

A Recipe for the Semantics of Reversible Programming

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Reversible Programming

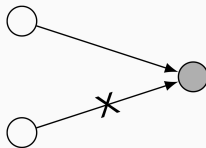
Originally

- Landauer and Bennett, 1961: Reversible Computation and Energy Dissipation.
- Reversible programs: for a program t , there is t^{-1} such that $t; t^{-1} = \text{skip}$.
- Applications to quantum computing.

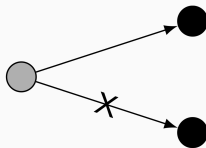
What we do

- Reversibility, but **not totality**.
- Syntax for reversible functions.
- With enough expressivity.
- Through the categorical semantics.

Backward determinism



Forward determinism



[Kaarsgaard&Rennela21]

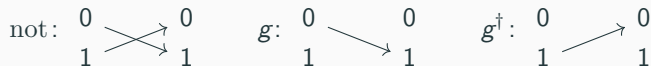
A general framework: dagger categories

Origine: functional analysis where $\langle fx \mid y \rangle = \langle x \mid f^\dagger y \rangle$.

Category \mathbf{C} equipped with a functor $(-)^{\dagger}: \mathbf{C}^{\text{op}} \rightarrow \mathbf{C}$, such that:

- On objects, $A^{\dagger} = A$.
- On morphisms:
 - $(g \circ f)^{\dagger} = f^{\dagger} \circ g^{\dagger}$,
 - $f^{\dagger\dagger} = f$.

Example with partial injective functions between sets, here $\{0, 1\}$.



A very important class of morphisms: *partial \dagger -isomorphism*. $ff^{\dagger}f = f$.

Examples of relevant dagger categories

Sets and bijections.

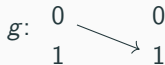


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Sets and bijections.



Sets and partial injections.



g is undefined on 1.

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Hilbert spaces and unitary maps.

$$\begin{array}{lcl} |0\rangle & \longrightarrow & |+\rangle \\ |1\rangle & \longrightarrow & |-\rangle \end{array} \quad \text{where}$$

$$|0\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad |1\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad |+\rangle = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \quad |-\rangle = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

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Hilbert spaces and contractions.

$$h: \begin{array}{ccc} |0\rangle & \longrightarrow & |+\rangle \\ |1\rangle & \longrightarrow & |-\rangle \end{array} \quad h|1\rangle = 0.$$

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Hopefully, there is **another** way.

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We form a function $t \mapsto t' : A \leftrightarrow B$, Whose semantics is

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$$\llbracket B \rrbracket \xrightarrow{\llbracket \Delta \vdash t' : B \rrbracket^\dagger} \llbracket \Delta \rrbracket \xrightarrow{\llbracket \Delta \vdash t : A \rrbracket} \llbracket A \rrbracket$$

Together with pattern-matching

With a sum type \oplus :

$$\frac{\Delta \vdash t: A}{\Delta \vdash \text{inj}_l t: A \oplus B}$$

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Our functions are then:

$$\left\{ \begin{array}{ccc} t_1 & \mapsto & t'_1 \\ t_2 & \mapsto & t'_2 \\ & \vdots & \\ t_m & \mapsto & t'_m \end{array} \right\} : A \leftrightarrow B$$

whenever $\Delta_i \vdash t_i: A$ and $t_j \perp t_k$, $\Delta_i \vdash t'_i: B$ and $t'_j \perp t'_k$.

Example

$$\begin{array}{l} \bullet \ x: A \vdash t: C \\ \bullet \ y: A \vdash t': C \\ \bullet \ t \perp t' \end{array} \quad \left\{ \begin{array}{l} \text{inj}_l x \mapsto t \\ \text{inj}_r y \mapsto t' \end{array} \right\} : A \oplus B \leftrightarrow C$$

Denotational semantics:

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 - ◆ **Compatible** morphisms on their domain and codomain admit a join.
 - ◆ Sometimes, provides a nice structure on morphisms.

Examples:

- Sets and partial injective functions **PInj**.
- Hilbert spaces and contractions **Contr** (sometimes written **Hilb**_{≤1}).

The case of inverse categories (such as \mathbf{PInj})

To Infinity and Beyond

Some reading: [Axelsen&Kaarsgaard16] + [Fiore04] + some calculations.

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→ A suitable inverse category **C** is parameterised **DCPO**-algebraically ω -compact.

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$$\text{map}(\omega) = \text{fix } f. \left\{ \begin{array}{l} [] \mapsto [] \\ h :: t \mapsto (\omega \ h) :: (f \ t) \end{array} \right\} : [A] \leftrightarrow [B]$$

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$$\text{fix}(F) = \sup_n \{F^n(\perp)\}$$

Summary of the language (mandatory slide)

(Ground types) $A, B ::= \mathbf{I} \mid A \oplus B \mid A \otimes B \mid$

(Function types) $T_1, T_2 ::= A \leftrightarrow B \mid$

(Unit term) $t, t_1, t_2 ::= *$

(Pairing) $\mid t_1 \otimes t_2$

(Injections) $\mid \text{inj}_l t \mid \text{inj}_r t$

(Function application) $\mid \omega t$

(Abstraction) $\omega ::= \{t_1 \mapsto t'_1 \mid \cdots \mid t_m \mapsto t'_m\}$

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(Fixed points) $\mid \textcolor{red}{f} \mid \textcolor{red}{fix } f.\omega$

(Higher abstractions) $\mid \textcolor{green}{\lambda} f.\omega \mid \omega_2 \omega_1$

λ -calculus with **fixed points** thanks to **DCPO**-enrichment.

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Rough summary

- Reversible Turing Machines [Axelsen&Glück11].
 - ◆ Simulate your favourite Turing machines.
- Encode RTMs in our language:
 - ◆ Alphabet & states mapped to $I \oplus \dots \oplus I$.
 - ◆ Tape as lists.
 - ◆ Functions simulating one-step transition of δ .
 - ◆ Iterate until final state.

The (pure) quantum case

The quantum troubles



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Contr (Hilbert spaces and contractive linear maps) is not enriched in an **interesting** way.

Composition does not preserve any reasonable poset structure.

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A kind of solution with techniques adapted from **guarded recursion**.

Computation in the topos of trees

Objects in the topos of trees are cochains in **Set**:

$$X(0) \xleftarrow{r_0} X(1) \xleftarrow{r_1} X(2) \xleftarrow{\quad} \dots$$

There is a functor $L: \mathbf{Set}^{\mathbb{N}^{\text{op}}} \rightarrow \mathbf{Set}^{\mathbb{N}^{\text{op}}}$, such that LX is:

$$1 \xleftarrow{!} X(0) \xleftarrow{r_0} X(1) \xleftarrow{r_1} X(2) \xleftarrow{\quad} \dots$$

and a natural transformation $\nu: \text{id} \Rightarrow L$, such that ν_X is:

$$\begin{array}{ccccccc} X(0) & \xleftarrow{r_0} & X(1) & \xleftarrow{r_1} & X(2) & \xleftarrow{r_2} & X(3) \xleftarrow{\quad} \dots \\ \downarrow ! & & \downarrow r_0 & & \downarrow r_1 & & \downarrow r_2 \\ 1 & \xleftarrow{!} & X(0) & \xleftarrow{r_0} & X(1) & \xleftarrow{r_1} & X(2) \xleftarrow{\quad} \dots \end{array}$$

and a family of morphisms $\text{fix}_X: [LX \rightarrow X] \rightarrow X$.

A guarded category

Start with a dagger category \mathbf{C} .

Consider the category whose objects are cochains in \mathbf{C} :

$$X(0) \longleftarrow X(1) \longleftarrow X(2) \longleftarrow \dots$$

And morphisms are natural transformations in \mathbf{C} :

$$\begin{array}{ccccccc} X(0) & \longleftarrow & X(1) & \longleftarrow & X(2) & \longleftarrow & \dots \\ \downarrow & & \downarrow & & \downarrow & & \\ Y(0) & \longleftarrow & Y(1) & \longleftarrow & Y(2) & \longleftarrow & \dots \end{array}$$

This category is enriched in the topos of trees $\mathbf{Set}^{\mathbb{N}^{\text{op}}}$ (with its fixed point operator).

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It still allows for the `map` function.

$$\text{map}(\omega) = \text{fix } f. \left\{ \begin{array}{l} [] \mapsto [] \\ h :: t \mapsto (\omega \ h) :: (f \ t) \end{array} \right\} : [A] \leftrightarrow [B]$$

Conclusion

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Thank you!