Unboxed Data with Dependent Types

Constantine Theocharis and Ellis Kesterton

University of St Andrews

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Programming with unboxed data

- unboxed data = no forced heap indirections
- The 'standard' in languages like C/C++, Rust, etc.
- Why?
 - \circ Contiguous arrays with constant-time indexing.
 - \circ Unboxed integers and packing small data.
 - Protocol buffers (e.g. network packets)
 - Data-driven design (e.g. entity-component systems)

What's the problem?

• With dependent types, we cannot resolve the *size in bytes* each type takes up, at compile time.

foo : (b : Bool) \rightarrow if b then Int else (Int, Int) foo True = 1 foo False = (1, 1)

• Dependently typed (and most functional) languages will box pretty much everything.

But what if we could?

• Staged Compilation with 2LTT [Kovács 2022]

2.4.2 *Memory Representation Polymorphism.* This refines monomorphization, so that types are not directly identified with memory representations, but instead representations are internalized in 2LTT as a meta-level type, and runtime types are indexed over representations.

- We have Rep : U₁ as the type of memory representations. We have considerable freedom in the specification of Rep. A simple setup may distinguish references from unboxed products, i.e. we have Ref : Rep and Prod : Rep → Rep → Rep, and additionally we may assume any desired primitive machine representation as a value of Rep.
- We have Russell-style $U_{0,j}$: Rep $\rightarrow U_{0,j+1} r$, where *r* is some chosen runtime representation for types; usually we would mark types are erased. We leave the meta-level $U_{1,j}$ hierarchy unchanged.
- We may introduce unboxed Σ -types and primitive machine types in the runtime language. For $r : \text{Rep}, r' : \text{Rep}, A : \bigcup_0 r$ and $B : A \to \bigcup_0 r'$, we may have $(x : A) \times Bx : \bigcup_0 (\text{Prod r r'})$. Thus, we have type dependency, but we do not have dependency in memory representations.

Since Rep is meta-level, there is no way to abstract over it at runtime, and during staging all Rep indices are computed to concrete canonical representations. This is a way to reconcile dependent types with some amount of control over memory layouts. The unboxed flavor of Σ ends up with a statically known flat memory representation, computed from the representations of the fields.

Goals

- A language where stack-allocated unboxed data is the default
- Explicit boxing primitive
- Efficient and safe indexing into data
- Zero-sized types = computational irrelevance
- Minimal other primitives: arrays are iterated sigma types
- 2LTT-compatible for metaprogramming

Non-goals

- Manual memory management/no GC
- Holding references to stack values
- Lifetime analysis, uniqueness or linearity
- Unboxed closures

Setup & notation

- Two-level type theory (Ty, Ty1, Tm, Tm1), SOAS.
- I will define and focus on the object fragment.
- The meta fragment is standard dependent type theory.

Set -- Universe of small types in the metatheory TYPE : TYPE -- Universe (type-in-type) in the meta level

 $(x : A) \rightarrow B -- \Pi$ at any level $(x : A, B) -- \Sigma$ at any level

What would this type system look like?

Layouts describe arrangements of data in memory.

```
Layout : TYPE
0, 1, ptr, idx : Layout
_+_ : Layout → Layout → Layout
```

```
ptr + idx + idx + 1 : Layout
-- A pointer followed by two integers, followed by a byte
```

• Object-level types are indexed by their layout.

Ty : Tm1 Layout \rightarrow Set Tm : Ty 1 \rightarrow Set

• Grothendiek-style universe

Type : Tm1 Layout \rightarrow Ty 0 Tm (Type 1) = Ty 1

• Effectively:

Type 1 : Type 0

The standard type formers are now indexed by an appropriate layout:

• Functions are pointer-sized, and box their captures.

A : Ty a B : Tm A \rightarrow Ty b

 $(x : A) ' \rightarrow ' B x : Ty ptr$

• Pairs store their data contiguously

A : Ty a B : Tm A \rightarrow Ty b (x : A, B x) : Ty (a + b)

• The unit type exists for all layouts, and acts like padding

() : Ty u

Example: ADTs as tagged unions

Bool : Type 1

```
Just : T \rightarrow Maybe T
Just x = (true, x)
```

```
Nothing : Maybe T
Nothing = (false, ())
```

Explicit boxing

• A box introduces a heap indirection, always pointer-sized.

A : Type a

Box A : Type ptr

• We can go back and forth using box and unbox operators.

(box, unbox) : Box A \simeq A

Byte : Type 1
(1, 2, ..., 100) : (Byte, Byte, ..., Byte) : Type 100
box (1, 2, ..., 100) : Box (Byte, Byte, ..., Byte) : Type ptr

Runtime-sized data

- A lot of the time we actually work with data whose size is only known at runtime! Prototypical example: **dynamic arrays**
- Let's extend the layouts:

```
Layout? : TYPE
_*_ : Nat → Layout? → Layout?
...
sta : Layout → Layout?
```

 Here Nat is partially static, and _*_/_+_ have appropriate reduction rules. • Now let's expand the universe of types:

```
Type? : Tm1 Layout? \rightarrow Ty 0
Type 1 = Type? (sta 1)
```

• Types of terms must still always be of a known layout

Ty : Tm1 Layout \rightarrow Set

Generating runtime-sized data

• We introduce a new type former that represents the 'generation' of runtime-sized data

Make : Type? 1 \rightarrow Type ptr (emb, give) : {A : Type a} \rightarrow Make A \simeq A

• A Make A is thought of as *mut A \rightarrow (): construct an A at some given location.

How do we construct runtime-sized data?

• Pairs and units generalise to the runtime-sized setting.

() : Make () (_,_) : (x : Make A) \rightarrow Make (B x) \rightarrow Make (x : A, B x)

• Can generalise boxing to runtime-sized data.

Example: Arrays

• Can be defined as iterated pairs

Array : Type t
$$\rightarrow$$
 (n : Nat) \rightarrow Type (n * t)
Array T 0 = () -- Type (0 * 1) = Type 0
Array T (S n) = (t : T, Array T n)
-- Type (S n * t) = Type (t + n * t)

replicate : $T \rightarrow (n : Nat) \rightarrow Make (Array T n)$ replicate t 0 = () replicate t (S n) = (give t, replicate t n) • To actually store arrays we must somehow box their contents

```
Vect : Type t \rightarrow Nat \rightarrow Type ptr
Vect T n = Box (Array T n)
```

```
List : Type t \rightarrow Type ptr
List T = (n : Nat0, Vect T (dyn n))
```

• Or work with them directly on the stack if their size is known at compile-time.

(0x1, 0x2, 0x3) : Array 3 Word : Type (word + word + word)

Computational irrelevance

• Possible with the existence of zero-sized types.

0_ : Type a → Type 0 irr : A → 0 A already : 0 0 A → 0 A • Irrelevant terms can be eliminated into zero-sized types.

let (irr x) = a in p x : P a

• With elaboration/sugar, similar to QTT with $\{0, \omega\}$.

at : {n : 0 Nat} \rightarrow Fin n \rightarrow Vect T n \rightarrow T

Indexing

- Iterated projections of data occupy intermediate stack space.
- Instead we can build up and store indices that are 'instantly' able to access their target.

A : Type? a B : $0 A \rightarrow$ Type? b

(x : A) >> B x : Type idx

(x : A) >> B x is an index into some x : A producing a B x.
 It is compiled as an integer offset.

• When A is sized, we get an application operation

[-] : (a : A) \rightarrow ((x : A) \gg B x) \rightarrow Make (B a)

• However, we do not have lambda abstractions. Instead, we have a 'section' composition operation

f: $(x : A) \implies B x$ g: $(x : 0 A) \rightarrow (y : B x) \implies C y$

f.g:(x:A) >> C x[f]

• The dependent pair projections come in this form

fst : (x : A, B x) >> A
snd : (p : (x : A, B x)) >> B p[fst]

• We can thus compute array indices

```
at : Fin n → Array T n >> T
at FZ = fst
at (FS i) = snd . get i
```

tape : Array 100 Symbol

tape[at 54] : Symbol

players : Game >> List Player
game : Game

game[players . at 3] : Player

Overview

-- generating runtime-sized terms
Make : Type? a → Type ptr

```
-- heap allocation
Box : Type? a \rightarrow Type ptr
```

```
-- irrelevant data
```

 0_- : Type? a \rightarrow Type 0

-- indexing into data _>>_ : (A : Type? a) \rightarrow (0 A \rightarrow Type? b) \rightarrow Type idx

Staging and compilation

- Layout gets translated to a fully static representation, can be computed to a byte size at compile time.
- Layout? still contains object-level terms, can be computed to a byte size at runtime.

Memory management

- Reference counting can be implemented because we know where the pointers are.
- Alternatively, one could use a plug-and-play garbage collection such as Bohm GC.

Mutation

- Can be handled using an ST -like monad as usual.
- A better solution might involve sub-structural features such as linearity or uniqueness.

Current progress

- Shallow embedding in Agda \checkmark
- \bullet Untyped model that justifies irrelevance \checkmark
- Implementation of this system 👍 WIP
 - o github.com/kontheocharis/unboxed-idr
- Semantics ? ? ?

Future work

- Finish the implementation, write some examples.
- Unboxed closures are possible through a **closed** modality.
- Investigate dependently-sized data.
- Investigate sub-structural object theories.
- Inductive types can be added, as *views* of unboxed data.

Dependently-sized data

- Our layouts are still not able to capture the idea of dependently-sized data.
- For example, a **UDP packet** header contains a length field, which determines the amount of bytes that follow the header.
- We cannot have

```
UdpPacket : Type? 1
```

because 1 must be determined by UdpPacket 's inhabitants.

The solution

• Add more layouts!

```
Layout?? : TYPE

-- Layout < Layout? < Layout??

var : (A : Type a) \rightarrow (A \rightarrow Layout??) \rightarrow Layout??

Var : (A : Type a)

\rightarrow {b : A \rightarrow Layout??}

\rightarrow {b : A \rightarrow Layout??}

\rightarrow (B : (h : 0 A) \rightarrow Type?? (b a))

\rightarrow Type?? (var A b)

makeVar : (a : Make A) \rightarrow (b : Make (B a)) \rightarrow Make (Var A B)
```

• Appropriate generalisations of existing type formers.

UDP packets

```
UdpHeader : Type 8
UdpHeader = (
    src : NetU16, -- NetU16 : Type 2
    dest : NetU16,
    length: NetU16,
    checksum: NetU16
)
```

UdpPacket : Type?? (var (h : UdpHeader) | 1 * toNat h.length)
UdpPacket = Var (h : UdpHeader) | Array Byte (toNat h.length)