aligned}$$

E.g., each tile is assigned a random length (1.0-1.2km), when exported into the System Under Test.

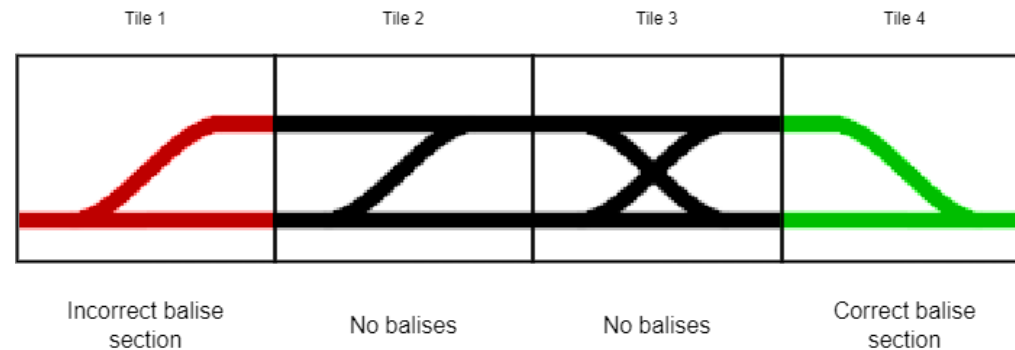


Illustrating Error Injection



Expected Observation: A Log File

A log file is created by Test Case Generator to later establish whether an injected error was observed by the System Under Test



```
** .INCORRECT.BALISE.LOG.FILE.**
```

```
balise_group_id>balise_id→distance→track_id→points_node_id→points_node_distance→distance_difference
```

```
1→1→607.8→Track1→PN1>608>-0.2
```

```
1→2→608.2→Track1→PN1>608>+0.2
```

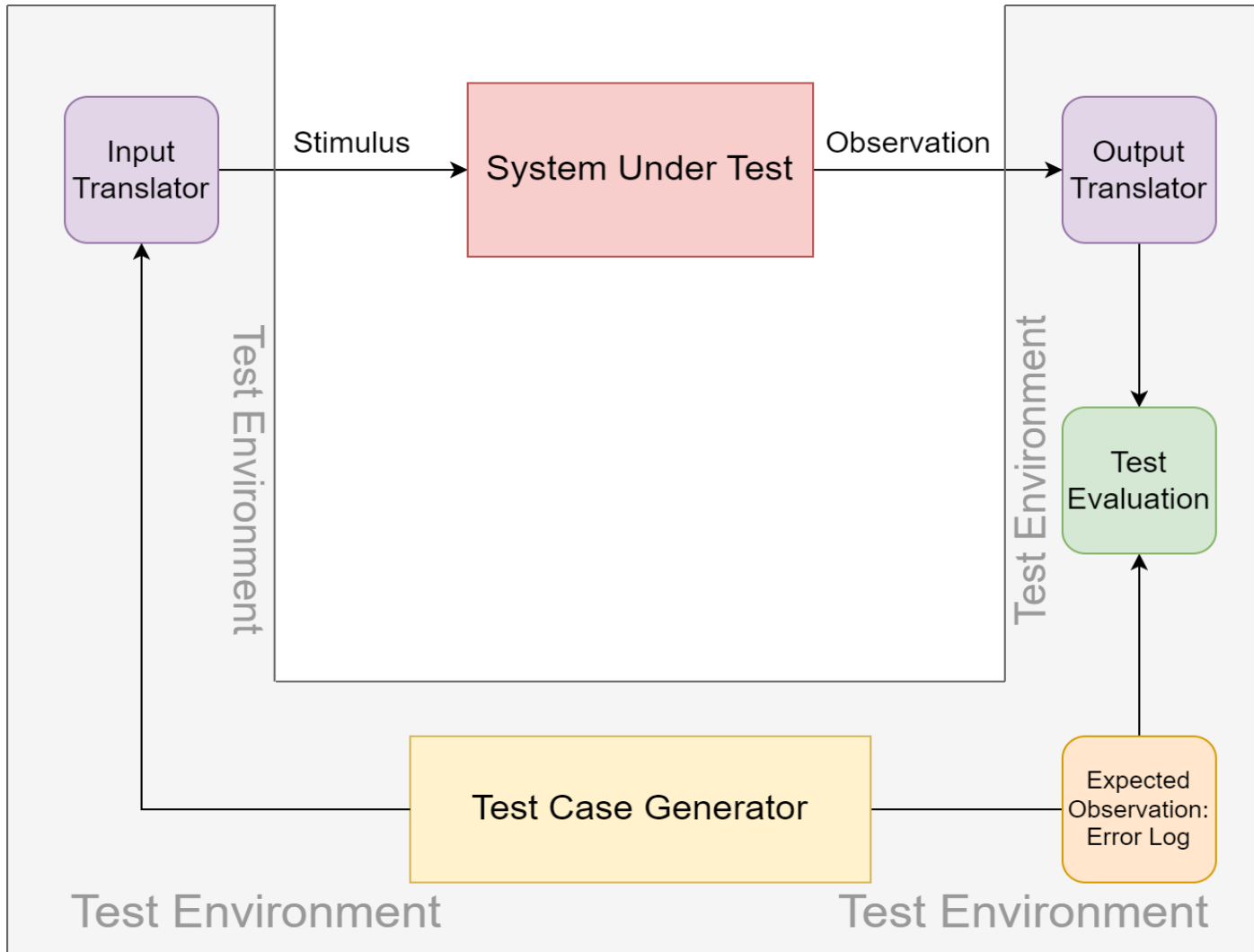
```
1→3→608.2→Track2→PN1>608>-0.2
```

Test Evaluation

“Comparing the output of the System Under Test with the log file”

The test is passed if and only if the SUT’s reported errors are an exact match with the generated log file, that is:

- ✓ all injected errors are found and,
- ✓ no additional errors (i.e., outside of test suite’s scope) are discovered.



Result: Automated Testing Environment

Developing Test Cases – Decision Table Based Testing

- Widely used since the early 1960s.
- A useful technique when dealing with “combinations of actions taken under varying sets of conditions”.
- Ensures that every combination of condition values has been considered.
- Therefore, it provides a mechanism for complete testing [7].

Decision Table Based Testing – Error Injection Problem

C1: Balise exists? (TRUE/FALSE)	FALSE	FALSE	TRUE	TRUE	TRUE	TRUE	TRUE	TRUE	TRUE
C2: Track direction (UP/DOWN)	-	-	-	UP	UP	UP	DOWN	DOWN	DOWN
C3: Distance gap between balise & points node (<, >, =)	-	-	-	> 1.0	Equal to 1.0	< 1.0	> 1.0	Equal to 1.0	< 1.0
C4: Points node exists? (TRUE/FALSE)	FALSE	TRUE	FALSE	TRUE	TRUE	TRUE	TRUE	TRUE	TRUE
Rule count:	6	6	6	1	1	1	1	1	1
A1: Pass	X	X	X	X	X		X	X	
A2: Fail						X			X

Live Demonstration

Summary

- 1-dimensional artificial scheme plans generation with Genetic Algorithms – synthetic test data.
- Translation to rail design tools for testing & log file to evaluate the test outcome.
- Testing technique – Decision Table Based Testing.

Further work:

- Implementing other design rules spanning across several tiles.
- 2-dimensional scheme plan generation.



Thank You

ANY QUESTIONS?

References

- [1] Railway Signalling A Track Layout. Accessed: Apr. 4, 2025. [Online Image]. Available: <https://www.railwaysignallingconcepts.in/railway-signalling-a-track-layout/>
- [2] Simhout, Berlin-Schöneberg. Eurobalises. (Aug. 18, 2018). Accessed: Apr. 4, 2025. [Online Image]. Available: [https://commons.wikimedia.org/wiki/File:Eurobalises_\(Fixed_and_Transparent_Data\)_at_Berlin-Sch%C3%B6neberg_S-Bahnhof.jpg](https://commons.wikimedia.org/wiki/File:Eurobalises_(Fixed_and_Transparent_Data)_at_Berlin-Sch%C3%B6neberg_S-Bahnhof.jpg)
- [3] M. Banerjee, V. Cai, S. Lakhsmanappa, A. Lawrence, M. Roggenbach, M. Seisenberger and T. Werner, “A Tool-Chain for the Verification of Geographic Scheme Data,” *RSSRail 2023, LNCS*, vol. 14198, pp. 211-224, 2023.
- [4] R. Abo and L. Voisin, “Formal implementation of data validation for railway safety-related systems with OVADO,” *SEFM'13, LNCS*, vol. 8368, pp. 221-236, 2014.
- [5] T. Lecomte, L. Burdy and M. Leuschel, “Formally Checking Large Data Sets in the Railways”, in *Workshop on the experience of and advances in developing dependable systems in Event-B*, 2012.
- [6] B. Luteberget, “Automated Reasoning for Planning Railway Infrastructure”, PhD Thesis, University of Oslo, Faculty of Mathematics and Natural Sciences, 2019.
- [7] P. C. Jorgensen, *Software Testing: A Craftsman's Approach*, 5th ed. Boca Raton: Crc Press, 2021, pp. 115-116.